

Prior distributions for variance parameters in hierarchical models(Comment on Article by Browne and Draper)

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Abstract. Various noninformative prior distributions have been suggested for scale parameters in hierarchical models. We construct a new folded-noncentral- t family of conditionally conjugate priors for hierarchical standard deviation parameters, and then consider noninformative and weakly informative priors in this family. We use an example to illustrate serious problems with the inverse-gamma family of “noninformative” prior distributions. We suggest instead to use a uniform prior on the hierarchical standard deviation, using the half- t family when the number of groups is small and in other settings where a weakly informative prior is desired. We also illustrate the use of the half- t family for hierarchical modeling of multiple variance parameters such as arise in the analysis of variance.

Keywords: Bayesian inference, conditional conjugacy, folded-noncentral- t distribution, half- t distribution, hierarchical model, multilevel model, noninformative prior distribution, weakly informative prior distribution

1 Introduction

Fully-Bayesian analyses of hierarchical linear models have been considered for at least forty years (Hill, 1965, Tiao and Tan, 1965, and Stone and Springer, 1965) and have remained a topic of theoretical and applied interest (see, e.g., Portnoy, 1971, Box and Tiao, 1973, Gelman et al., 2003, Carlin and Louis, 1996, and Meng and van Dyk, 2001). Browne and Draper (2005) review much of the extensive literature in the course of comparing Bayesian and non-Bayesian inference for hierarchical models. As part of their article, Browne and Draper consider some different prior distributions for variance parameters; here, we explore the principles of hierarchical prior distributions in the context of a specific class of models.

Hierarchical (multilevel) models are central to modern Bayesian statistics for both conceptual and practical reasons. On the theoretical side, hierarchical models allow a more “objective” approach to inference by estimating the parameters of prior distributions from data rather than requiring them to be specified using subjective information (see James and Stein, 1960, Efron and Morris, 1975, and Morris, 1983). At a practical level, hierarchical models are flexible tools for combining information and partial pooling of inferences (see, for example, Kreft and De Leeuw, 1998, Snijders and Bosker, 1999, Carlin and Louis, 2001, Raudenbush and Bryk, 2002, Gelman et al., 2003).

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A hierarchical model requires hyperparameters, however, and these must be given their own prior distribution. In this paper, we discuss the prior distribution for hierarchical variance parameters. We consider some proposed noninformative prior distributions, including uniform and inverse-gamma families, in the context of an expanded conditionally-conjugate family. We propose a half- t model and demonstrate its use as a weakly-informative prior distribution and as a component in a hierarchical model of variance parameters.

1.1 The basic hierarchical model

We shall work with a simple two-level normal model of data y_{ij} with group-level effects α_j :

$$\begin{aligned} y_{ij} &\sim N(\mu + \alpha_j, \sigma_y^2), \quad i = 1, \dots, n_j, \quad j = 1, \dots, J \\ \alpha_j &\sim N(0, \sigma_\alpha^2), \quad j = 1, \dots, J. \end{aligned} \quad (1)$$

We briefly discuss other hierarchical models in Section 7.2.

Model (1) has three hyperparameters— μ , σ_y , and σ_α —but in this paper we concern ourselves only with the last of these. Typically, enough data will be available to estimate μ and σ_y that one can use any reasonable noninformative prior distribution—for example, $p(\mu, \sigma_y) \propto 1$ or $p(\mu, \log \sigma_y) \propto 1$.

Various noninformative prior distributions for σ_α have been suggested in Bayesian literature and software, including an improper uniform density on σ_α (Gelman et al., 2003), proper distributions such as $p(\sigma_\alpha^2) \sim \text{inverse-gamma}(0.001, 0.001)$ (Spiegelhalter et al., 1994, 2003), and distributions that depend on the data-level variance (Box and Tiao, 1973). In this paper, we explore and make recommendations for prior distributions for σ_α , beginning in Section 3 with conjugate families of proper prior distributions and then considering noninformative prior densities in Section 4.

As we illustrate in Section 5, the choice of “noninformative” prior distribution can have a big effect on inferences, especially for problems where the number of groups J is small or the group-level variance σ_α^2 is close to zero. We conclude with recommendations in Section 7.

2 Concepts relating to the choice of prior distribution

2.1 Conditionally-conjugate families

Consider a model with parameters θ , for which ϕ represents one element or a subset of elements of θ . A family of prior distributions $p(\phi)$ is *conditionally conjugate* for ϕ if the conditional posterior distribution, $p(\phi|y)$ is also in that class. In computational terms, conditional conjugacy means that, if it is possible to draw ϕ from this class of prior distributions, then it is also possible to perform a Gibbs sampler draw of ϕ in the posterior distribution. Perhaps more important for understanding the model,

conditional conjugacy allows a prior distribution to be interpreted in terms of equivalent data (see, for example, Box and Tiao, 1973).

Conditional conjugacy is a useful idea because it is preserved when a model is expanded hierarchically, while the usual concept of conjugacy is not. For example, in the basic hierarchical normal model, the normal prior distributions on the α_j 's are conditionally conjugate but not conjugate; the α_j 's have normal posterior distributions, conditional on all other parameters in the model, but their marginal posterior distributions are not normal.

