521 M7280 – SATELLITE GEODESY SPRING SEMESTER 2017

Lab No. 5

handed out Wednesday, March 29, 2017 due Wednesday, April 12, 2017, 09:10 Name:

GREENWICH SIDEREAL TIME vs. QUASI-INERTIAL FRAME

- 1. Write a Matlab program that computes the Greenwich Sidereal Time (GST) (sampling at every 10 minutes) for a three-day period. Use the GST value on your birthday as the initial value.
 - a. List your results in a table from, which should contain 7 columns: time (0 to 3*24*60 minutes for every 10 minutes; GST (°, ', "); GST (hour, min, sec). The output significant digit should be equivalent to 0.0001 second.
 - b. Plot the GST values in a map. Mark the GST values at the start of each day with a different symbol.
 - c. Check the accuracy of your program using the provided table.
- 2. Convert the ECEF coordinates of one point that you generated in the previous assignment to the coordinates in quasi-inertial frame during a one-day period.
 - a. List your results in a table with 9 columns: GST (hour, min, sec), x, y, z, X, Y, Z.
 - b. Plot the point's position in two 3-D maps (one for quasi-inertial and the other for ECEF frames).
- 3. Discuss extensively the required significant digit (1a), the behavior of GST (1b), and the behaviors of the point in the quasi-inertial and ECEF frames (2a & 2b).

Use for
$$GM = 398600.4418 (km^3/s^2)$$
, $\omega_e^* = 7292115.8553 \times 10^{-11} (rad/s)$, $\omega_e = 7292115 \times 10^{-11} (rad/s)$, and $R = 6371.000000 (km)$.

Your (individual) final report should contain (use A4 papers):

- this page as the cover sheet
- source code(s) and outputs; do not forget to add your name and lots of comment cards to the source listing (%)
- input and output files from program [input/output values used and calculated], if any
- plots, including captions on axes, title, your name, LB#/HM#, course title, date (if any)
- derivation and description of formulas used, accompanied by figures where applicable
- evidence of computational accuracy
- discussion of results