

<p><b>Graphs</b></p> <p>Undir: <math>m \leq \binom{n}{2}</math>, <math>\sum_v \deg(v) = 2m</math></p> <p>Dir: <math>m \leq n * (n - 1)</math>, <math>\sum_v \text{indeg}(v) = \sum_v \text{outdeg}(v) = m</math></p> <p>Subgraph: result of removing an edge, <math>V' \subseteq V, E' \subseteq E</math></p> <p>Induced SG: result of removing node. Is subgraph, <math>e \in E' \leftrightarrow (e \in E \wedge (u, v)) \in V</math>.</p> <p><math>u</math> connected to <math>v</math>: <math>(u \sim v) \rightarrow \exists</math> path from <math>u</math> to <math>v</math></p> <p><math>G</math> connected if <math>(u \sim v) \forall (u, v)</math></p> <p><b>Representations</b></p> <p>Adj. Matrix: row 1 = outgoing edge, col 1 = incoming edge</p> <ul style="list-style-type: none"> <li>- Undir: <math>G = G^T</math></li> <li>- Find a neighbour: <math>O(n)</math></li> <li>- Access(<math>v</math>) = <math>O(1)</math>, traverse <math>V = O(n)</math></li> <li>- Traverse all edges of <math>v = O(n)</math></li> <li>- Traverse all edges of <math>G = O(n^2)</math></li> <li>- <math>O(V^2) = O(n^2)</math> space</li> </ul> <p>Adj. List: <math>\sum_v \text{outdeg}(v) = E</math></p> <ul style="list-style-type: none"> <li>- <math>O(V + E) = O(n + m)</math> space</li> <li>- Find a neighbour: <math>O(1)</math></li> <li>- Traverse all edges of <math>v = O( \text{neighbours}(v) )</math></li> <li>- Traverse all edges of <math>G = O(m)</math></li> <li>- Access(<math>v</math>) = <math>O(1)</math>, traverse <math>V = O(n)</math></li> </ul> <p><b>Trees</b></p> <p>Tree: connected, acyclic graph</p> <ul style="list-style-type: none"> <li>- Add edge <math>\rightarrow</math> cycle; Remove edge <math>\rightarrow</math> not connected</li> <li>- n - 1 edges</li> </ul> <p>Forest: graph with trees as connected components</p> <p>Spanning tree: <math>T \subseteq G</math> S.T <math>V(T) = V(G)</math></p> <p>Undir. is a tree <math>\leftrightarrow</math> connected and <math>E = V - 1</math></p> <p><b>BFS</b></p> <ul style="list-style-type: none"> <li>- <math>O(n + m)</math> time (list), <math>O(n^2)</math> (matrix)</li> <li>- <math>\Theta(n)</math> space for both list and matrix</li> <li>- Finds all nodes, finds shortest path from <math>s</math> to all others</li> </ul> <p><b>BFS</b></p> <ul style="list-style-type: none"> <li>- <math>O(n + m)</math> time (list), <math>O(n^2)</math> (matrix)</li> <li>- Finds all nodes, finds shortest path from <math>s</math> to all others</li> </ul> <p><b>Edge Classes</b></p> <p>The edge <math>(u, v)</math> refers to the FOREST, not the graph.</p> <ul style="list-style-type: none"> <li>- Tree: <math>(u, v) \in \text{Forest}</math></li> <li>- Forward: <math>v</math> is descendant of <math>u</math></li> <li>- Back: <math>v</math> is ancestry of <math>u</math> (back = fwd in undirs)</li> <li>- Cross: none of the above are true.</li> <li>- Und: DFS tree/fwd only, BFS tree/cross only</li> <li>- Dir: DFS: all edges, BFS: no fwd edges</li> </ul> <p><b>DAGs</b></p> <ul style="list-style-type: none"> <li>- Source: no incoming edges</li> <li>- Sink: no outgoing edges</li> <li>- Multiple sources/sinks are possible. At least one of each in every DAG.</li> <li>- Source &amp; Sink <math>\rightarrow</math> no cycles</li> <li>- A Digraph is a DAG <math>\leftrightarrow</math> DFS has no back edges</li> </ul> <p><b>Toposort</b></p> <ul style="list-style-type: none"> <li>- Produces ordering s.t <math>(u, v) \in E \rightarrow u</math> appears before <math>v</math> in the ordering</li> <li>- Digraph has a Toposort <math>\leftrightarrow</math> it is a DAG</li> <li>- Run DFS, order in decreasing order of finish time</li> <li>- <math>O(n + m)</math></li> <li>- Orders are not unique.</li> </ul> <p><b>SCCs</b></p> <ul style="list-style-type: none"> <li>- Run DFS. Run DFS on <math>G^T</math>, in decreasing order of ftime. The forests of the transpose DFS are the SCCs.</li> <li>- Independent of toposort ordering</li> </ul>	<p><b>Minimum Spanning Trees</b></p> <ul style="list-style-type: none"> <li>- Spanning tree w/ minimum weight</li> <li>- DFS and BFS build spanning trees, but <i>not</i> necessarily the MST.</li> <li>- Optimal Substructure: if <math>T = \text{MST of } G \rightarrow T[U]</math>, where <math>U \subseteq V</math>, if <math>T[U]</math> is connected it is an MST.</li> </ul> <p><b>Prim:</b> add best vertex</p> <p><b>Kruskal's Algorithm</b> (<math>O((m + n) \log(n))</math>)</p> <ul style="list-style-type: none"> <li>- Only consider edges that do NOT create a cycle (safe edges)</li> <li>- Add lowest-cost edge on each iteration</li> <li>- Has greedy-choice property</li> </ul> <p><b>Edge Switching</b></p> <ul style="list-style-type: none"> <li>- Let <math>e' \notin T</math>, where <math>T \cup \{e'\}</math> has a cycle. For any <math>e \in E</math>, where <math>e</math> is in the cycle, <math>T \cup \{e'\} - \{e\}</math> is a tree.</li> </ul> <p><b>Single-Source Shortest Paths (SSSPs)</b></p> <ul style="list-style-type: none"> <li>- The problem: find the min-cost path from source <math>s</math> to each vertex <math>v</math>.</li> <li>- Shortest path is at most of length <math>n - 1</math>.</li> </ul> <p><b>Dijkstra</b></p> <ul style="list-style-type: none"> <li>- List + binary heap (as a min-PQ): <math>O((m + n) \log(n))</math></li> <li>- Matrix: <math>O(n^2 + m \log(n))</math></li> <li>- Fib heap: <math>\Theta(m + n \log(n))</math></li> <li>- No negative cycles (undir), no negative edges (dir)</li> </ul> <p><b>Relaxing an Edge</b></p> <ul style="list-style-type: none"> <li>- <math>d(v)</math> only updated w/ relax <math>\rightarrow d(v) \geq d(s, v)</math></li> </ul> <p>relax(<math>u, v</math>): if <math>d(v) &gt; d(u) + w(u, v)</math>:</p> $d(v) \leftarrow d(u) + w(u, v)$ <p><b>Bellman-Ford</b> <math>O(VE)</math></p> <ul style="list-style-type: none"> <li>- Can handle negative edge weights (but not negative cycles!)</li> </ul> <p><b>Procedure:</b> Initialize <math>d(v) = \infty, \forall v</math>; set <math>d(s) = 0</math>; for <math>i \in \{1, \dots, (n - 1)\}</math>, relax <i>all edges</i>; for <math>e \in E</math>, if <math>d(u) + w(u, v) &lt; d(v)</math>, return False. Else, return true. This last step checks for negative cycles.</p> <ul style="list-style-type: none"> <li>- Use a DP table, dim = <math>0 : (n - 1) \times n</math></li> <li>- <math>d_i[v] \leftarrow \min(d_{i-1}[v], \min_{u \in \text{Neigh}(v)} [d_{i-1}[u] + w(u, v)])</math></li> </ul> <p><b>Floyd-Warshall</b> <math>O(n^3)</math></p> <ul style="list-style-type: none"> <li>- Allows negative weights, no negative cycles.</li> <li>- All-pairs shortest path (APSP)</li> </ul> <p>Suppose <math>V = \{1, 2, \dots, n\}</math>.</p> <p>Then, <math>d[i, j, k]</math> = distance of shortest path from <math>i</math> to <math>j</math>, such that all intermediate vertices <math>\in \{1, 2, \dots, k\}</math>.</p> <ul style="list-style-type: none"> <li>- Case 1: don't need vertex <math>k</math>: <math>d[i, j, k] = d[i, j, (k - 1)]</math>.</li> <li>- Case 2: need vertex <math>k</math>: <math>d[i, j, k] = d[i, k, (k - 1)] + d[k, j, (k - 1)]</math>.</li> <li>- So, <math>d[i, j, k] = \min(\text{Case 1, Case 2})</math></li> <li>- Base cases: <math>d[i, j, 0] = w(i, j), d[i, i, k] = 0</math>.</li> </ul>
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## Greedy Algorithms