As we shall see, by judicious model expansion we can expand the class of conditionally conjugate prior distributions for the hierarchical variance parameter.

2.2 Improper limit of a prior distribution

Improper prior densities can, but do not necessarily, lead to proper posterior distributions. To avoid confusion it is useful to define improper distributions as particular limits of proper distributions. For the variance parameter σ_α , two commonly-considered improper densities are $\text{uniform}(0, A)$, as $A \rightarrow \infty$, and $\text{inverse-gamma}(\epsilon, \epsilon)$, as $\epsilon \rightarrow 0$.

As we shall see, the $\text{uniform}(0, A)$ model yields a limiting proper posterior density as $A \rightarrow \infty$, as long as the number of groups J is at least 3. Thus, for a finite but sufficiently large A , inferences are not sensitive to the choice of A .

In contrast, the $\text{inverse-gamma}(\epsilon, \epsilon)$ model does *not* have any proper limiting posterior distribution. As a result, posterior inferences are sensitive to ϵ —it cannot simply be comfortably set to a low value such as 0.001.

2.3 Weakly-informative prior distribution

We characterize a prior distribution as *weakly informative* if it is proper but is set up so that the information it does provide is intentionally weaker than whatever actual prior knowledge is available. We will discuss this further in the context of a specific example, but in general any problem has some natural constraints that would allow a weakly-informative model. For example, for regression models on the logarithmic or logit scale, with predictors that are binary or scaled to have standard deviation 1, we can be sure for most applications that effect sizes will be less than 10, or certainly less than 100.

Weakly-informative distributions are useful for their own sake and also as necessary limiting steps in noninformative distributions, as discussed in Section 2.2 above.

2.4 Calibration

Posterior inferences can be evaluated using the concept of *calibration* of the posterior mean, the Bayesian analogue to the classical notion of “bias.” For any parameter θ , we

label the posterior mean as $\hat{\theta} = E(\theta|y)$ and define the **miscalibration of the posterior mean as $E(\theta|\hat{\theta}, y) - \hat{\theta}$, for any value of $\hat{\theta}$** . If the prior distribution is true—that is, if the data are constructed by first drawing θ from $p(\theta)$, then drawing y from $p(y|\theta)$ —then the posterior mean is automatically calibrated; that is its miscalibration is 0 for all values of $\hat{\theta}$.

For improper prior distributions, however, things are not so simple, since it is impossible for θ to be drawn from an unnormalized density. To evaluate calibration in this context, it is necessary to posit a “true prior distribution” from which θ is drawn along with the “inferential prior distribution” that is used in the Bayesian inference.

For the hierarchical model discussed in this paper, we can consider the improper uniform density on σ_α as a limit of uniform prior densities on the range $(0, A)$, with $A \rightarrow \infty$. For any finite value of A , we can then see that the improper uniform density leads to inferences with a positive miscalibration—that is, overestimates (on average) of σ_α .

We demonstrate this miscalibration in two steps. First, suppose that both the true and inferential prior distributions for σ_α are uniform on $(0, A)$. Then the miscalibration is trivially zero. Now keep the true prior distribution at $U(0, A)$ and let the inferential prior distribution go to $U(0, \infty)$. This will necessarily increase $\hat{\theta}$ for any data y (since we are now averaging over values of θ in the range $[A, \infty)$) without changing the true θ , thus causing the average value of the miscalibration to become positive.

This miscalibration is an unavoidable consequence of the asymmetry in the parameter space, with variance parameters restricted to be positive. Similarly, there are no always-nonnegative classical unbiased estimators of σ_α or σ_α^2 in the hierarchical model. Similar issues are discussed by Bickel and Blackwell (1967) and Meng and Zaslavsky (2002).

3 Conditionally-conjugate prior distributions for hierarchical variance parameters

3.1 Inverse-gamma prior distribution for σ_α^2

The parameter σ_α^2 in model (1) does not have any simple family of conjugate prior distributions because its marginal likelihood depends in a complex way on the data from all J groups (Hill, 1965, Tiao and Tan, 1965). However, the inverse-gamma family is conditionally conjugate, in the sense defined in Section 2.1: if σ_α^2 has an inverse-gamma prior distribution, then the conditional posterior distribution $p(\sigma_\alpha^2 | \alpha, \mu, \sigma_y, y)$ is also inverse-gamma.

The inverse-gamma(α, β) model for σ_α^2 can also be expressed as an inverse- χ^2 distribution with scale $s_\alpha^2 = \beta/\alpha$ and degrees of freedom $\nu_\alpha = 2\alpha$ (Gelman et al., 2003). The inverse- χ^2 parameterization can be helpful in understanding the information underlying various choices of proper prior distributions, as we discuss in Section 4.

