

Clifford Tableaus and the Stabilizer Algorithm

Leonard Uscinowicz

Technical University of Munich

December 20th, 2024



Outline



- Preliminary Definitions
- Stabilizer Formalism

Pauli Matrixes



$$I = \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix} \qquad X = \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} \qquad Y = \begin{pmatrix} 0 & -i \\ i & 0 \end{pmatrix} \qquad Z = \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix}$$

Products of Pauli matrices:

$$I^2 = X^2 = Y^2 = Z^2 = I$$

$$IX = XI = X \qquad IY = YI = Y \qquad IZ = ZI = Z$$

$$XY = iZ \qquad YX = -iZ$$

$$YZ = iX \qquad ZY = -iX$$

$$ZX = iY \qquad XZ = -iY$$

[1] Scott Aaronson and Daniel Gottesman. "Improved simulation of stabilizer circuits". In: *Physical Review A—Atomic, Molecular, and Optical Physics* 70.5 (2004), p. 052328

Group Theory



Group (G,\cdot) is a non-empty set G with a binary group multiplication operation " \cdot " with the properties:

- Closure: $\forall g_1, g_2 \in G \Longrightarrow g_1 \cdot g_2 \in G$
- **Associativity:** $\forall g_1, g_2, g_3 \in G \Longrightarrow g_1 \cdot (g_2 \cdot g_3) = (g_1 \cdot g_2) \cdot g_3$
- Identity: $\exists e \in G$ such that $\forall g \in G \Longrightarrow e \cdot g = g \cdot e = g$
- Inverse: $\forall g \in G \Longrightarrow \exists g^{-1} \in G \text{ such that } g \cdot g^{-1} = g^{-1} \cdot g = e$
- [2] Michael A Nielsen and Isaac L Chuang. *Quantum computation and quantum information*. Cambridge university press, 2010

Pauli Group



Pauli Group \mathcal{P}_n is defined as the group of n-qubit Pauli operators. It consists of all tensor products of n Pauli matrices, together with a phase factor of ± 1 or $\pm i$.

$$\mathcal{P}_{1} = \{ \pm I, \pm iI, \pm X, \pm iX, \pm Y, \pm iY, \pm Z, \pm iZ \}$$

$$\mathcal{P}_{n} = \left\{ i^{m} \bigotimes_{j=1}^{n} \sigma_{k_{j}} \middle| m, k_{j} \in \{0, 1, 2, 3\}, \sigma_{0} = I, \sigma_{1} = X, \sigma_{2} = Y, \sigma_{3} = Z \right\}$$

Size of a Pauli Group: $|\mathcal{P}_n| = 4^{n+1}$

[1] Scott Aaronson and Daniel Gottesman. "Improved simulation of stabilizer circuits". In: *Physical Review A—Atomic, Molecular, and Optical Physics* 70.5 (2004), p. 052328

Pauli Group Operation



Given two Pauli operators $P=i^{m_P}\bigotimes_{j=1}^n P_j$ and $Q=i^{m_Q}\bigotimes_{j=1}^n Q_j$, their product, as necessitated by Group Definition, is:

$$P \cdot Q = i^{m_P + m_Q} \bigotimes_{j=1}^n P_j Q_j$$

P commutes with Q if the number of indices j such that P_j anti-commutes with Q_j is even.

[1] Scott Aaronson and Daniel Gottesman. "Improved simulation of stabilizer circuits". In: *Physical Review A—Atomic, Molecular, and Optical Physics* 70.5 (2004), p. 052328

Group Generators



A set of l elements $\{g_i\}_{1 \leq i \leq l}$ generates a group G if every element $g \in G$ can be written as a product of the generators.

In this case, the group ${\cal G}$ can be written in terms of its generators:

$$G = \langle g_i \mid i \in \mathbb{N}, 1 \leq i \leq l \rangle$$
 Examples:
$$\begin{aligned} \mathcal{P}_1 &= \langle X, Z, iI \rangle \\ \langle X \rangle &= \{I, X\} \end{aligned}$$

Outline



- Preliminary Definitions
- Stabilizer Formalism

Stabilizer Groups Definitions



- Element $g \in \mathcal{P}_n$ stabilizes $|\psi\rangle$ iff $g |\psi\rangle = |\psi\rangle$. $|\psi\rangle$ is eigenstate of g with eigenvalue +1.
- $S \cong$ Subgroup of the Pauli Group \mathcal{P}_n : $S \subseteq \mathcal{P}_n$.
- $V_S =$ Set of n-qubit states stabilized by S:

$$V_S = \{ |\psi\rangle \mid S \subseteq \mathcal{P}_n, \forall g \in S \text{ holds: } g |\psi\rangle = |\psi\rangle \}$$

Stabilizer Groups Properties



Not just any subgroup S of the Pauli group can be used as the stabilizer for a non-trivial vector space V_S .

Conditions for S such that V_S not trivial:

- **Commutativity:** $\forall g_1, g_2 \in S$ holds: $g_1g_2 = g_2g_1$
- Strict Identity: $-I \notin S$, $iI \notin S$, $-iI \notin S$,

Stabilizer Conditions Commutativity Proof



Let V_S be non-trivial.

Let $g_1, g_2 \in S$.

- \implies g_1 and g_2 are tensor products of Pauli matrices.
- \implies g_1 and g_2 must either commute or anti-commute.

Suppose g_1 and g_2 anti-commute:

$$|\psi
angle = g_1g_2\,|\psi
angle = -g_2g_1\,|\psi
angle = -\,|\psi
angle \quad\Longleftrightarrow\quad |\psi
angle = \vec{0}\quad\Longrightarrow\quad V_S \ \mbox{is trivial}.$$

- \implies g_1 and g_2 anti-commuting leads to a contradiction.
- $\Longrightarrow g_1$ and g_2 commute.
- [2] Michael A Nielsen and Isaac L Chuang. *Quantum computation and quantum information*. Cambridge university press, 2010

Refernces



- [1] Scott Aaronson and Daniel Gottesman. "Improved simulation of stabilizer circuits". In: *Physical Review A—Atomic, Molecular, and Optical Physics* 70.5 (2004), p. 052328.
- [2] Michael A Nielsen and Isaac L Chuang. *Quantum computation and quantum information*. Cambridge university press, 2010.