Optimal Substructure: an optimal choice must be included in *an* optimal solution, but not necessarily all of them.

### Fractional Knapsack

$v_i$  = profit per unit weight  $b_i/w_i$

$x_i = \min(w_i, W_{\text{remaining}})$

add  $x_i$  amount of item  $i$

$W_{\text{remaining}} \leftarrow W_{\text{remaining}} - x_i$

Choose item with highest  $v_i$

$X^*$  is unique  $\rightarrow$  all  $x^* \in X^*$  are saturated.

### Job Scheduling

- Earliest-Start-Time-First (ESTF)

Sort the  $n$  jobs by start time  $O(n \log(n))$ ; iterate  $n$  times, and on each iteration find the right machine, schedule the job, and update the times. Total runtime:  $O(n \log(n))$ .

Alternatively use a min-heap: also  $O(n \log(n))$ .

### Activity Selection

- Earliest-Finish-Time-First (EFTF);  $\Theta(n \log(n))$

### Dynamic Programming

#### Integral Knapsack

-  $n$  items: table with  $0 : n - 1$  rows,  $0 : W$  columns.  $D$  is remaining capacity,  $W$  is total capacity.

-  $\forall D, A[0, D] = 0$

-  $\forall i, A[i, 0] = 0$

- Else,  $A[i, D] = \max(A[i - 1, D], v_i + A[i - 1, D - w_i])$

#### Rod Cutting

-  $r_0 = 0$

- Else,  $r_n = \max_{i \in 1:n} (p_i + r_{n-i})$

### Longest Common Subsequence

-  $O(nm)$

-  $\text{len}(X) = n, \text{len}(Y) = m$ .

- Table:  $0 : n \times 0 : m$ .

-  $A[i, j] = \max(D[i - 1, j], D[i, j - 1], 1 + D[i - 1, j - 1])$

- Last one only if  $X[i] = Y[j]$ .

### MCM

-  $n$  matrices

-  $d \in \{0, \dots, n + 1\}$

-  $A[i, j] = \min_{i \leq k < j} (A[i, k] + A[k + 1, j], + d_{i-1}d_kd_j)$