

```
In [1]: import csv
import numpy as np
from sklearn.metrics import accuracy_score
import random
import matplotlib.pyplot as plt
```

Perceptron Learning algorithm

[2 points] Implement the Perceptron Learning algorithm. Run it on the data file "classification.txt" ignoring the 5th column. That is, consider only the first 4 columns in each row. The first 3 columns are the coordinates of a point; and the 4th column is its classification label +1 or -1. Report your results (weights and accuracy after the final iteration).

```
In [2]: data = []
with open('classification.txt') as f:
    file = csv.reader(f)
    for line in file:
        data.append(line)
data = np.array(data).astype('float64')
```

```
In [3]: def perceptron_learning_ALG(x, y_true, alpha):
    w = np.zeros(len(x[0]))
    iteration = 0
    yhat = -1*(x.dot(w) < 0) + 1*(x.dot(w) >= 0)
    while np.any(yhat != y_true):
        for idx in range(len(x)):
            z = x[idx].dot(w)
            if y_true[idx]==1 and z<0:
                w = w + alpha*x[idx]
                break
            if y_true[idx]==-1 and z>=0:
                w = w - alpha*x[idx]
                break
        yhat = -1*(x.dot(w) < 0) + 1*(x.dot(w) >= 0)
        iteration+=1
    acc = accuracy_score(y_true, yhat)
    return iteration, w, acc
```

```
In [4]: data_points = data[:, :3]
yi = data[:, 3]
xi = np.concatenate((np.ones((len(data_points), 1)), data_points), axis=1)
iteration, w, acc = perceptron_learning_ALG(xi, yi, 0.1)
iteration, w, acc
```

```
Out[4]: (23884, array([ 0.          , 11.33717993, -9.11213384, -6.78511535]), 1.0)
```

Pocket algorithm

[1 point] Implement the Pocket algorithm and run it on the data file "classification.txt" ignoring the 4th column. That is, consider only the first 3 columns and the 5th column in each row. The first 3 columns are the coordinates of a point; and the 5th column is its classification label +1 or -1. Plot the number of misclassified points against the number of iterations of the algorithm. Run up to 7000 iterations. Also, report your results (weights and accuracy after the final iteration).

```
In [178]: data = []
with open('classification.txt') as f:
    file = csv.reader(f)
    for line in file:
        data.append(line)
data = np.array(data).astype('float64')
```

```
In [179]: def sign(z):
          yhat = -1*(z < 0) + 1*(z >= 0)
          return yhat
```

```
In [180]: def find_all_diff(w, x, y):
          zi = x.dot(w)
          yhat = sign(zi)
          all_diff_idx = np.where(yhat!=y)[0]
          return all_diff_idx
```

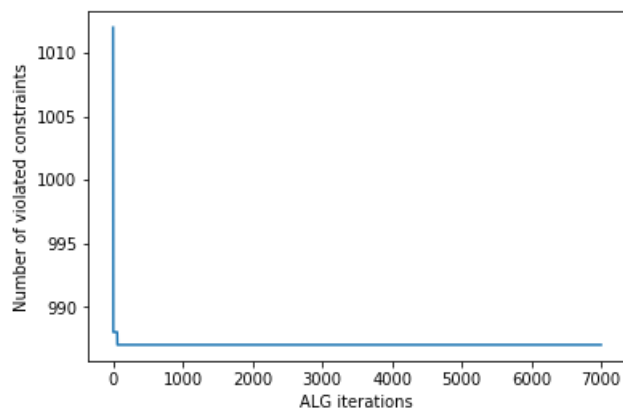
ALG1: Only update w when w' makes fewer mistakes than w

```
In [249]: def pocket_ALG(x, y_true, alpha, iteration_num):
          w = np.zeros(len(x[0]))
          w_diff_idx = find_all_diff(w, x, y_true)
          violated_amount = []
          for i in range(iteration_num):
              violated_amount.append(len(w_diff_idx))
              diff_idx = random.choice(w_diff_idx)
              w2 = w + alpha*y_true[diff_idx]*x[diff_idx]
              w2_diff_idx = find_all_diff(w2, x, y_true)
              if len(w2_diff_idx) < len(w_diff_idx):
                  w = w2.copy()
                  w_diff_idx = w2_diff_idx.copy()
          zi = x.dot(w)
          yhat = sign(zi)
          acc = accuracy_score(y_true, yhat)
          return w, w_diff_idx, acc, violated_amount, yhat
```

```
In [286]: data_points = data[:, :3]
          yi = data[:, 4]
          xi = np.concatenate((np.ones((len(data_points), 1)), data_points), axis=1)
          w, w_diff_idx, acc, violated_amount, yhat = pocket_ALG(xi, yi, 0.1, 7000)
          w, acc
```

```
Out[286]: (array([ 0.          , -0.02579255,  0.00195799,  0.05170381]), 0.5065)
```

```
In [287]: x = [i for i in range(1,7001)]
          y = violated_amount
          plt.plot(x,y)
          plt.xlabel('ALG iterations')
          plt.ylabel('Number of violated constraints')
          plt.show()
```



