Homework 1

A spaucialt is modeled as a rigid body B+ dampn D+ 3 whiles Wi, Wz, Wz

tach whose is a feat disk with mass $m_{w_1} = m_{w_2} = m_{w_3} = 5 \text{ kg}$ and radius R = 1 m

The has rest point at P and mass $m_0 = 10 \text{ kg}$ and coefficients $K_d = 5.5 \frac{K_0}{S_{eff}^2}$ $G_a = 30 \frac{K_0}{S_{eff}}$

B has metria matrix $J_{BP}^{(B)} = \begin{bmatrix} J_1 & 0 & 0 \\ 0 & \overline{J_2} & 0 \\ 0 & 0 & \overline{J_3} \end{bmatrix}$ and mass $M_B = 100 \text{ kg}$

axes of W_1 and W_3 in the (\hat{b}_1, \hat{b}_3) -plane distance of W_1, W_2, W_3 from P is $b_W = 2m$

 $J_1 = 350 \text{ kgm}^2$ $J_2 = 300 \text{ kg m}^2$ $J_3 = 600 \text{ kg m}^2$

The 3 wheels are either

- (a) notating with courtant augulor relocity wsi (i.e. the initial)
- (6) subject to viscous damping, with Kw=0.1 kgm² sec
- 2 cases are considered, with propagation time of 30 minutes
 - (1) w, and W3 set to (a), W2 set to (b)
 - (2) W1, W2, W3 set to (b)

Initial conditions for (1) and (2) are

$$\underline{\omega}^{\mathsf{T}}(o) = \begin{bmatrix} 36 & 3 & 3 \end{bmatrix}^{\mathsf{T}} \frac{\mathsf{deg}}{\mathsf{sec}} \qquad \omega_{\mathsf{S1}}(o) = \omega_{\mathsf{S9}}(o) = 720 \frac{\mathsf{deg}}{\mathsf{sec}} \; ; \; \omega_{\mathsf{S2}}(o) = 60 \frac{\mathsf{deg}}{\mathsf{sec}}$$

$$\xi(o) = 0 \qquad \xi(o) = 0 \qquad \nabla_{\underline{\mathsf{F}}}^{\mathsf{T}}(o) = \begin{bmatrix} 0 & 0 & 0 \end{bmatrix}^{\mathsf{T}}$$

Portray the time histories (mi [0, 30]min) of

(i) components of w(t) (ii) wsi(t), i=1,2,3 (iii) Flt) and \$(t) (iv) Mechanical for coses (1) and (2) and comment on them