3.2 Folded-noncentral- t prior distribution for σ_α

We can expand the family of conditionally-conjugate prior distributions by applying a redundant multiplicative reparameterization to model (1):

$$\begin{aligned} y_{ij} &\sim N(\mu + \xi\eta_j, \sigma_y^2) \\ \eta_j &\sim N(0, \sigma_\eta^2). \end{aligned} \quad (2)$$

The parameters α_j in (1) correspond to the products $\xi\eta_j$ in (2), and the hierarchical standard deviation σ_α in (1) corresponds to $|\xi|\sigma_\eta$ in (2). This “parameter expanded” model was originally constructed to speed up EM and Gibbs sampler computations. The overparameterization reduces dependence among the parameters in a hierarchical model and improves MCMC convergence (Liu, Rubin, and Wu, 1998, Liu and Wu, 1999, van Dyk and Meng, 2001, Gelman et al., 2005). It has also been suggested that the additional parameter can increase the flexibility of applied modeling, especially in hierarchical regression models with several batches of varying coefficients (Gelman, 2004). Here we merely note that this expanded model form allows conditionally conjugate prior distributions for both ξ and σ_η , and these parameters are independent in the conditional posterior distribution. There is thus an implicit conditionally conjugate prior distribution for $\sigma_\alpha = |\xi|\sigma_\eta$.

For simplicity we restrict ourselves to independent prior distributions on ξ and σ_η . In model (2), the conditionally-conjugate prior family for ξ is normal—given the data and all the other parameters in the model, the likelihood for ξ has the form of a normal distribution, derived from $\sum_{j=1}^J n_j$ factors of the form $(y_{ij} - \mu)/\eta_j \sim N(\xi, \sigma_y^2/\eta_j^2)$. The conditionally-conjugate prior family for σ_η^2 is inverse-gamma, as discussed in Section 3.1.

The implicit conditionally-conjugate family for σ_α is then the set of distributions corresponding to the absolute value of a normal random variable, divided by the square root of a gamma random variable. That is, σ_α has the distribution of the absolute value of a noncentral- t variate (see, for example, Johnson and Kotz, 1972). We shall call this the *folded noncentral t distribution*, with the “folding” corresponding to the absolute value operator. The noncentral t in this context has three parameters, which can be identified with the mean of the normal distribution for ξ , and the scale and degrees of freedom for σ_η^2 . (Without loss of generality, the scale of the normal distribution for ξ can be set to 1 since it cannot be separated from the scale for σ_η .)

The folded noncentral t distribution is not commonly used in statistics, and we find it convenient to understand it through various special and limiting cases. In the limit that the denominator is specified exactly, we have a folded normal distribution; conversely, specifying the numerator exactly yields the square-root-inverse- χ^2 distribution for σ_α , as in Section 3.1.

An appealing two-parameter family of prior distributions is determined by restricting the prior mean of the numerator to zero, so that the folded noncentral t distribution for σ_α becomes simply a half- t —that is, the absolute value of a Student- t distribution centered at zero. We can parameterize this in terms of scale A and degrees of freedom

ν :

$$p(\sigma_\alpha) \propto \left(1 + \frac{1}{\nu} \left(\frac{\sigma_\alpha}{A}\right)^2\right)^{-(\nu+1)/2}.$$

This family includes, as special cases, the improper uniform density (if $\nu = -1$) and the proper half-Cauchy, $p(\sigma_\alpha) \propto (\sigma_\alpha^2 + s_\alpha^2)^{-1}$ (if $\nu = 1$).

The half- t family is not itself conditionally-conjugate—starting with a half- t prior distribution, you will still end up with a more general folded noncentral t conditional posterior—but it is a natural subclass of prior densities in which the distribution of the multiplicative parameter ξ is symmetric about zero.

4 Noninformative and weakly-informative prior distributions for hierarchical variance parameters

4.1 General considerations

Noninformative prior distributions are intended to allow Bayesian inference for parameters about which not much is known beyond the data included in the analysis at hand. Various justifications and interpretations of noninformative priors have been proposed over the years, including invariance (Jeffreys, 1961), maximum entropy (Jaynes, 1983), and agreement with classical estimators (Box and Tiao, 1973, Meng and Zaslavsky, 2002). In this paper, we follow the approach of Bernardo (1979) and consider so-called noninformative priors as “reference models” to be used as a standard of comparison or starting point in place of the proper, informative prior distributions that would be appropriate for a full Bayesian analysis (see also Kass and Wasserman, 1996).

We view any noninformative or weakly-informative prior distribution as inherently provisional—after the model has been fit, one should look at the posterior distribution and see if it makes sense. If the posterior distribution does not make sense, this implies that additional prior knowledge is available that has not been included in the model, and that contradicts the assumptions of the prior distribution that has been used. It is then appropriate to go back and alter the prior distribution to be more consistent with this external knowledge.

4.2 Uniform prior distributions

We first consider uniform prior distributions while recognizing that we must be explicit about the scale on which the distribution is defined. Various choices have been proposed for modeling variance parameters. A uniform prior distribution on $\log \sigma_\alpha$ would seem natural—working with the logarithm of a parameter that must be positive—but it results in an improper posterior distribution. An alternative would be to define the prior distribution on a compact set (e.g., in the range $[-A, A]$ for some large value of A), but then the posterior distribution would depend strongly on the lower bound $-A$

of the prior support.

The problem arises because the marginal likelihood, $p(y|\sigma_\alpha)$ —after integrating over α, μ, σ_y in (1)—approaches a finite nonzero value as $\sigma_\alpha \rightarrow 0$. Thus, if the prior density for $\log \sigma_\alpha$ is uniform, the posterior distribution will have infinite mass integrating to the limit $\log \sigma_\alpha \rightarrow -\infty$. To put it another way, in a hierarchical model the data can never rule out a group-level variance of zero, and so the prior distribution cannot put an infinite mass in this area.

