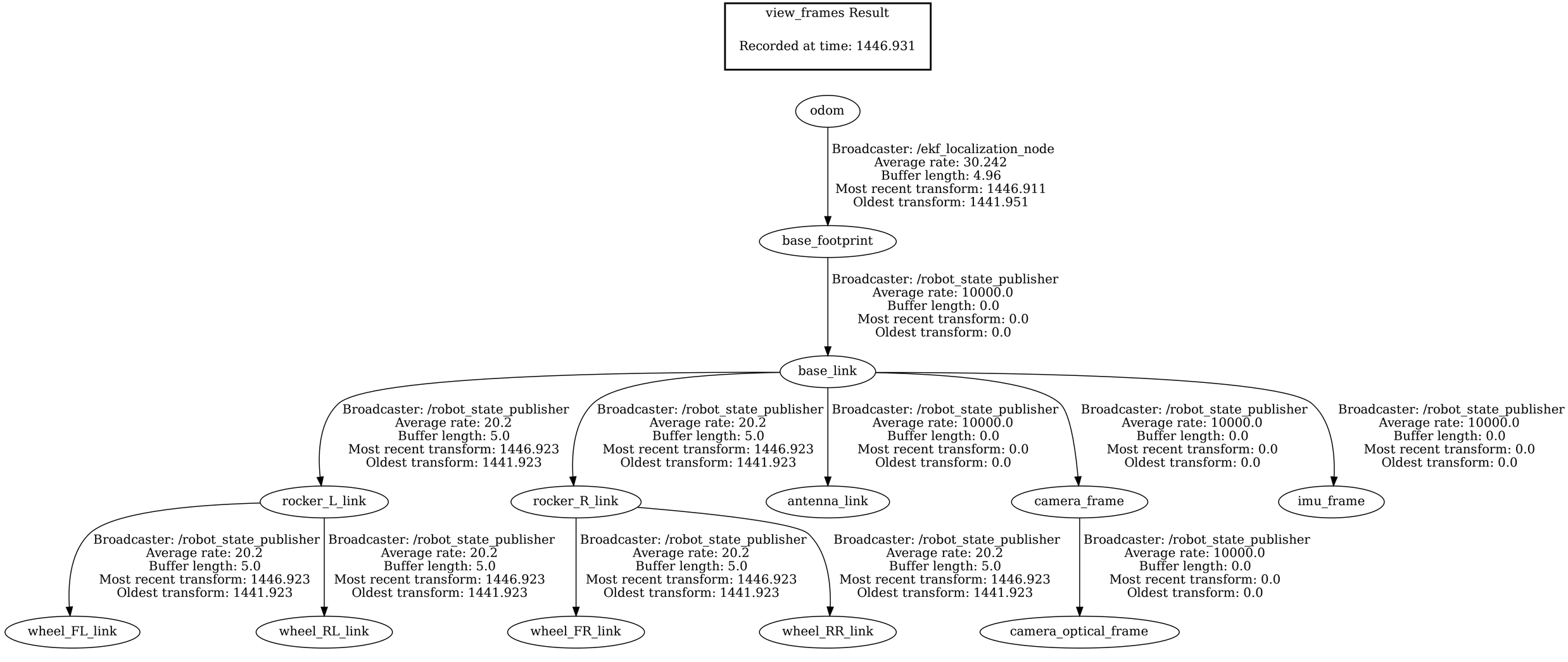
view_frames Result
Recorded at time: 1446.931
odom
Broadcaster: /ekf_localization_node
Average rate: 30.242
Buffer length: 4.96
Most recent transform: 1446.911
Oldest transform: 1441.951
base_footprint
Broadcaster: /robot_state_publisher
Average rate: 10000.0
Buffer length: 0.0
Most recent transform: 0.0
Oldest transform: 0.0
base_link
Broadcaster: /robot_state_publisher
Average rate: 20.2
Buffer length: 5.0
Most recent transform: 1446.923
Oldest transform: 1441.923
Broadcaster: /robot_state_publisher
Average rate: 20.2
Buffer length: 5.0
Most recent transform: 1446.923
Oldest transform: 1441.923
Broadcaster: /robot_state_publisher
Average rate: 10000.0
Buffer length: 0.0
Most recent transform: 0.0
Oldest transform: 0.0
Broadcaster: /robot_state_publisher
Average rate: 10000.0
Buffer length: 0.0
Most recent transform: 0.0
Oldest transform: 0.0
Broadcaster: /robot_state_publisher
Average rate: 10000.0
Buffer length: 0.0
Most recent transform: 0.0
Oldest transform: 0.0
rocker_L_link
rocker_R_link
antenna_link
camera_frame
imu_frame
Broadcaster: /robot_state_publisher
Average rate: 20.2
Buffer length: 5.0
Most recent transform: 1446.923
Oldest transform: 1441.923
Broadcaster: /robot_state_publisher
Average rate: 20.2
Buffer length: 5.0
Most recent transform: 1446.923
Oldest transform: 1441.923
Broadcaster: /robot_state_publisher
Average rate: 20.2
Buffer length: 5.0
Most recent transform: 1446.923
Oldest transform: 1441.923
Broadcaster: /robot_state_publisher
Average rate: 20.2
Buffer length: 5.0
Most recent transform: 1446.923
Oldest transform: 1441.923
Broadcaster: /robot_state_publisher
Average rate: 10000.0
Buffer length: 0.0
Most recent transform: 0.0
Oldest transform: 0.0
wheel_FL_link
wheel_RL_link
wheel_FR_link
wheel_RR_link
camera_optical_frame