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%{
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MATH 467 - Fall 2015
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Revision History
                                    Programmer
Date
                 Changes
11/15/2015
                  Original
                                     Jacob Leonard
       ~Seeking Counsel from Professor Wang~
               Reverted Function
12/4/2015
                                           Jacob Leonard
12/4-12/2015
                Troubleshooting
                                           Jacob Leonard
12/13/2015
              Fixing Step Size
                                           Jacob Leonard
             Analyzing Step Size Values Jacob Leonard
12/15/2015
12/16/2015
                  Completed
                                           Jacob Leonard
%}
%}
%this script is for the fixed step size gradient method
%formula but for x and y given the quadratic function
%define the values of x and y from -2 to 2, increasing by 1/25, for 101
%values
for j = 1:101
    x(j) = (-2+(4*(j-1))/100);
    y(j) = (-2+(4*(j-1))/100);
end
%define an anonymous function handle for the equations that compose the gradient and them{arkappa}
f = @(x,y) ((x^4+y^4-6*x^2*y^2-1)^2+(4*x^3*y-4*x*y^3)^2);
G = \{(x,y) (8*x*(x^6+3*x^4*y^2+x^2*(3*y^4-1)+y^2*(y^4+3))), (x,y) (8*y*(x^6+3*x^4*y^2+3*x^2*u^4+3))\}
(y^4+1)+y^2*(y^4-1));
Gradient = [g{1}(x,y),g{2}(x,y)];
H = \{@(x,y) (8*(7*x^6+15*x^4*y^2+x^2*(9*y^4-3)+y^2*(y^4+3))), @(x,y) (48*x*y*\checkmark
(x^4+2*x^2*y^2+y^4+1)); @(x,y) (48*x*y*(x^4+2*x^2*y^2+y^4+1)), @(x,y) (8*(x^6+9*x^4*y^2+3*x^2*y^2+y^4+1))
(5*y^4+1)+y^2*(7*y^4-3));
%Hessian = [H{1}(x,y),H{2}(x,y);H{3}(x,y),H{4}(x,y)];
%tolerance is the desired level of accuracy
tolerance = 10^{-7}:
%this matrix shows the number of iterations for matlab to think the value
%is zero, or within the desired tolerance
FixedStep = zeros(101,101);
%this is the value of the function at the point the algorithm terminated
FixedStepValues = zeros(101,101);
for i = 1:101
    for j = 1:101
        Z(:,:,1) = [x(i);y(j)];
        %set the values in Z equal to 0 to track the progress
        Z(1,1,2:5000)=0;
        Z(2,1,2:5000)=0;
        g(:,:,1) = [G\{1\}(x(i),y(j)),G\{2\}(x(i),y(j))];
        %if the graident is equal to zero with the first iteration, then
        %the minimum is reached
        if (g(1,1,1) == 0) \&\& (g(1,2,1) == 0)
            FixedStep(i,j) = 0;
            FixedStepValues(i,j) = f(Z(1,1,1),Z(2,1,1)); \checkmark
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continue
        end
        qT(:,:,1) = transpose(q(:,:,1));
        %define alpha
        alpha = .0005;
        %begin the iterations for steps
        for k = 2:5000
            Z(:,:,k) = Z(:,:,k-1)-alpha*(gT(:,:,k-1));
            %to speed up the code, if the Z values go to NaN or Inf, the
            %loop breaks to the next point, and sets the step number to the
            %maximum, and sets the value to 1
            if (isnan(Z(1,1,k)) == 1) || (isnan(Z(2,1,k)) == 1)
                FixedStep(i,j) = 5000;
                FixedStepValues(i,j) = 1; ✓
                break
            end
            if (isinf(Z(1,1,k)) == 1) \mid | (isinf(Z(2,1,k)) == 1)
                FixedStep(i,j) = 5000;
                FixedStepValues(i,j) = 1; \checkmark
                break
            end
            %find the new graident for the updated value
            g(:,:,k) = [G\{1\}(Z(1,1,k),Z(2,1,k)),G\{2\}(Z(1,1,k),Z(2,1,k))];
            %if the gradient equals zero then the optimal value is
            %considered to have been reached
            if (g(1,1,k)) == 0 && (g(1,2,k) == 0)
                FixedStep(i,j) = k-1;
                FixedStepValues(i,j) = f(Z(1,1,k),Z(2,1,k)); \checkmark
                break
            end
            gT(:,:,k) = transpose(g(:,:,k));
            %if the function value dips below the tolerance, then it is
            %considered to have converged to the optimal value
            if f(Z(1,1,k),Z(2,1,k)) < tolerance;
                FixedStep(i,j) = k-1;
                FixedStepValues(i,j) = 0;
                break
            %if the algorithm reaches the end of the allowed number of
            %iterations, then the number of steps is recorded and the
            %value is sent to 1, and considered to have not converged
            if k == 5000
                FixedStep(i,j) = 5000;
                FixedStepValues(i,j) = 1;
            end
        end
    end
end
xAxis = linspace(-2,2,101);
yAxis = linspace(-2,2,101);
%this plot will look at the number of steps it took for the algorithm to finish, the real≰
values of the function over the interval
%for which the algorithm finished, and the imaginary values for which the
%algorithm finished
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subplot(2,2,1:2)
%this plot will show the number of iterations it took
contourf(xAxis,yAxis,FixedStep);
xlabel('x');
ylabel('y');
title('Fixed Step Size Method # of Steps ,Alpha=.0005, Max=5000');
colorbar;
subplot(2,2,3:4)
FixedStepValuesReal = real(FixedStepValues);
contourf(xAxis,yAxis,FixedStepValuesReal);
xlabel('x');
ylabel('y');
title('Binary Convergence Plot x=[-2:2], y=[-2:2],Alhpa=.0005');
colorbar;
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