## $\mathbf{H}\mathbf{A}\mathbf{M}\mathbf{T}$

Heat and Mass Transfer

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# 1 Introduction

 ${\rm Text}\ [1].$ 

### **FEM**

The simulation domain is seen in Fig.

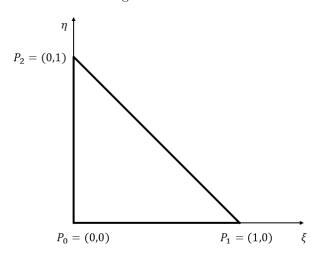


Figure 2.1: Radiation.

Using the definitions

$$x_i \equiv P_{i,x} \tag{2.1}$$

$$y_i \equiv P_{i,y} \tag{2.2}$$

and

$$\Delta x_k = x_0 - x_k \tag{2.3}$$

$$\Delta y_k = y_0 - y_k \tag{2.4}$$

the cartesian coordinates can be expressed in terms of the new coordinates as

$$x(\xi,\eta) = x_0 + \Delta x_1 \xi + \Delta x_2 \eta \tag{2.5}$$

$$y(\xi,\eta) = y_0 + \Delta y_1 \xi + \Delta y_2 \eta \tag{2.6}$$

and the new coordinates as

$$\xi(x,y) = \frac{1}{\det(J(x,y))} (\Delta y_2(x-x_0) - \Delta x_2(y-y_0))$$
 (2.7)

$$\xi(x,y) = \frac{1}{\det(J(x,y))} (\Delta y_2(x-x_0) - \Delta x_2(y-y_0))$$

$$\eta(x,y) = \frac{1}{\det(J(x,y))} (-\Delta y_1(x-x_0) + \Delta x_1(y-y_0))$$
(2.8)

with the Jacobian matrix

$$J(x,y) = \begin{bmatrix} x_{\xi} & x_{\eta} \\ y_{\xi} & y_{\eta} \end{bmatrix} = \begin{bmatrix} \Delta x_1 & \Delta x_2 \\ \Delta y_1 & \Delta y_2 \end{bmatrix}$$
 (2.9)

and its determinant

$$\det(J(x,y)) = \Delta x_1 \Delta y_2 - \Delta x_2 \Delta y_1. \tag{2.10}$$

The Jacobian for the backward transformation can be expressed as

$$J(\xi, \eta) = \begin{bmatrix} \xi_x & \xi_y \\ \eta_x & \eta_y \end{bmatrix} = \frac{1}{\det(J(x, y))} \begin{bmatrix} \Delta y_2 & -\Delta x_2 \\ -\Delta y_1 & \Delta x_1 \end{bmatrix}$$
(2.11)

and its determinant

$$\det \left( \mathbf{J}(\xi, \eta) \right) = \frac{\Delta x_1 \Delta y_2 + \Delta x_2 \Delta y_1}{\Delta x_1 \Delta y_2 - \Delta x_2 \Delta y_1}. \tag{2.12}$$

Required derivatives can be transformed as

$$\frac{\partial u(\xi,\eta)}{\partial x} = \frac{\partial u}{\partial \xi} \frac{\partial \xi}{\partial x} + \frac{\partial u}{\partial \eta} \frac{\partial \eta}{\partial x}$$
 (2.13)

$$\frac{\partial u(\xi,\eta)}{\partial y} = \frac{\partial u}{\partial \xi} \frac{\partial \xi}{\partial y} + \frac{\partial u}{\partial \eta} \frac{\partial \eta}{\partial y}.$$
 (2.14)