Another option is a uniform prior distribution on σ_α itself, which has a finite integral near $\sigma_\alpha = 0$ and thus avoids the above problem. We have generally used this noninformative density in our applied work (see Gelman et al., 2003), but it has a slightly disagreeable miscalibration toward positive values (see Section 2.4), with its infinite prior mass in the range $\sigma_\alpha \rightarrow \infty$. With $J = 1$ or 2 groups, this actually results in an improper posterior density, essentially concluding $\sigma_\alpha = \infty$ and doing no shrinkage (see Gelman et al., 2003, Exercise 5.8). In a sense this is reasonable behavior, since it would seem difficult from the data alone to decide how much, if any, shrinkage should be done with data from only one or two groups—and in fact this would seem consistent with the work of Stein (1955) and James and Stein (1960) that unshrunk estimators are admissible if $J < 3$. However, from a Bayesian perspective it is awkward for the decision to be made ahead of time, as it were, with the data having no say in the matter. In addition, for small J , such as 4 or 5, we worry that the heavy right tail of the posterior distribution would lead to overestimates of σ_α and thus result in shrinkage that is less than optimal for estimating the individual α_j 's.

We can interpret the various improper uniform prior densities as limits of weakly-informative conditionally-conjugate priors. The uniform prior distribution on $\log \sigma_\alpha$ is equivalent to $p(\sigma_\alpha) \propto \sigma_\alpha^{-1}$ or $p(\sigma_\alpha^2) \propto \sigma_\alpha^{-2}$, which has the form of an inverse- χ^2 density with 0 degrees of freedom and can be taken as a limit of proper conditionally-conjugate inverse-gamma priors.

The uniform density on σ_α is equivalent to $p(\sigma_\alpha^2) \propto \sigma_\alpha^{-1}$, an inverse- χ^2 density with -1 degrees of freedom. This density cannot easily be seen as a limit of proper inverse- χ^2 densities (since these must have positive degrees of freedom), but it can be interpreted as a limit of the half- t family on σ_α , where the scale approaches ∞ (and any value of ν). Or, in the expanded notation of (2), one could assign any prior distribution to σ_η and a normal to ξ , and let the prior variance for ξ approach ∞ .

Another noninformative prior distribution sometimes proposed in the Bayesian literature is uniform on σ_α^2 . We do not recommend this, as it seems to have the miscalibration toward higher values as described above, but more so, and also requires $J \geq 4$ groups for a proper posterior distribution.

4.3 Inverse-gamma(ϵ, ϵ) prior distributions

The inverse-gamma(ϵ, ϵ) prior distribution is an attempt at noninformativeness within the conditionally conjugate family, with ϵ set to a low value such as 1 or 0.01 or 0.001

(the latter value being used in the examples in Bugs; see Spiegelhalter et al., 1994, 2003). A difficulty of this prior distribution is that in the limit of $\epsilon \rightarrow 0$ it yields an improper posterior density, and thus ϵ must be set to a reasonable value. Unfortunately, for datasets in which low values of σ_α are possible, inferences become very sensitive to ϵ in this model, and the prior distribution hardly looks noninformative, as we illustrate in Section 5.

4.4 Half-Cauchy prior distributions

The half-Cauchy is a special case of the conditionally-conjugate folded-noncentral- t family of prior distributions for σ_α ; see Section 3.2, which has a broad peak at zero and a scale parameter A . In the limit $A \rightarrow \infty$ this becomes a uniform prior density on $p(\sigma_\alpha)$. Large but finite values of A represent prior distributions which we call “weakly informative” because, even in the tail, they have a gentle slope (unlike, for example, a half-normal distribution) and can let the data dominate if the likelihood is strong in that region. In Sections 5.2 and 6, we consider half-Cauchy models for variance parameters which are estimated from a small number of groups (so that inferences are sensitive to the choice of weakly-informative prior distribution).

5 Application to the 8-schools example

We demonstrate the properties of some proposed noninformative prior densities with a simple example of data from $J = 8$ educational testing experiments described in Rubin (1981) and Gelman et al. (2003, Chapter 5 and Appendix C). Here, the parameters $\alpha_1, \dots, \alpha_8$ represent the relative effects of Scholastic Aptitude Test coaching programs in eight different schools, and σ_α represents the between-school standard deviations of these effects. The effects are measured as points on the test, which was scored from 200 to 800 with an average of about 500; thus the largest possible range of effects could be about 300 points, with a realistic upper limit on σ_α of 100, say.

5.1 Noninformative prior distributions for the 8-schools problem

Figure 1 shows the posterior distributions for the 8-schools model resulting from three different choices of prior distributions that are intended to be noninformative.

The leftmost histogram shows the posterior inference for σ_α (as represented by 6000 simulation draws from a model fit using Bugs) for the model with uniform prior density. The data show support for a range of values below $\sigma_\alpha = 20$, with a slight tail after that, reflecting the possibility of larger values, which are difficult to rule out given that the number of groups J is only 8—that is, not much more than the $J = 3$ required to ensure a proper posterior density with finite mass in the right tail.

