Liu Xiangchen

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Tianjin
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EDUCATION

Tianjin University Sep 2018 - Present

Measurement and Control Technology and Instruments Bachelor School of Precision Instrument and Opto-electronics Engineering Tianjin

Major GPA: 3.85/4.0

Undergraduate Coursework: Introduction to Robotics(ROS) Computer Vision(C++) Digital Signal Processing(MATLAB) Visual C++ programming(Object-oriented C++) System verilog design(Verilog) Mathematics Model (Python) Advanced Mathematics(99) Probability Theory and Mathematical Statistics(97)

Honors:

Oct. 2020, China University Robot Competition(Robomaster) Third Prize - Tianjin University

Oct. 2021, China University Robot Competition(Robomaster) Third Prize - Tianjin University

Nov. 2020, TI Cup College Student Electronic Design Competition Third Prize - Tianjin University

Mar. 2020, Mathematical Contest In Modeling Honorable Prize - Tianjin University

Nov. 2019, The Chinese Mathematics Competitions First Prize - Tianjin University

RESEARCH EXPERIENCE

iTAM: A incremental Tracking and Mapping system Mar 2021 - Present

Participator

iTAM is a robust RGB-D tracking and mapping system which makes use of multi-level constraints to optimize camera pose and obtain a completed dense map by detecting the occluded regions and Non-planar instance using geometric segmentation and image inpainting. Accomplishing the detection of the occluded area and the non-planar area and Completion of the occluded area based on boundaries and image after inpainted. This work is under the lead of Computer Aided Medical Procedures & Augmented Reality, Technical University of Munich

LEADERSHIP EXPERIENCE

Auto-aim system in Robomaster Competition Sep 2020 - Present

Leader Vision/Algorithm Group Tianjin

The auto-aim system is to help our robot to achieve the intelligent detection of enemy robot, which makes use of traditional geometric feature extraction and the nerual network as the detector, using the extended kalman filter(EKF) as the predictor, KCF as the tracker. Realizing automatic attack on enemy robots in robot competitions.

SuperCapacity in Robomaster Jan 2020 - Aug 2021

Leader Control Group Tianjin

The Super Capacity Project aims to improve the maneuverability of robots in fierce competitions.

Designed the control algorithm in the MCU(STM32) to get the sensor data from several sensors and optimzie the data, using PID controller to control the general power of the robot, Accomplished the function to charge the capacity and release the energy in the capacity intelligently, improved the performance of our robots.

MISCELLANEOUS

- **Skills:** c/c++,Python,matlab,c++qt,ui开发qt,ros算法仿真,linux c++,arm-linux,opencv,machine vision, object detection
- **Languages:** CET-6, CET-4, TOEFL
- **Interests:** Indoor SLAM, Robotics, Machine Vision, Geometric Segmentation