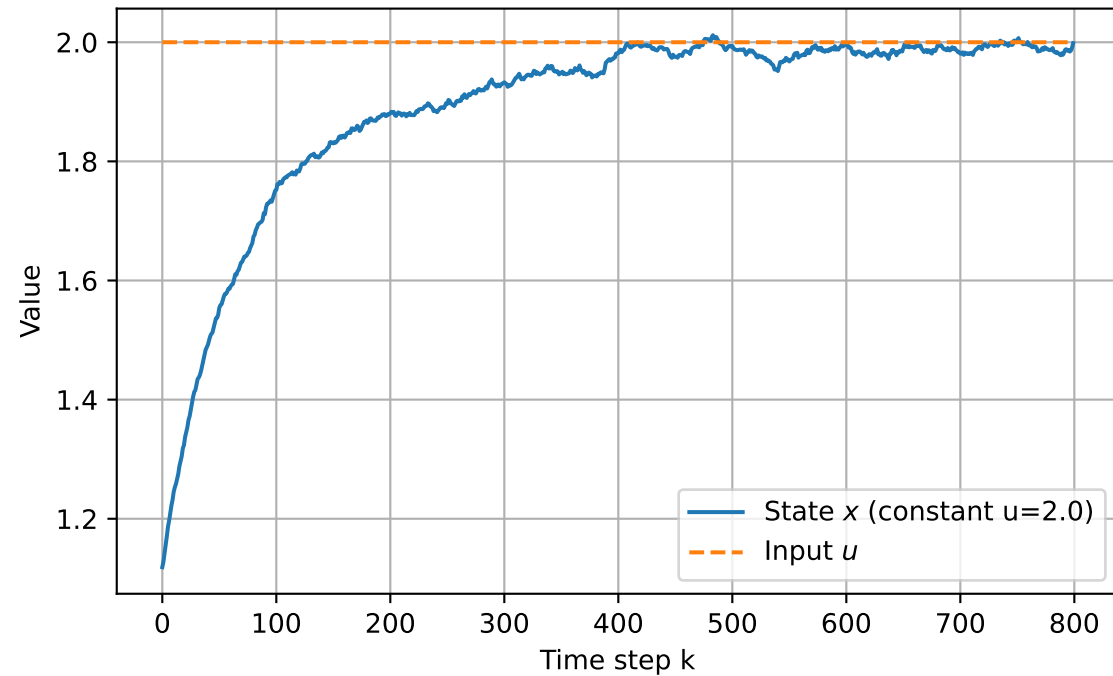


Trajectory with Constant Input



Trajectory with Sinusoidal Input

