

Homework 2

Consider a spacecraft composed of a main cylindrical body B_1 and 4 appendages

Body B_1 , with radius R and length L

$$m_{B1} = 2000 \text{ Kg}$$

$$R = 1 \text{ m}$$

$$L = 4 \text{ m}$$

Bodies B_2 and B_3 , with radius r_A and length l_A

Bodies B_4 and B_5 , with radius r_B and length l_B

$$m_{B2} = m_{B3} = m_{B4} = m_{B5} = 100 \text{ Kg}$$

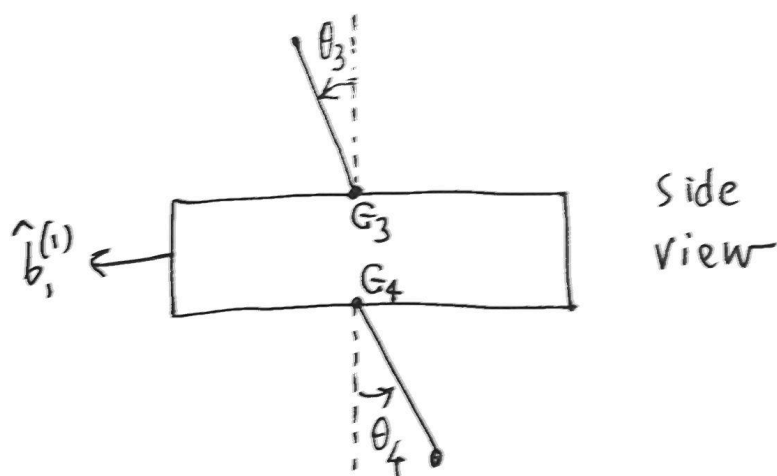
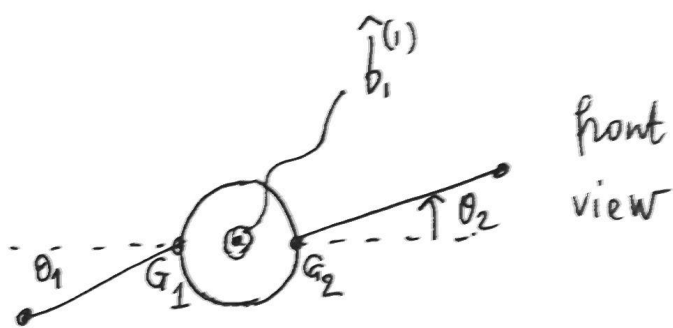
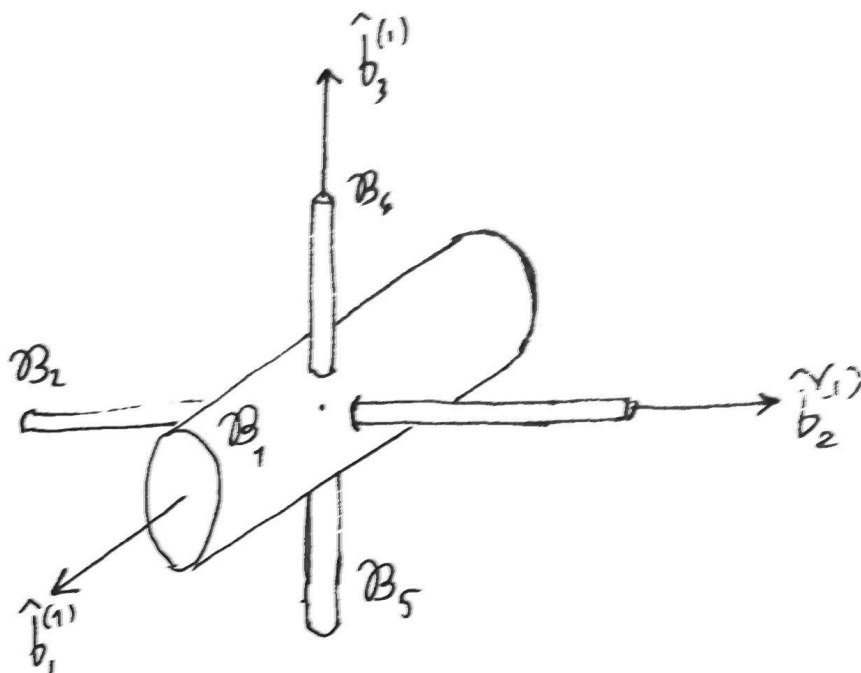
$$r_A = r_B = 0.05 \text{ m}$$

G_1, \dots, G_4 are revolute joints (1 degree of freedom).

Each of them is associated with an elastic torque and a friction torque about the respective rotation axis, with coefficients

$$K_1 = 100 \text{ Nm} \text{ for the elastic torque (proportional to } \theta_i)$$

$$K_2 = 50 \text{ Nm sec} \text{ for the friction torque (proportional to } \dot{\theta}_i)$$



The spacecraft travels a circular orbit of radius $R_0 = 7000 \text{ km}$ and the inertial frame coincides with \underline{B}_1 at t_0 (initial time).

Thus the position and velocity of the center of mass of B_1 at t_0 are

$$\underline{v}_{p1}(t_0) = \begin{bmatrix} 0 & \sqrt{\frac{\mu}{R_0}} & 0 \end{bmatrix} \underline{N}^T \quad \text{where } \underline{N} = \underline{B}_1(t_0)$$

$$\underline{r}_{p1}(t_0) = \begin{bmatrix} R_0 & 0 & 0 \end{bmatrix} \underline{N}^T$$

The remaining initial conditions are

$$\underline{\omega}_1(t_0) = \begin{bmatrix} 1 & 0.1 & 0.1 \end{bmatrix} \text{sec}^{-1} \underline{B}_1^T$$

$$\theta_1(t_0) = -30 \text{ deg} \quad \theta_2(t_0) = 30 \text{ deg} \quad \theta_3(t_0) = -30 \text{ deg} \quad \theta_4(t_0) = 10 \text{ deg}$$

$$\sigma_1(t_0) = -0.2 \text{sec}^{-1} \quad \sigma_2(t_0) = 0.2 \text{sec}^{-1} \quad \sigma_3(t_0) = 0.1 \text{sec}^{-1} \quad \sigma_4(t_0) = -0.3 \text{sec}^{-1}$$

Consider two cases

$$(A) \quad l_A = 2 \text{ m} \quad l_B = 9 \text{ m} \quad , \quad \text{propagation time } [0, 1800] \text{ sec}$$

$$(B) \quad l_A = 2 \text{ m} \quad l_B = 3 \text{ m} \quad , \quad \text{propagation time } [0, 7200] \text{ sec}$$

Portray the time histories of

$$(i) \quad \underline{\omega}_1(t) \quad , \quad \underline{v}_{p1}(t)$$

$$(ii) \quad \sigma_i(t) \quad (i=1, \dots, 4)$$

$$(iii) \quad \theta_i(t) \quad (i=1, \dots, 4)$$

Comment on the asymptotic rotational state of the spacecraft