In contrast, the middle histogram in Figure 1 shows the result with an inverse-gamma(1,1) prior distribution for σ_α^2 . This new prior distribution leads to changed

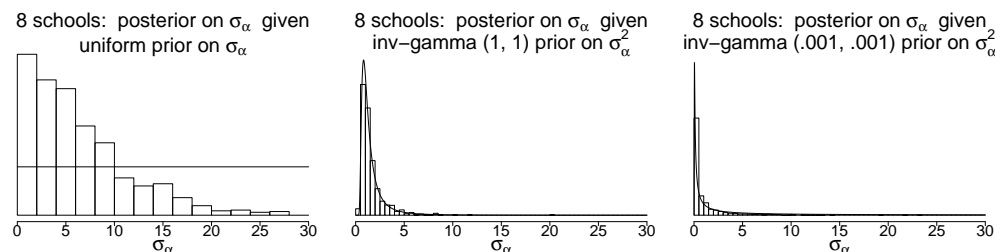


Figure 1: Histograms of posterior simulations of the between-school standard deviation, σ_α , from models with three different prior distributions: (a) uniform prior distribution on σ_α , (b) inverse-gamma(1, 1) prior distribution on σ_α^2 , (c) inverse-gamma(0.001, 0.001) prior distribution on σ_α^2 . Overlain on each is the corresponding prior density function for σ_α . (For models (b) and (c), the density for σ_α is calculated using the gamma density function multiplied by the Jacobian of the $1/\sigma_\alpha^2$ transformation.) In models (b) and (c), posterior inferences are strongly constrained by the prior distribution. Adapted from Gelman et al. (2003, Appendix C).

inferences. In particular, the posterior mean and median of σ_α are lower and shrinkage of the α_j 's is greater than in the previously-fitted model with a uniform prior distribution on σ_α . To understand this, it helps to graph the prior distribution in the range for which the posterior distribution is substantial. The graph shows that the prior distribution is concentrated in the range $[0.5, 5]$, a narrow zone in which the likelihood is close to flat compared to this prior (as we can see because the distribution of the posterior simulations of σ_α closely matches the prior distribution, $p(\sigma_\alpha)$). By comparison, in the left graph, the uniform prior distribution on σ_α seems closer to “noninformative” for this problem, in the sense that it does not appear to be constraining the posterior inference.

Finally, the rightmost histogram in Figure 1 shows the corresponding result with an inverse-gamma(0.001, 0.001) prior distribution for σ_α^2 . This prior distribution is even more sharply peaked near zero and further distorts posterior inferences, with the problem arising because the marginal likelihood for σ_α remains high near zero.

In this example, we do not consider a uniform prior density on $\log \sigma_\alpha$, which would yield an improper posterior density with a spike at $\sigma_\alpha = 0$, like the rightmost graph in Figure 1, but more so. We also do not consider a uniform prior density on σ_α^2 , which would yield a posterior distribution similar to the leftmost graph in Figure 1, but with a slightly higher right tail.

This example is a gratifying case in which the simplest approach—the uniform prior density on σ_α —seems to perform well. As detailed in Gelman et al. (2003, Appendix C), this model is also straightforward to program directly using the Gibbs sampler or in Bugs, using either the basic model (1) or slightly faster using the expanded parameterization (2).

The appearance of the histograms and density plots in Figure 1 is crucially affected

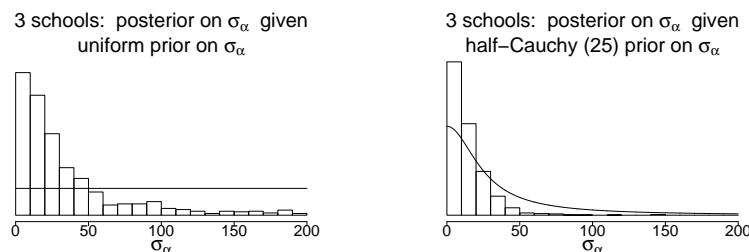


Figure 2: Histograms of posterior simulations of the between-school standard deviation, σ_α , from models for the 3-schools data with two different prior distributions on σ_α : (a) uniform $(0, \infty)$, (b) half-Cauchy with scale 25, set as a weakly informative prior distribution given that σ_α was expected to be well below 100. The histograms are not on the same scales. Overlain on each histogram is the corresponding prior density function. With only $J = 3$ groups, the noninformative uniform prior distribution is too weak, and the proper Cauchy distribution works better, without appearing to distort inferences in the area of high likelihood.

by the choice to plot them on the scale of σ_α . If instead they were plotted on the scale of $\log \sigma_\alpha$, the inverse-gamma(0.001, 0.001) prior density would appear to be the flattest. However, the inverse-gamma(ϵ, ϵ) prior is not at all “noninformative” for this problem since the resulting posterior distribution remains highly sensitive to the choice of ϵ . As explained in Section 4.2, the hierarchical model likelihood does not constrain $\log \sigma_\alpha$ in the limit $\log \sigma_\alpha \rightarrow -\infty$, and so a prior distribution that is noninformative on the log scale will not work.

