

LEARNING MAY WORK...

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LOGISTICS

Registration update

Lecture videos on Canvas

- Media gallery
- Please keep coming to class!

Self-assessment online [here](#)

- Due Friday January 18, 2019 (11:59PM EST) (Friday January 25, 2019 for DL)

Lecture slides and notes

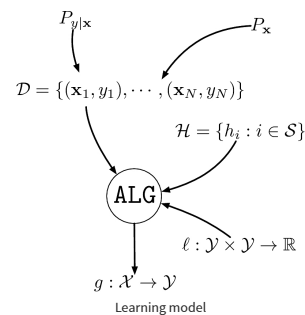
- I will make every effort to post ahead of time



<http://www.phdcomics.com>

RECAP: COMPONENTS OF SUPERVISED MACHINE LEARNING

- A **dataset** $\mathcal{D} \triangleq \{(\mathbf{x}_1, y_1), \dots, (\mathbf{x}_N, y_N)\}$
 - $\{\mathbf{x}_i\}_{i=1}^N$ drawn i.i.d. from an unknown probability distribution $P_{\mathbf{x}}$ on \mathcal{X}
 - $\{y_i\}_{i=1}^N$ are the corresponding targets $y_i \in \mathcal{Y} \triangleq \mathbb{R}$
- An **unknown conditional distribution** $P_{y|\mathbf{x}}$
 - $P_{y|\mathbf{x}}$ models $f : \mathcal{X} \rightarrow \mathcal{Y}$ with noise
- A **set of hypotheses** \mathcal{H} as to what the function could be
- A **loss function** $\ell : \mathcal{Y} \times \mathcal{Y} \rightarrow \mathbb{R}^+$ capturing the “cost” of prediction
- An **algorithm** ALG to find the best $h \in \mathcal{H}$ that explains f



RECAP: THE SUPERVISED LEARNING PROBLEM

Learning is not **memorizing**

- Our goal is **not** to find $h \in \mathcal{H}$ that accurately assigns values to elements of \mathcal{D}
- Our goal is to find the **best** $h \in \mathcal{H}$ that accurately **predicts** values of **unseen** samples

Consider hypothesis $h \in \mathcal{H}$. We can easily compute the **empirical risk** (a.k.a. **in-sample** error)

$$\hat{R}_N(h) \triangleq \frac{1}{N} \sum_{i=1}^N \ell(y_i, h(\mathbf{x}_i))$$

What we really care about is the **true risk** (a.k.a. **out-sample** error)

$$R(h) \triangleq \mathbb{E}_{\mathbf{x}y}(\ell(y, h(\mathbf{x})))$$

Question #1: Can **generalize**?

- For a given h , is $\hat{R}_N(h)$ close to $R(h)$?

Question #2: Can we learn **well**?

- Given \mathcal{H} , the **best** hypothesis is $h^\# \triangleq \operatorname{argmin}_{h \in \mathcal{H}} R(h)$
- Our algorithm can only find $h^* \triangleq \operatorname{argmin}_{h \in \mathcal{H}} \hat{R}_N(h)$
- Is $\hat{R}_N(h^*)$ close to $R(h^\#)$?
- Is $R(h^\#) \approx 0$?

WHY THE QUESTIONS MATTERS

Quick demo: nearest neighbor classification

A SIMPLER LEARNING PROBLEM

Consider a special case of the general supervised learning problem

- Dataset $\mathcal{D} \triangleq \{(\mathbf{x}_1, y_1), \dots, (\mathbf{x}_N, y_N)\}$
 - $\{\mathbf{x}_i\}_{i=1}^N$ drawn i.i.d. from unknown $P_{\mathbf{x}}$ on \mathcal{X}
 - $\{y_i\}_{i=1}^N$ labels with $\mathcal{Y} = \{0, 1\}$ (binary classification)
- Unknown $f : \mathcal{X} \rightarrow \mathcal{Y}$, no noise.
- Finite set of hypotheses \mathcal{H} , $|\mathcal{H}| = M < \infty$
 - $\mathcal{H} \triangleq \{h_i\}_{i=1}^M$
- Binary loss function $\ell : \mathcal{Y} \times \mathcal{Y} \rightarrow \mathbb{R}^+ : (y_1, y_2) \mapsto \mathbf{1}\{y_1 \neq y_2\}$

In this very specific case, the true risk simplifies

$$R(h) \triangleq \mathbb{E}_{\mathbf{x}y}(\mathbf{1}\{h(\mathbf{x}) \neq y\}) = \mathbb{P}_{\mathbf{x}y}(h(\mathbf{x}) \neq y)$$

The empirical risk becomes

$$\hat{R}_N(h) = \frac{1}{N} \sum_{i=1}^N \mathbf{1}\{h(\mathbf{x}_i) \neq y_i\}$$

CAN WE LEARN?

Our objective is to find a hypothesis h^* that ensures a small risk

$$h^* = \operatorname{argmin}_{h \in \mathcal{H}} \hat{R}_N(h)$$

For a **fixed** $h_j \in \mathcal{H}$, how does $\hat{R}_N(h_j)$ compares to $R(h_j)$?

