

<p>Graphs</p> <p>Undir: $m \leq \binom{n}{2}$, $\sum_v \deg(v) = 2m$</p> <p>Dir: $m \leq n * (n - 1)$, $\sum_v \text{indeg}(v) = \sum_v \text{outdeg}(v) = m$</p> <p>Subgraph: result of removing an edge, $V' \subseteq V, E' \subset E$</p> <p>Induced SG: result of removing node. Is subgraph, $e \in E' \leftrightarrow (e \in E \wedge (u, v)) \in V$.</p> <p>$u$ connected to v: $(u \sim v) \rightarrow \exists$ path from u to v</p> <p>G connected if $(u \sim v) \forall (u, v)$</p> <p>Representations</p> <p>Adj. Matrix: row 1 = outgoing edge, col 1 = incoming edge</p> <ul style="list-style-type: none"> - Undir: $G = G^T$ - Find a neighbour: $O(n)$ - Access(v) = $O(1)$, traverse $V = O(n)$ - Traverse all edges of $v = O(n)$ - Traverse all edges of $G = O(n^2)$ - $O(V^2) = O(n^2)$ space <p>Adj. List: $\sum_v \text{outdeg}(v) = E$</p> <ul style="list-style-type: none"> - $O(V + E) = O(n + m)$ space - Find a neighbour: $O(1)$ - Traverse all edges of $v = O(\text{neighbours}(v))$ - Traverse all edges of $G = O(m)$ - Access(v) = $O(1)$, traverse $V = O(n)$ <p>Trees</p> <p>Tree: connected, acyclic graph</p> <ul style="list-style-type: none"> - Add edge \rightarrow cycle; Remove edge \rightarrow not connected - $n - 1$ edges <p>Forest: graph with trees as connected components</p> <p>Spanning tree: $T \subseteq G$ S.T $V(T) = V(G)$</p> <p>Undir. is a tree \leftrightarrow connected and $E = V - 1$</p> <p>BFS</p> <ul style="list-style-type: none"> - $O(n + m)$ time (list), $O(n^2)$ (matrix) - $\Theta(n)$ space for both list and matrix - Finds all nodes, finds shortest path from s to all others <p>BFS</p> <ul style="list-style-type: none"> - $O(n + m)$ time (list), $O(n^2)$ (matrix) - Finds all nodes, finds shortest path from s to all others <p>Edge Classes</p> <p>The edge (u, v) refers to the FOREST, not the graph.</p> <ul style="list-style-type: none"> - Tree: $(u, v) \in \text{Forest}$ - Forward: v is descendant of u - Back: v is ancestry of u (back = fwd in undirs) - Cross: none of the above are true. - Und: DFS tree/fwd only, BFS tree/cross only - Dir: DFS: all edges, BFS: no fwd edges <p>DAGs</p> <ul style="list-style-type: none"> - Source: no incoming edges - Sink: no outgoing edges - Multiple sources/sinks are possible. At least one of each in every DAG. - Source & Sink \rightarrow no cycles - A Digraph is a DAG \leftrightarrow DFS has no back edges <p>Toposort</p> <ul style="list-style-type: none"> - Produces ordering s.t $(u, v) \in E \rightarrow u$ appears before v in the ordering - Digraph has a Toposort \leftrightarrow it is a DAG - Run DFS, order in decreasing order of finish time - $O(n + m)$ - Orders are not unique. <p>SCCs</p> <ul style="list-style-type: none"> - Run DFS. Run DFS on G^T, in decreasing order of ftime. The forests of the transpose DFS are the SCCs. - Independent of toposort ordering 	<p>Minimum Spanning Trees</p> <ul style="list-style-type: none"> - Spanning tree w/ minimum weight - DFS and BFS build spanning trees, but <i>not</i> necessarily the MST. - Optimal Substructure: if $T = \text{MST of } G \rightarrow T[U]$, where $U \subset V$, if $T[U]$ is connected it is an MST. <p>Prim: add best vertex</p> <p>Kruskal's Algorithm ($O((m + n) \log(n))$)</p> <ul style="list-style-type: none"> - Only consider edges that do NOT create a cycle (safe edges) - Add lowest-cost edge on each iteration - Has greedy-choice property <p>Edge Switching</p> <ul style="list-style-type: none"> - Let $e' \notin T$, where $T \cup \{e'\}$ has a cycle. For any $e \in E$, where e is in the cycle, $T \cup \{e'\} - \{e\}$ is a tree. <p>Single-Source Shortest Paths (SSSPs)</p> <ul style="list-style-type: none"> - The problem: find the min-cost path from source s to each vertex v. - Shortest path is at most of length $n - 1$. <p>Relax</p> <p>If $d(v) > d(u) + w(u, v)$, then $d(v) \leftarrow d(u) + w(u, v)$</p> <p>Dijkstra</p> <p>Algo: <i>Init.</i> $S = \emptyset$; <i>Init.</i> $d(v) = \infty, \forall v \neq s, d(s) = 0$; <i>Init.</i> Min-Queue, keyed by $d(v)$. <i>While</i> $Q \neq \emptyset$, <i>extract</i> $u = \min(Q)$, <i>Add</i> u to S; <i>Relax</i> all edges (u, v).</p> <ul style="list-style-type: none"> - List + binary heap (as a min-PQ): $O((m + n) \log(n))$ - Matrix: $O(n^2 + m \log(n))$ - Fib heap: $\Theta(m + n \log(n))$ - No negative cycles (undir), no negative edges (dir) <p>Properties</p> <p><i>Subpath Optimality:</i> If $P = (s, \dots, u, \dots, v, \dots, t)$, then each subpath is the shortest corresponding path.</p> <p><i>Triangle Inequality:</i> $d(u, w) \leq d(u, v) + d(v, w)$.</p> <p>Relaxing an Edge</p> <ul style="list-style-type: none"> - $d(v)$ only updated w/ relax $\rightarrow d(v) \geq d(s, v)$ <p>relax(u, v): if $d(v) > d(u) + w(u, v)$:</p> $d(v) \leftarrow d(u) + w(u, v)$ <p>Bellman-Ford $O(VE)$</p> <ul style="list-style-type: none"> - Can handle negative edge weights (but not negative cycles!) - Updates distances OFFLINE. <p>Algo: <i>Init.</i> $d(v) = \infty, \forall v \neq s, d(s) = 0$; <i>For</i> $i \in \{1, \dots, n - 1\}$, <i>For</i> $(u, v) \in E$, <i>Relax</i> edges (u, v). <i>Endfor.</i> <i>For</i> $(u, v) \in E$; <i>If</i> $d(u) + w(u, v) \leq d(v)$, <i>Return</i> FALSE. <i>Else</i> return TRUE.</p> <ul style="list-style-type: none"> - Use a DP table, dim = 0 : $(n - 1) \times n$ - $d_i[v] \leftarrow \min(d_{i-1}[v], \min_{u \in \text{Neigh}(v)} [d_{i-1}[u] + w(u, v)])$ - Order irrelevant to final product. <p>Floyd-Warshall $O(n^3)$</p> <ul style="list-style-type: none"> - $V \times V$ table, v_1, \dots, v_n. - Allows negative weights, no negative cycles. - All-pairs shortest path (APSP) <p>Suppose $V = \{1, 2, \dots, n\}$.</p> <p>Then, $d[i, j, k]$ = distance of shortest path from i to j, such that all intermediate vertices $\in \{1, 2, \dots, k\}$.</p> <ul style="list-style-type: none"> - Case 1: don't need vertex k: $d[i, j, k] = d[i, j, (k - 1)]$. - Case 2: need vertex k: $d[i, j, k] = d[i, k, (k - 1)] + d[k, j, (k - 1)]$. - So, $d[i, j, k] = \min(\text{Case 1, Case 2})$ - Base cases: $d[i, j, 0] = w(i, j), d[i, i, k] = 0$.
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Greedy Algorithms