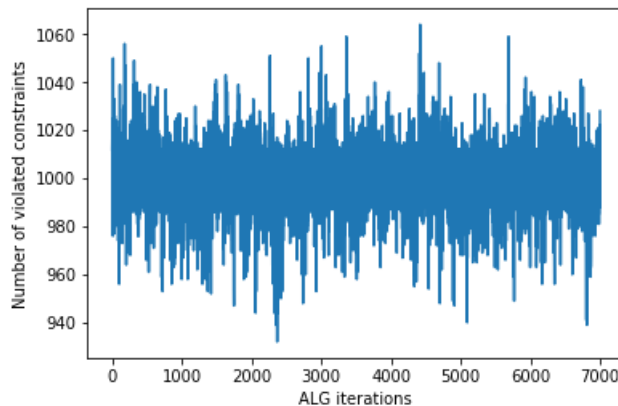
ALG2: Randomly pick one that is wrong and update w every time, but remember the w that have least wrong prediction

```
In [298]: def pocket_ALG(x, y_true, alpha, iteration_num):
    w = np.zeros(len(x[0]))
    w_diff_idx = find_all_diff(w, x, y_true)
    violated_amount = []
    w_diff_least = len(y)
    for i in range(iteration_num):
        violated_amount.append(len(w_diff_idx))
        diff_idx = random.choice(w_diff_idx)
        w = w + alpha*y_true[diff_idx]*x[diff_idx]
        w_diff_idx = find_all_diff(w, x, y_true)
        if len(w_diff_idx) < w_diff_least:
            w_diff_least = len(w_diff_idx)
            w_best = w
    zi = x.dot(w)
    yhat = sign(zi)
    acc = accuracy_score(y_true, yhat)
    return w_best, w_diff_idx, acc, violated_amount, yhat
```

```
In [299]: data_points = data[:, :3]
yi = data[:, 4]
xi = np.concatenate((np.ones((len(data_points), 1)), data_points), axis=1)
w_best, w_diff_idx, acc, violated_amount, yhat = pocket_ALG(xi, yi, 0.1, 7000)
w_best, acc
```

```
Out[299]: (array([ 0.          , -0.15457602,  0.12474349,  0.02682324]), 0.506)
```

```
In [300]: x = [i for i in range(1, 7001)]
y = violated_amount
plt.plot(x, y)
plt.xlabel('ALG iterations')
plt.ylabel('Number of violated constraints')
plt.show()
```



Logistic Regression

[3 points] Implement Logistic Regression and run it on the points in the data file "classification.txt" ignoring the 4th column. That is, consider only the first 3 columns and the 5th column in each row. The first 3 columns are the coordinates of a point; and the 5th column is its classification label +1 or -1. Use the sigmoid function $\Theta(s) = \frac{e^s}{1+e^s}$. Run up to 7000 iterations. Report your results (weights and accuracy after the final iteration).

```
In [162]: data = []
with open('classification.txt') as f:
    file = csv.reader(f)
    for line in file:
        data.append(line)
data = np.array(data).astype('float64')
```

```
In [164]: def sigmoid(s):
          z = np.exp(s)/(1+np.exp(s))
          return z
```

```
In [165]: def gradient_Ein(w, xi, yi):
          sum2=0
          for x,y in zip(xi,yi):
              sum2 += y*x*(1/(1+np.exp(y*x.dot(w))))
          return sum2*(-1/len(xi))
```

```
In [168]: def Logistic_Reg(xi, yi, alpha, iteration_num):
          w = np.zeros(len(xi[0]))
          for i in range(iteration_num):
              w = w - alpha*gradient_Ein(w, xi, yi)
          s = xi.dot(w)
          theta = sigmoid(s)
          yhat = -1*(theta < 0.5) + 1*(theta >= 0.5)
          acc = accuracy_score(yi, yhat)
          return w, acc, yhat, theta
```

```
In [169]: data_points = data[:, :3]
          yi = data[:, 4]
          xi = np.concatenate((np.ones((len(data_points), 1)), data_points), axis=1)
          w, acc, yhat, theta = Logistic_Reg(xi, yi, 0.1, 7000)
          w, acc
```

```
Out[169]: (array([-0.03149498, -0.17769975,  0.11444872,  0.07669738]), 0.5295)
```

Linear Regression

[1 point] Implement Linear Regression and run it on the points in the data file "linear-regression.txt". The first 2 columns in each row represent the independent X and Y variables; and the 3rd column represents the dependent Z variable. Report your results (weights after the final iteration).

```
In [170]: data = []
          with open('linear-regression.txt') as f:
              file = csv.reader(f)
              for line in file:
                  data.append(line)
          data = np.array(data).astype('float64')
```

```
In [173]: def Linear_Reg(xi, yi):
          DDT = xi.transpose().dot(xi)
          DDT_inv = np.linalg.inv(DDT)
          w = DDT_inv.dot(xi.transpose()).dot(yi)
          return w
```

```
In [174]: data_points = data[:, :2]
          yi = data[:, 2]
          xi = np.concatenate((np.ones((len(data_points), 1)), data_points), axis=1)
          w = Linear_Reg(xi, yi)
          w
```

```
Out[174]: array([0.01523535, 1.08546357, 3.99068855])
```