Observe that for $h_j \in \mathcal{H}$

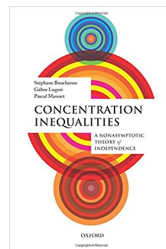
- The empirical risk is a sum of iid random variables

$$\hat{R}_N(h_j) = \frac{1}{N} \sum_{i=1}^N \mathbf{1}\{h_j(\mathbf{x}_i) \neq y_i\}$$

- $\mathbb{E}(\hat{R}_N(h_j)) = R(h_j)$

$\mathbb{P}\left(|\hat{R}_N(h_j) - R(h_j)| > \epsilon\right)$ is a statement about the deviation of a normalized sum of iid random variables from its mean

We're in luck! Such bounds, a.k.a, known as **concentration inequalities**, are a well studied subject



CONCENTRATION INEQUALITIES 101

Lemma (Markov's inequality)

Let X be a **non-negative** real-valued random variable. Then for all $t > 0$

$$\mathbb{P}(X \geq t) \leq \frac{\mathbb{E}(X)}{t}.$$

Lemma (Chebyshev's inequality)

Let X be a real-valued random variable. Then for all $t > 0$

$$\mathbb{P}(|X - \mathbb{E}(X)| \geq t) \leq \frac{\operatorname{Var}(X)}{t^2}.$$

Proposition (Weak law of large numbers)

Let $\{X_i\}_{i=1}^N$ be i.i.d. real-valued random variables with finite mean μ and finite variance σ^2 . Then

$$\mathbb{P}\left(\left|\frac{1}{N} \sum_{i=1}^N X_i - \mu\right| \geq \epsilon\right) \leq \frac{\sigma^2}{N\epsilon^2} \quad \lim_{N \rightarrow \infty} \mathbb{P}\left(\left|\frac{1}{N} \sum_{i=1}^N X_i - \mu\right| \geq \epsilon\right) = 0.$$

BACK TO LEARNING

By the law of large number, we know that

$$\forall \epsilon > 0 \quad \mathbb{P}_{\{(\mathbf{x}_i, y_i)\}} \left(\left| \widehat{R}_N(h_j) - R(h_j) \right| \geq \epsilon \right) \leq \frac{\text{Var}(\mathbf{1}\{h_j(\mathbf{x}_1) \neq y\})}{N\epsilon^2} \leq \frac{1}{N\epsilon^2}$$

Given enough data, we can *generalize*

How much data? $N = \frac{1}{\delta\epsilon^2}$ to ensure $\mathbb{P} \left(\left| \widehat{R}_N(h_j) - R(h_j) \right| \geq \epsilon \right) \leq \delta$.

That's not quite enough! We care about $\widehat{R}_N(h^*)$ where $h^* = \underset{h \in \mathcal{H}}{\text{argmin}} \widehat{R}_N(h)$

- If $M = |\mathcal{H}|$ is large we should expect the existence of $h_k \in \mathcal{H}$ such that $\widehat{R}_N(h_k) \ll R(h_k)$

$$\begin{aligned} & \mathbb{P} \left(\left| \widehat{R}_N(h^*) - R(h^*) \right| \geq \epsilon \right) \leq ? \\ & \mathbb{P} \left(\left| \widehat{R}_N(h^*) - R(h^*) \right| \geq \epsilon \right) \leq \mathbb{P} \left(\exists j : \left| \widehat{R}_N(h^*) - R(h^*) \right| \geq \epsilon \right) \\ & \mathbb{P} \left(\left| \widehat{R}_N(h^*) - R(h^*) \right| \geq \epsilon \right) \leq \frac{M}{N\epsilon^2} \end{aligned}$$

We need $N \geq \frac{M}{\delta\epsilon^2}$ to ensure $\mathbb{P} \left(\left| \widehat{R}_N(h^*) - R(h^*) \right| \geq \epsilon \right) \leq \delta$.

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CONCENTRATION INEQUALITIES 102

We can obtain *much* better bounds than with Chebyshev

Lemma (Hoeffding's inequality)

Let $\{X_i\}_{i=1}^N$ be i.i.d. real-valued zero-mean random variables such that $X_i \in [a_i, b_i]$. Then for all $\epsilon > 0$

$$\mathbb{P} \left(\left| \frac{1}{N} \sum_{i=1}^N X_i \right| \geq \epsilon \right) \leq 2 \exp \left(- \frac{2N^2\epsilon^2}{\sum_{i=1}^N (b_i - a_i)^2} \right).$$

In our learning problem

$$\begin{aligned} \forall \epsilon > 0 \quad & \mathbb{P} \left(\left| \widehat{R}_N(h_j) - R(h_j) \right| \geq \epsilon \right) \leq 2 \exp(-2N\epsilon^2) \\ \forall \epsilon > 0 \quad & \mathbb{P} \left(\left| \widehat{R}_N(h^*) - R(h^*) \right| \geq \epsilon \right) \leq 2M \exp(-2N\epsilon^2) \end{aligned}$$

We need $N \geq \frac{1}{2\epsilon^2} (\log M + \log \frac{2}{\delta})$

M can be quite large (almost exponential in N) and, with enough data, we can generalize h^* .

How about learning $h^\# \triangleq \underset{h \in \mathcal{H}}{\text{argmin}} R(h)$?

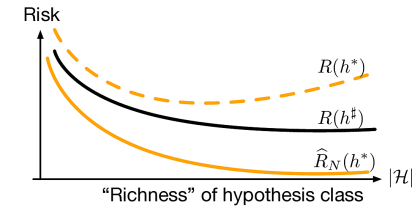
LEARNING CAN WORK!

Lemma.

If $\forall j \in \mathcal{H} \left| \widehat{R}_N(h_j) - R(h_j) \right| \leq \epsilon$ then $\left| R(h^*) - R(h^\#) \right| \leq 2\epsilon$.

How do we make $R(h^\#)$ small?

- Need bigger hypothesis class \mathcal{H} ! (could we take $M \rightarrow \infty$?)
- Fundamental trade-off of learning



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WHAT IS A GOOD HYPOTHESIS?

Ideally we want $|\mathcal{H}|$ small so that $R(h^*) \approx R(h^\sharp)$ and get lucky s that $R(h^*) \approx 0$

In general this is *not* possible

- Remember, we usually have to learn $P_{y|x}$, not a function f

Next time

- What is the optimal binary classification hypothesis class?
- How small can $R(h^*)$ be?