Optimal Substructure: an optimal choice must be included in *an* optimal solution, but not necessarily all of them.

Fractional Knapsack

v_i = profit per unit weight b_i/w_i

x_i = $\min(w_i, W_{\text{remaining}})$

add x_i amount of item i

$W_{\text{remaining}} \leftarrow W_{\text{remaining}} - x_i$

Choose item with highest v_i

X^* is unique \rightarrow all $x^* \in X^*$ are saturated.

Job Scheduling

- Earliest-Start-Time-First (ESTF)

Sort the n jobs by start time $O(n \log(n))$; iterate n times, and on each iteration find the right machine, schedule the job, and update the times.

Total runtime: $O(n \log(n))$.

Alternatively use a min-heap: also $O(n \log(n))$.

Activity Selection

- Earliest-Finish-Time-First (EFTF); $\Theta(n \log(n))$

Dynamic Programming

Integral Knapsack

- n items: table with $0 : n - 1$ rows, $0 : W$ columns. D is remaining capacity, W is total capacity.

- $\forall D, A[0, D] = 0$

- $\forall i, A[i, 0] = 0$

- Else, $A[i, D] = \max(A[i - 1, D], v_i + A[i - 1, D - w_i])$

Rod Cutting

- $r_0 = 0$

- Else, $r_n = \max_{i \in 1:n} (p_i + r_{n-i})$

Longest Common Subsequence

- $O(nm)$

- $len(X) = n, len(Y) = m$.

- Table: $0 : n \times 0 : m$.

- $A[i, j] = \max(D[i - 1, j], D[i, j - 1], 1 + D[i - 1, j - 1])$

- Last one only if $X[i] = Y[j]$.

MCM

- n matrices

- $d \in \{0, \dots, n + 1\}$

- $A[i, j] = \min_{i \leq k < j} (A[i, k] + A[k + 1, j], + d_{i-1} d_k d_j)$

Asymptotic Cheatsheet

For some set S ,

If $f(n) \in S(g(n))$ and $g(n) \in S(h(n))$ then $f(n) \in S(h(n))$.

$$\sum_{k=0}^n r^k = \frac{1-r^{n+1}}{1-r} = \frac{r^{n+1}-1}{r-1}$$

$$n! = \sqrt{2\pi n} \left(\frac{n}{e}\right)^n$$

Limits:

$$\lim_{n \rightarrow \infty} \frac{h(n)}{f(n)} = 0 \rightarrow h(n) \in o(f(n))$$

$$\lim_{n \rightarrow \infty} \frac{h(n)}{f(n)} = k > 0 \rightarrow h(n) \in \Theta(f(n))$$

$$\log^k(n) \in o(n^\varepsilon), \forall k, \varepsilon > 0$$

$$n \log(n) \in \Theta(\log(n!))$$

Master Theorem

Let $T(n) = aT(\frac{n}{b}) + f(n)$

Bottom-Heavy: Leaves dominate runtime

- $f(n) \in O(n^{\log_b(a)-\varepsilon}) \rightarrow T(n) \in \Theta(n^{\log_b(a)})$

Balanced: Leaves and internal nodes do equal work

- $f(n) \in \Theta(n^{\log_b(a) \log_n^k}) \rightarrow T(n) \in \Theta(n^{\log_b(a) \log^{k+1}(n)}), k \geq 0$

Top-Heavy: Eariler nodes dominate runtime

- $f(n) \in \Omega(n^{\log_b(a)+\varepsilon})$, and $af(\frac{n}{b}) \leq \delta f(n), \delta < 1 \rightarrow T(n) \in \Theta(f(n))$

Heaps

Max-Heap Property: $A[\text{Parent}(i)] \geq A[i]$

Heap of n keys has height $\lfloor \log(n) \rfloor$

buildMaxHeap: $O(n)$

extractMax: $O(\log(n))$

heapSort: $\Theta(n \log(n))$

QuickSort

Sorting Lower Bound

Binary Search Trees

Right-(Left)-Rotate: x becomes the right (left) child of new root, usually its left (right) child.

AVL Trees

- Height-balanced: $|h_l - h_r| \leq 1$

- $h = O(\log(n))$

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