5.2 Weakly informative prior distribution for the 3-schools problem

The uniform prior distribution seems fine for the 8-school analysis, but problems arise if the number of groups J is much smaller, in which case the data supply little information about the group-level variance, and a noninformative prior distribution can lead to a posterior distribution that is improper or is proper but unrealistically broad. We demonstrate by reanalyzing the 8-schools example using just the data from the first 3 of the schools.

Figure 2 displays the inferences for σ_α from two different prior distributions. First we continue with the default uniform distribution that worked well with $J = 8$ (as seen in Figure 1). Unfortunately, as the left histogram of Figure 2 shows, the resulting posterior distribution for the 3-schools dataset has an extremely long right tail, containing values of σ_α that are too high to be reasonable. This heavy tail is expected since J is so low (if J were any lower, the right tail would have an infinite integral), and using this as a posterior distribution will have the effect of undershrinking the estimates of the school effects α_j , as explained in Section 4.2.

The right histogram of Figure 2 shows the posterior inference for σ_α resulting from a half-Cauchy prior distribution of the sort described at the end of Section 3.2, with scale

parameter $A = 25$ (a value chosen to be a bit higher than we expect for the standard deviation of the underlying θ_j 's in the context of this educational testing example, so that the model will constrain σ_α only weakly). As the line on the graph shows, this prior distribution is high over the plausible range of $\sigma_\alpha < 50$, falling off gradually beyond this point. This prior distribution appears to perform well in this example, reflecting the marginal likelihood for σ_α at its low end but removing much of the unrealistic upper tail.

This half-Cauchy prior distribution would also perform well in the 8-schools problem; however it was unnecessary because the default uniform prior gave reasonable results. With only 3 schools, we went to the trouble of using a weakly informative prior, a distribution that was not intended to represent our actual prior state of knowledge about σ_α but rather to constrain the posterior distribution, to an extent allowed by the data.

6 Modeling variance components hierarchically

6.1 Application to a latin square Anova

We next consider an analysis of variance problem which has several variance components, one for each source of variation. Gelman (2005) analyzes data from a $5 \times 5 \times 2$ split-plot latin square with five full-plot treatments (labeled A, B, C, D, E), and with each plot divided into two subplots (labeled 1 and 2).

Source	df
row	4
column	4
(A,B,C,D,E)	4
plot	12
(1,2)	1
row \times (1,2)	4
column \times (1,2)	4
(A,B,C,D,E) \times (1,2)	4
plot \times (1,2)	12

Each row of the table corresponds to a different variance component, and the split-plot Anova can be understood as a linear model with nine variance components, $\sigma_1^2, \dots, \sigma_9^2$ —one for each row of the table. A default Bayesian analysis assigns a uniform prior distribution, $p(\sigma_1, \dots, \sigma_9) \propto 1$ (Gelman, 2005).

More generally, we can set up a hierarchical model, where the variance parameters have a common distribution with hyperparameters estimated from the data. Based on the analyses given above, we consider a half-Cauchy prior distribution with peak 0 and scale A , and with a uniform prior distribution on A . The hierarchical half-Cauchy model allows most of the variance parameters to be small but with the occasionally large σ_α ,

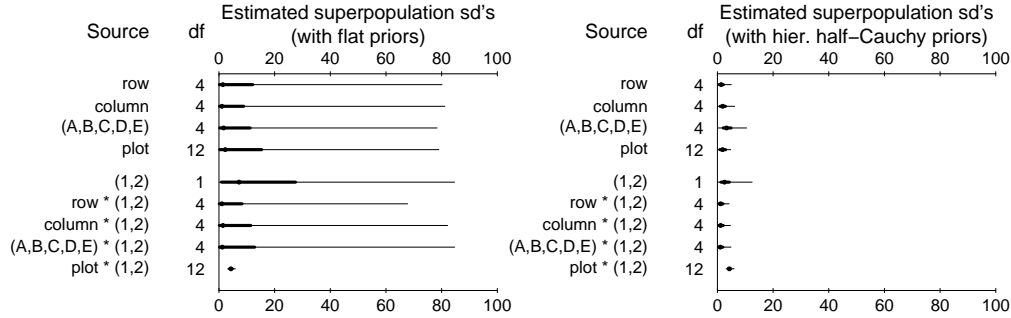


Figure 3: Posterior medians, 50%, and 95% intervals for standard deviation parameters σ_k estimated from a split-plot latin square experiment. The left plot shows inferences given uniform prior distributions on the σ_k 's, and the right plot shows inferences given a hierarchical half-Cauchy model with scale fit to the data. The half-Cauchy model gives much sharper inferences, using the partial pooling that comes with fitting a hierarchical model.

which seems reasonable in the typical settings of analysis of variance, in which most sources of variation are small but some are large (Daniel, 1959, Gelman, 2005).

6.2 Superpopulation and finite-population standard deviations

Figure 3 shows the inferences in the latin square example, given uniform and hierarchical half-Cauchy prior distributions for the standard deviation parameters σ_k . As the left plot shows, the uniform prior distribution does not rule out the potential for some extremely high values of the variance components—the degrees of freedom are low, and the interlocking of the linear parameters in the latin square model results in difficulty in estimating any single variance parameter. In contrast, the hierarchical half-Cauchy model performs a great deal of shrinkage, especially of the high ranges of the intervals. (For most of the variance parameters, the posterior medians are similar under the two models; it is the 75th and 97.5th percentiles that are shrunk by the hierarchical model.) This is an ideal setting for hierarchical modeling of variance parameters in that it combines separately imprecise estimates of each of the individual σ_k 's.