With use tetrahedral ansatz functions  $\phi(\xi, \eta)$  with the definition

$$\phi_i \equiv \phi(P_i) \tag{2.15}$$

which can be explicitly given as for the new coordinate system as

$$\phi_0(\xi, \eta) = -\xi - \eta + 1 \tag{2.16}$$

$$\phi_1(\xi, \eta) = \xi \tag{2.17}$$

$$\phi_2(\xi, \eta) = \eta. \tag{2.18}$$

Using this ansatz function the temperature is defined in the support space as

$$T(\xi, \theta) = \sum_{i}^{3} T_{i} \phi_{i} \tag{2.19}$$

and its gradient

$$\nabla T(\xi, \eta) = \begin{pmatrix} \frac{\partial T}{\partial \xi} \frac{\partial \xi}{\partial \xi} + \frac{\partial T}{\partial \eta} \frac{\partial \eta}{\partial x} \\ \frac{\partial T}{\partial \xi} \frac{\partial \xi}{\partial y} + \frac{\partial T}{\partial \eta} \frac{\partial \eta}{\partial y} \end{pmatrix}$$
(2.20)

$$= \frac{1}{\det(\mathbf{J}(x,y))} \begin{pmatrix} (-T_0 + T_1)\Delta y_2 - (-T_0 + T_2)\Delta y_1 \\ -(-T_0 + T_1)\Delta x_2 + (-T_0 + T_2)\Delta x_1 \end{pmatrix}$$
(2.21)

$$= \frac{1}{\det(J(x,y))} \begin{pmatrix} T_0(\Delta y_1 - \Delta y_2) + T_1 \Delta y_2 - T_2 \Delta y_1 \\ T_0(\Delta x_2 - \Delta x_1) - T_1 \Delta x_2 + T_2 \Delta x_1 \end{pmatrix}.$$
(2.22)

### 3 Boundary Conditions

#### 3.1 Heat Flux

Given a boundary segment we can prescribe the a heat flux normal to that boundary as

$$\lambda \left( \vec{n} \cdot \nabla T \right) = \dot{q}_{\perp} \tag{3.1}$$

where  $\lambda$  is the thermal conductivity,  $\vec{n}$  the normal vector of the boundary,  $\nabla T$  the temperature gradient at a given point in the cell and  $\dot{q}_{\perp}$  the differential heat flux perpendicular to the boundary.

We use linear element as our ansatz function for T and triangles as cells which means that  $\vec{n}$  and  $\nabla T$  are constants. If we now assume a per cell constant thermal conductivity  $\lambda$  this means that the differential heat flux  $\dot{q}_{\perp}$  must be constant over a given cell side.

Using the FEM ansatz with linear tetrahedral elements we can write

$$\lambda \int_{0}^{1} \int_{0}^{1-\eta} (\vec{n} \cdot \nabla T) \,\phi_{0} \det(\mathbf{J}(x,y)) \,\mathrm{d}\xi \,\mathrm{d}\eta = \dot{q}_{\perp} \int_{0}^{1} \int_{0}^{1-\eta} \phi_{0} \det(\mathbf{J}(x,y)) \,\mathrm{d}\xi \,\mathrm{d}\eta. \quad (3.2)$$

Assuming the boundary is the button one the normal vector is simply

$$\vec{n} = \begin{pmatrix} 0 \\ -1 \end{pmatrix} \tag{3.3}$$

which leads to

$$\vec{n} \cdot \nabla T = -\frac{\partial T}{\partial y} = \frac{T_0(\Delta x_1 - \Delta x_2) + T_1 \Delta x_2 - T_2 \Delta x_1}{\det(J(x, y))}$$
(3.4)

which leads to

$$(T_0(\Delta x_1 - \Delta x_2) + T_1 \Delta x_2 - T_2 \Delta x_1) \iint \phi_0 \,\mathrm{d}\xi \,\mathrm{d}\eta = \tag{3.5}$$

$$\frac{\dot{q}_{\perp} \det (\mathbf{J}(x,y))}{\lambda} \iint \phi_0 \,\mathrm{d}\xi \,\mathrm{d}\eta \tag{3.6}$$

$$T_0(\Delta x_1 - \Delta x_2) + T_1 \Delta x_2 - T_2 \Delta x_1 = \frac{\dot{q}_{\perp}}{\lambda} \det(J(x, y)).$$
(3.7)

