

## • Homework 6

The Soyuz capsule orbits the Earth at an altitude of 400 km (in circular, equatorial orbit). Its main data are

$$m = 2400 \text{ Kg} \quad S = 3.8 \text{ m}^2 \text{ (aerodynamic surface)}$$

$$C_D = 1.341 \text{ (average value of } C_D \text{ along the entire flight)}$$

$$\tilde{L} = 0 \text{ (no lift)}$$

$$R_c = 2.235 \text{ m} \quad \left\{ \begin{array}{l} \text{radius of curvature at stagnation point} \\ \text{i.e. at the nose} \end{array} \right.$$

De-orbit follows a tangential braking  $\Delta v$ . Two cases are considered: (1)  $\Delta v = 0.2 \frac{\text{km}}{\text{sec}}$  (2)  $\Delta v = 0.4 \frac{\text{km}}{\text{sec}}$

For each of these two cases

- Find  $v_{I,ini}$  and  $\gamma_{I,ini}$  at  $h_{E1} = 100 \text{ km}$ , i.e. the inertial velocity magnitude and the related flight path angle at the entry interface
- Find  $v_{R,ini}$  and  $\gamma_{R,ini}$  associated with  $v_{I,ini}$  and  $\gamma_{I,ini}$  using the relation  $\underline{v_I} = \underline{v_R} + \underline{\omega_E} \times \underline{r_E}$ ; the two values  $v_{R,ini}$  and  $\gamma_{R,ini}$  coincide with  $v_{E1}$  and  $\gamma_{E1}$ , used as initial conditions for reentry.
- Propagate numerically the reentry trajectory up to touchdown (altitude = 0) using equation set (B1); portray the time histories of  $h(t)$ ,  $\gamma_R(t)$ ,  $v_R(t)$ , and the reentry trajectory.

- (d) Plot the time histories of the quaternions associated with  $R_{C \leftarrow N}$ , where the inertial frame  $N$  is ECI and the (commanded) body axes are  $BA$  (see notes)

Use the initial conditions  $\theta_{g0} = 60 \text{ deg}$  and  $\lambda_{g0} = 30 \text{ deg}$  and zero control angles (at all times).

Comment and explain the symmetries in the time histories of the quaternions

- (e) Report the value of the time of flight and the values of  $a_d^{(max)}$ ,  $q_s^{(max)}$ ,  $p_d^{(max)}$  and the times at which they occur.

For  $a_d$ , use  $a_d = -\ddot{v}_I = -\frac{d}{dt} \sqrt{\dot{v}_R^2 + \omega_E^2 r^2 + 2\omega_E r \dot{v}_R \cos \gamma_R}$

- (f) Portray  $\gamma_R(h)$ ,  $\dot{v}_R(h)$ ,  $q_s(h)$ ,  $a_d(h)$ ,  $p_d(h)$

for the numerically integrated trajectory found at previous points and (in the same figures) the respective plots obtained with the use of the Allen-Eggers analytical solution.

For the evaluation of  $q_s$ , use the following constant:-

$$\frac{K}{v_0^3 \sqrt{\rho_0}} = 1.762 \cdot 10^{-4} \text{ Kg}^{1/2} \text{ m}^{-1}$$