# NavSafe A Safer Way To Get Around

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#### NavSafe Objective

NavSafe seeks to meet the following objective:

▶ Determine the safest route for a person to travel on based on data of collisions in the Seattle area.

#### Scope

Features required to accomplish this project:

- Searching algorithm
- Custom edge-weighted graph (bidirectional)
  - Vertices = Intersection
  - Edges = Path between pair of intersections
  - Weight of an edge/vertex based on cumulative severity indices
- Shortest path algorithm (i.e., Dijkstra) to find safest route

#### Motivation

- Vehicle collisions
  - Potential risk of injury or death
- Many high-risk intersections with flawed designs
  - ▶ Factor out of the travelers control
  - Mistakes by pedestrian or driver has a higher chance of being fatal in these intersections
- Areas where flawed design could occur:
  - Road width
  - Speed limit
  - Markings and signs
  - Intersection infrastructure such as dividers and shoulders

## Dataset(s) Used

- "Collisions" from Seattle GIS Open Data
  - Number of Collisions
  - Weather, road, and daylight conditions
  - Type of collision (pedestrian/vehicle)
  - Collision details (left/right turn, etc.)
  - Severity of collision
- Intersections dataset from the City of Seattle's data site
- Streets dataset from the City of Seattle's data site

#### Requirements Specification

- Functional Requirements
  - Read Module
  - Collision ADT Module
  - Intersection ADT Module
  - Graphing Module
  - Sort Module
  - Searching Module
- Non-Functional Requirements
  - Reliability
  - Accuracy of Results
  - Performance
  - Constraints

## Design Specification

- Read Module: Read CSV files and create ADTs to be used
- Graphing Module Stage 1: Create custom edge-weighted graph
- ► Search Module: Search for collisions that occurred on an edge and factor them into the weighing of the edge
- Graphing Module Stage 2: Using edge-weighted graph, find shortest path from starting intersection to destination intersection.
- ► Sorting Module Sort by severity index, fatalities, serious and non-serious injuries mergesort, output top 3 intersections that should be avoided

#### Verification and Validation

#### **Quality Control Procedures**

- Unit Testing
  - Verify that individual units of code work as intended
- System Testing
  - Verify the program and specifications are aligned

# Screenshot of implementation