Assuming the boundary is on the left we get to a similar argumentation to

$$T_0(\Delta y_2 - \Delta y_1) - T_1 \Delta y_2 + T_2 \Delta y_1 = \frac{\dot{q}_\perp}{\lambda} \det(J(x, y)).$$
(3.8)

#### 3.2 Radiation

The net radiation heat flux from surface 1 to surface 2 using grey body radiation can be calculated as

$$\dot{Q}_{1\to 2} = A_1 F_{1\to 2} E_1 - A_2 F_{2\to 1} E_2. \tag{3.9}$$

using the formula for emission of grey bodies

$$E_i = \epsilon_i \sigma T_i^4 \tag{3.10}$$

and the reciprocity rule for configuration factors  $A_1F_{1\rightarrow 2}=A_2F_{2\rightarrow 1}$  we can write

$$\dot{Q}_{1\to 2} = \sigma A_1 F_{1\to 2} \left( \epsilon_1 T 1^4 - \epsilon_2 T_2^4 \right) \tag{3.11}$$

and  $\dot{Q}_{1\rightarrow 2}=-\dot{Q}_{2\rightarrow 1}.$  Given two line segments as seen in Fig. 3.1

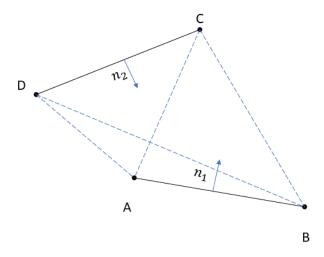


Figure 3.1: Radiation.

the configuration factor from surface  $\overline{AB}$  to surface  $\overline{CD}$  can be calculated as

$$F_{\overline{AB} \to \overline{CD}} = \frac{\overline{AC} + \overline{BD} - \overline{AD} - \overline{BC}}{2\overline{AB}}$$
 (3.12)

where  $\overline{XY}$  is the distance from X to Y. The total heat flux from or to a single surface is the sum of the heat fluxes to other surfaces plus the heat flux to the background

$$\dot{Q}_{tot} = \sigma A_1 \left\{ \epsilon_1 T_1^4 \sum_i F_{1 \to i} - \sum_i \epsilon_i F_{1 \to i} T_i^4 \right\} + \dot{Q}_{backgr}$$
 (3.13)

$$\dot{Q}_{tot} = \sigma A_1 \left\{ \epsilon_1 T_1^4 \sum_i F_{1 \to i} - \sum_i \epsilon_i F_{1 \to i} T_i^4 + F_{1 \to bg} (\epsilon_i T_1^4 - \epsilon_{bg} T_{bg}^4) \right\}$$
(3.14)

Since  $F_{1 \to bg} = 1 - \sum_{i} F_{1 \to i}$  we get

$$\dot{Q}_{tot} = \sigma A_1 \left\{ \epsilon_1 T_1^4 - \sum_i \epsilon_i F_{1 \to i} T_i^4 - F_{1 \to bg} \right) \epsilon_{bg} T_{bg}^4 \right\}$$
 (3.15)

In terms of boundary conditions, using  $\dot{q}_{1\rightarrow 2}=\dot{Q}_{1\rightarrow 2}/A_1$ , we ca write

$$\lambda \left( \vec{n} \cdot \nabla T \right) = \dot{q}_{1 \to 2} \tag{3.16}$$

# **Bibliography**

[1] Hans Dieter Baehr and Karl Stephan. Wärme- und Stoffübertragung. Berlin, Heidelberg: Springer Berlin Heidelberg, 2019. ISBN: 978-3-662-58440-8 978-3-662-58441-5. DOI: 10.1007/978-3-662-58441-5. URL: http://link.springer.com/10.1007/978-3-662-58441-5 (visited on 10/20/2024).