As discussed in Gelman (2005, Section 3.5), the σ_k 's are *superpopulation* parameters in that each represents the standard deviation of an entire population of effects, of which only a few of which were sampled for the experiment at hand. In estimating variance parameters estimated from few degrees of freedom, it can be helpful also to look at the *finite-population* standard deviation s_α of the corresponding linear parameters α_j .

For a simple hierarchical model of the form (1), s_α is simply the standard deviation of the J values of α_j . More generally, for more complicated linear models such as

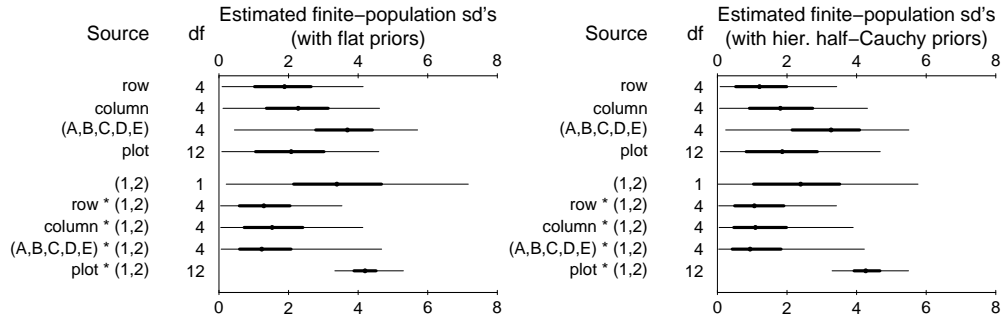


Figure 4: Posterior medians, 50%, and 95% intervals for finite-population standard deviations s_k estimated from a split-plot latin square experiment. The left plot shows inferences given uniform prior distributions on the σ_k 's, and the right plot shows inferences given a hierarchical half-Cauchy model with scale fit to the data. The half-Cauchy model gives sharper estimates even for these finite-population standard deviations, indicating the power of hierarchical modeling for these highly uncertain quantities. Compare to Figure 3 (which is on a different scale).

the split-plot latin square, s_α for any variance component is the root mean square of the coefficients' residuals after projection to their constraint space (see Gelman, 2005, Section 3.1). In any case, this finite-population standard deviation s can be calculated from its posterior simulations and, especially when degrees of freedom are low, is more precisely estimated than the superpopulation standard deviation σ .

Figure 4 shows posterior inferences for the finite-population standard deviation parameters s_α for each row of the latin square split-plot Anova, showing inferences given the uniform and hierarchical half-Cauchy prior distributions for the variance parameters σ_α . The half-Cauchy prior distribution does slightly better than the uniform, with the largest shrinkage occurring for the variance component that has just one degree of freedom. The Cauchy scale parameter A was estimated at 1.8, with a 95% posterior interval of [0.5, 5.1].

7 Recommendations

7.1 Prior distributions for variance parameters

In fitting hierarchical models, we recommend starting with a noninformative uniform prior density on standard deviation parameters σ_α . We expect this will generally work well unless the number of groups J is low (below 5, say). If J is low, the uniform prior density tends to lead to high estimates of σ_α , as discussed in Section 5.2. This miscalibration is an unavoidable consequence of the asymmetry in the parameter space,

with variance parameters restricted to be positive. Similarly, there are no always-nonnegative classical unbiased estimators of σ_α or σ_α^2 in the hierarchical model.

A user of a noninformative prior density might still like to use a proper distribution—reasons could include Bayesian scruple, the desire to perform prior predictive checks (see Box, 1980, Gelman, Meng, and Stern, 1996, and Bayarri and Berger, 2000) or Bayes factors (see Kass and Raftery, 1995, O’Hagan, 1995, and Pauler, Wakefield, and Kass, 1999), or because computation is performed in Bugs, which requires proper distributions. For a noninformative but proper prior distribution, we recommend approximating the uniform density on σ_α by a uniform on a wide range (for example, $U(0, 100)$ in the SAT coaching example) or a half-normal centered at 0 with standard deviation set to a high value such as 100. The latter approach is particularly easy to program as a $N(0, 100^2)$ prior distribution for ξ in (2).

When more prior information is desired, for instance to restrict σ_α away from very large values, we recommend working within the half- t family of prior distributions, which are more flexible and have better behavior near 0, compared to the inverse-gamma family. A reasonable starting point is the half-Cauchy family, with scale set to a value that is high but not off the scale; for example, 25 in the example in Section 5.2. When several variance parameters are present, we recommend a hierarchical model such as the half-Cauchy, with hyperparameter estimated from data.

We do *not* recommend the inverse-gamma(ϵ, ϵ) family of noninformative prior distributions because, as discussed in Sections 4.3 and 5.1, in cases where σ_α is estimated to be near zero, the resulting inferences will be sensitive to ϵ . The setting of near-zero variance parameters is important partly because this is where classical and Bayesian inferences for hierarchical models will differ the most (see Draper and Browne, 2005, and Section 3.4 of Gelman, 2005).

