

HAMT - Tool for simulation of Heat And Mass Transfer

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Contents

1	Numerics	3
1.1	Finite Difference Method - FDM	3
1.1.1	Dirichlet Boundary Conditions	3
1.1.2	Neumann Boundary Conditions	3
1.1.3	Radiation Boundary Conditions	3
2	Heat Transfer	5
2.1	Homogeneous Heat Transfer Equation	5
2.2	FDM - Homogeneous Equidistant Cartesian 2D	5
2.2.1	Central Equation	6
2.2.2	Corner Equations	6
2.2.3	Side Equations	6
2.2.4	Verification	6

1 Numerics

1.1 Finite Difference Method - FDM

First order Discretization.

$$f'_f = \frac{f_{i+1} - f_i}{\Delta x} \quad (1.1)$$

$$f'_b = \frac{f_i - f_{i-1}}{\Delta x} \quad (1.2)$$

$$f'_c = \frac{1}{2} (f'_f + f'_b) = \frac{1}{2} \left(\frac{f_{i+1} - f_i}{\Delta x} + \frac{f_i - f_{i-1}}{\Delta x} \right) = \frac{f_{i+1} - f_{i-1}}{2 \Delta x} \quad (1.3)$$

second order

$$f'' = \frac{f'_f - f'_b}{\Delta x} = \frac{f_{i+1} - f_i}{\Delta x^2} - \frac{f_i - f_{i-1}}{\Delta x^2} = \frac{f_{i+1} - 2f_i + f_{i-1}}{\Delta x^2} \quad (1.4)$$

Assuming the differentials $a \frac{\partial f}{\partial x}$ and $a \frac{\partial^2 f}{\partial x^2}$ where a is not constant.

$$a f'_c = \frac{1}{2} \left(\frac{a_{i+1}(f_{i+1} - f_i)}{\Delta x} + \frac{a_{i-1}(f_i - f_{i-1})}{\Delta x} \right) = \frac{a_{i+1}f_{i+1} + (a_{i-1} - a_{i+1})f_i - a_{i-1}f_{i-1}}{2 \Delta x} \quad (1.5)$$

$$a f'' = a_{i+1} \frac{f_{i+1} - f_i}{\Delta x^2} - a_{i-1} \frac{f_i - f_{i-1}}{\Delta x^2} = \frac{a_{i+1}f_{i+1} - (a_{i+1} + a_{i-1})f_i + a_{i-1}f_{i-1}}{\Delta x^2} \quad (1.6)$$

1.1.1 Dirichlet Boundary Conditions

$$f|_i = f_0 \quad (1.7)$$

1.1.2 Neumann Boundary Conditions

$$\left. \frac{\partial f}{\partial x} \right|_{x=i} = c \quad (1.8)$$

$$\frac{f_i - f_{i-i}}{\Delta x} = c \quad (1.9)$$

$$f_i - f_{i-i} = \Delta x c \quad (1.10)$$

1.1.3 Radiation Boundary Conditions

$$\vec{q}_r = \epsilon \sigma T^4 \vec{n} \quad (1.11)$$

Using the Taylor series

$$T f(x; a) = \sum_{n=0}^{\infty} \frac{f^{(n)}(a)}{n!} (x - a)^n \quad (1.12)$$

we get the linearized equation for the heat flux due to radiation

$$T \dot{q}_r(T; T_0) = (4 \epsilon \sigma T_0^3) T - 3 \epsilon \sigma T_0^4. \quad (1.13)$$

Using equation (2.3)

$$-\lambda \frac{\partial T}{\partial x} = T \dot{q}_r(T; T_0) \quad (1.14)$$

leads to the discitized, linear equation

$$(1 + 4 k T_0^3) T_i - T_{i-1} = 3 k T_0^4 \quad (1.15)$$

where

$$k = \frac{\epsilon \sigma \Delta x}{\lambda} \quad (1.16)$$

2 Heat Transfer

The base equation for the heat transfer is the balance equation of the form

$$\frac{\partial \rho}{\partial t} + \nabla \cdot \vec{j} = f(\vec{r}, t) \quad (2.1)$$

where ρ is the density of the quantity in question, \vec{j} is the flux, \vec{r} is the position vector and t is time. For heat transfer problem we define ρ as the volumetric heat density q which is defined as

$$q = \frac{Q}{V} = c \rho T \quad (2.2)$$

\vec{j} is equivalent to the heat flux \vec{q}

$$\vec{q} = -\lambda \nabla T \quad (2.3)$$

and the source $f(\vec{r}, t)$ is the volumetric heat source $\dot{q}_v(\vec{r}, t)$. Inserting 2.2 and 2.3 in 2.1 leads to the heat transfer equation

$$\frac{\partial(c \rho T)}{\partial t} + \nabla \cdot (-\lambda \nabla T) = \dot{q}_v(\vec{r}, t) \quad (2.4)$$

where the quantities are defined as seen in table ??.

Table 2.1: Electron beam - simulation parameters

Quantity	Description	Unit
c	Specific heat capacity	$\text{J kg}^{-1} \text{K}^{-1}$
ρ	Density	kg m^{-3}
T	Temperature	K
λ	Thermal conductivity	$\text{W m}^{-1} \text{K}^{-1}$
\dot{q}_v	Volumetric heat source	W m^{-3}

2.1 Homogeneous Heat Transfer Equation

Assuming...

$$\lambda \Delta T = 0 \quad (2.5)$$

The homogeneous heat equation in cartesian coordinates is expressed as

$$\lambda \frac{\partial^2 T}{\partial x^2} + \lambda \frac{\partial^2 T}{\partial y^2} + \lambda \frac{\partial^2 T}{\partial z^2} = 0 \quad (2.6)$$

while in cylinder coordinates as

$$\lambda \frac{1}{r} \frac{\partial}{\partial r} \left(r \frac{\partial T}{\partial r} \right) + \lambda \frac{1}{r^2} \frac{\partial^2 T}{\partial \phi^2} + \lambda \frac{\partial^2 T}{\partial z^2} = 0. \quad (2.7)$$

2.2 FDM - Homogeneous Equidistant Cartesian 2D

By assuming only the x and y directions equation (2.6) reduces to

$$\lambda \frac{\partial^2 T}{\partial x^2} + \lambda \frac{\partial^2 T}{\partial y^2} = 0. \quad (2.8)$$

2.2.1 Central Equation

Using equation (1.6) equation (2.8) can be discretized as

$$\lambda_{i+1,j}T_{i+1,j} + \lambda_{i,j+1}T_{i,j+1} - \lambda_{tot}T_{i,j} + \lambda_{i-1,j}T_{i-1,j} + \lambda_{i,j-1}T_{i,j-1} = 0 \quad (2.9)$$

where

$$\lambda_{tot} = \lambda_{i+1,j} + \lambda_{i-1,j} + \lambda_{i,j+1} + \lambda_{i,j-1}. \quad (2.10)$$

In case any of the λ parameters is to be taken on a boundary between two segments, a mean between the two is to be taken. The correctness of this assumption can be proven by setting up 4 equations around a center node using Fourier's law. For $\lambda = \text{const}$ the equation reduces to

$$T_{i+1,j} + T_{i,j+1} - 4T_{i,j} + T_{i-1,j} + T_{i,j-1} = 0 \quad (2.11)$$

2.2.2 Corner Equations

2.2.3 Side Equations

2.2.4 Verification