Figure 1 illustrates the generally robust properties of the uniform prior density on σ_α . Many Bayesians have preferred the inverse-gamma prior family, possibly because its conditional conjugacy suggested clean mathematical properties. However, by writing the hierarchical model in the form (2), we see conditional conjugacy in the wider class of half- t distributions on σ_α , which include the uniform and half-Cauchy densities on σ_α (as well as inverse-gamma on σ_α^2) as special cases. From this perspective, the inverse-gamma family has nothing special to offer, and we prefer to work on the scale of the standard deviation parameter σ_α , which is typically directly interpretable in the original model.

7.2 Generalizations

The reasoning in this paper should apply to hierarchical regression models (including predictors at the individual or group levels), hierarchical generalized linear models (as discussed by Christiansen and Morris, 1997, and Natarajan and Kass, 2000), and more complicated nonlinear models with hierarchical structure. The key idea is that parameters α_j —in general, group-level exchangeable parameters—have a common distribution with some scale parameter which we label σ_α . Some of the details will change—in

particular, if the model is nonlinear, then the normal prior distribution for the multiplicative parameter ξ in (2) will not be conditionally conjugate, however ξ can still be updated using the Metropolis algorithm. In addition, when regression predictors must be estimated, more than $J = 3$ groups may be necessary to estimate σ_α from a noninformative prior distribution, thus requiring at least weakly informative prior distributions for the regression coefficients, the variance parameters, or both.

There is also room to generalize these distributions to variance matrices in multivariate hierarchical models, going beyond the commonly-used inverse-Wishart family of prior distributions (Box and Tiao, 1973), which has problems similar to the inverse-gamma for scalar variances. Noninformative or weakly informative conditionally-conjugate priors could be applied to structured models such as described by Barnard, McCulloch, and Meng (2000) and Daniels and Kass (1999, 2001), expanded using multiplicative parameters as in Liu (2001) to give the models more flexibility.

Further work needs to be done in developing the next level of hierarchical models, in which there are several batches of exchangeable parameters, each with their own variance parameter—the Bayesian counterpart to the analysis of variance (Sargent and Hodges, 1997, Gelman, 2005). Specifying a prior distribution jointly on variance components at different levels of the model could be seen as a generalization of priors on the shrinkage factor, which is a function of both σ_y and σ_α (see Daniels, 1999, Natarajan and Kass, 2000, and Spiegelhalter, Abrams, and Myles, 2004, for an overview). In a model with several levels, it would make sense to give the variance parameters a parametric model with hyper-hyperparameters. This could be the ultimate solution to the difficulties of estimating σ_α for batches of parameters α_j where J is small, and we suppose that the folded-noncentral- t family could be useful here, as illustrated in Section 6.

Appendix: R and Bugs code for the hierarchical model with half-Cauchy prior density

Computations for the hierarchical normal model are most conveniently performed using Bugs (Spiegelhalter et al., 1994, 2003) as called from R (R Development Core Team, 2003), or by programming the Gibbs sampler directly in R. Both these strategies are described in detail in Gelman et al. (2003, Appendix C). Here we give an Bugs implementation of the 8-schools model with the half-Cauchy prior distribution (that is, the half- t with degrees-of-freedom parameter $\nu = 1$).

We put the following Bugs code in the file `schools.halfcauchy.bug`:

```
# Bugs model:  a half-Cauchy prior distribution on sigma.theta is induced
# using a normal prior on xi and an inverse-gamma on tau.eta

model {
  for (j in 1:J){
    y[j] ~ dnorm (theta[j], tau.y[j])      # J = the number of schools
    theta[j] <- mu.theta + xi*eta[j]        # data model:  the likelihood
  }
}
```

```

    tau.y[j] <- pow(sigma.y[j], -2)
  }
  xi ~ dnorm (0, tau.xi)
  tau.xi <- pow(prior.scale, -2)
  for (j in 1:J){
    eta[j] ~ dnorm (0, tau.eta)          # hierarchical model for theta
  }
  tau.eta ~ dgamma (.5, .5)              # chi^2 with 1 d.f.
  sigma.theta <- abs(xi)/sqrt(tau.eta)   # cauchy = normal/sqrt(chi^2)
  mu.theta ~ dnorm (0.0, 1.0E-6)        # noninformative prior on mu
}

```

We can then set up the data and call the Bugs model from R (using the `bugs.R` routines at Gelman, 2003). The scale parameter in the half-Cauchy distribution is `prior.scale`, which we set to the value 25 in the R code.

R code for calling the Bugs 8-schools model with half-Cauchy prior dist

```

schools <- read.table ("schools.dat", header=T)
J <- nrow (schools)
y <- schools$estimate
sigma.y <- schools$sd
prior.scale <- 25
data <- list ("J", "y", "sigma.y", "prior.scale")
inits <- function (){
  list (eta=rnorm(J), mu.theta=rnorm(1), xi=rnorm(1), tau.eta=runif(1))}
parameters <- c ("theta", "mu.theta", "sigma.theta")
schools.sim <- bugs (data, inits, parameters, "schools.halfcauchy.bug",
  n.chains=3, n.iter=1000)

```

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