

Linear Algebra 04

时间: 2022年4月28日

1. Find the general solution of the system

$$\begin{aligned}x_1 - 2x_2 - x_3 + 3x_4 &= 0 \\ -2x_1 + 4x_2 + 5x_3 - 5x_4 &= 3 \\ 3x_1 - 6x_2 - 6x_3 + 8x_4 &= 2\end{aligned}$$

[解答]

Row reduce the system's augmented matrix:

$$\begin{bmatrix} 1 & -2 & -1 & 3 & 0 \\ -2 & 4 & 5 & -5 & 3 \\ 3 & -6 & -6 & 8 & 2 \end{bmatrix} \sim \sim \begin{bmatrix} 1 & -2 & -1 & 3 & 0 \\ 0 & 0 & 3 & 1 & 3 \\ 0 & 0 & -3 & -1 & 2 \end{bmatrix} \sim \begin{bmatrix} 1 & -2 & -1 & 3 & 0 \\ 0 & 0 & 3 & 1 & 3 \\ 0 & 0 & 0 & 0 & 5 \end{bmatrix}$$

This echelon matrix shows that the system is inconsistent, because its rightmost column is a pivot column; the third row corresponds to the equation $0 = 5$. There is no need to perform any more row operations. Note that the presence of the free variables in this problem is irrelevant because the system is inconsistent.

1. 求解线性方程组的通解.

① 写出系数矩阵对应的增广矩阵.

② 化简增广矩阵. 根据是否有解考虑是否化简到简化阶梯形矩阵.

$$\begin{bmatrix} 1 & -2 & -1 & 3 & 0 \\ -2 & 4 & 5 & -5 & 3 \\ 3 & -6 & -6 & 8 & 2 \end{bmatrix} \rightsquigarrow \begin{bmatrix} 1 & -2 & -1 & 3 & 0 \\ 0 & 0 & 3 & 1 & 3 \\ 0 & 0 & -3 & -1 & 2 \end{bmatrix} \rightsquigarrow \begin{bmatrix} ① & -2 & -1 & 3 & 0 \\ 0 & 0 & ③ & 1 & 3 \\ 0 & 0 & 0 & 0 & 5 \end{bmatrix}$$

主元个数为2且出现 $0=b(b \neq 0)$ 的情况, 显然不相容.

→ 复习教材第17页定理2和20页的应用行化简算法求解线性方程组

2. a. If a matrix **A** is diagonalizable, then the columns of **A** are linearly dependent. (T/F?)

如果一个矩阵A是可对角化的, 则A的列线性相关. (False)

2. a. A可对角化, A的各列线性无关 (反例如下). false.

5.3节定理①可逆, 但不可对角化. 5.3节习题31.

② 可对角化但不可逆 5.3节习题32.

b. Two eigenvectors corresponding to the distinct eigenvalues are always linearly independent. (T/F?)

对应于不同特征值的两个特征向量总是线性无关的. (True)

2.b. 对应于两个不同的特征值的特征向量总是线性无关的 (True)

证明: 设矩阵 A ($n \times n$) 特征值为 λ_1, λ_2 ($\lambda_1 \neq \lambda_2$) 对应的特征向量为 \vec{x}_1, \vec{x}_2 .

由特征向量的定义 (教材 5.1 节定义 P267).

$$A\vec{x}_1 = \lambda_1\vec{x}_1, \quad A\vec{x}_2 = \lambda_2\vec{x}_2$$

于是发现到这一步, 不好证明下去, (正难则反). 我们采用反证法.

我们假设对应于不同特征值的特征向量线性相关.

故存在不全为零的实数 k_1, k_2 , s.t.: $k_1\vec{x}_1 + k_2\vec{x}_2 = 0$, 故同时乘以 A , 得

$$A k_1\vec{x}_1 + A k_2\vec{x}_2 = \lambda_1 k_1\vec{x}_1 + \lambda_2 k_2\vec{x}_2 = 0, \text{ 又 } k_1\vec{x}_1 = -k_2\vec{x}_2$$

$$\text{代入 } k_1\lambda_1\vec{x}_1 + k_2\lambda_2\vec{x}_2 = 0 \text{ 可得 } -\lambda_1 k_2\vec{x}_2 + \lambda_2 k_2\vec{x}_2 = 0$$

$$\text{即 } k_2(\lambda_2 - \lambda_1) = 0. \text{ 又 } \lambda_1 \neq \lambda_2, \forall k_2, \vec{x}_2 \text{ 不为零, 故矛盾!}$$

故对应于不同特征值的特征向量线性无关.

c. A 3x3 matrix A with 3 linearly dependent eigenvectors is invertible. (T/F?)

一个有3个线性相关特征向量的3x3的矩阵A是可逆的. (False)

2.c. 3个线性相关的特征向量对应的 3x3 的矩阵A是不可对角化的.

由 2.a, 与矩阵是否可逆无关.

总结: 矩阵是否可以对角化, 特征值和特征向量的情况如何与矩阵的秩没有直接关系!

3. 如果题2(b)是错误的, 请修改为正确的并证明题2(b); 如果题2(b)是正确的, 请证明之.

[解答]

[如何理解不同特征值对应的特征向量线性无关? - 知乎 \(zhihu.com\)](https://www.zhihu.com/question/26826444)

问题: 为什么不同特征值对应的特征向量线性无关?

解答: 首先我们对于矩阵 A 的特征值 λ_1 , 有等式满足 $Ax_1 = \lambda_1 x_1$, 特征向量为 x_1 .

对于特征值 λ_2 , 有等式满足 $Ax_2 = \lambda_2 x_2$.

下面用反证法进行证明! 首先假设不同特征值对应的特征向量线性相关

如果对于不同的 λ_1, λ_2 所对应的特征向量线性相关的话, 那么满足下面等式:

$k_1 x_1 + k_2 x_2 = 0$, 那么等式两边同时乘以矩阵 A , 得到 $A k_1 x_1 + A k_2 x_2 = 0$, 化简为:

$\lambda_1 k_1 x_1 + \lambda_2 k_2 x_2 = 0$, 又因为根据等式 $k_1 x_1 + k_2 x_2 = 0$ 可以得到,

$k_2 x_2 = -k_1 x_1$, 带入到 $\lambda_1 k_1 x_1 + \lambda_2 k_2 x_2 = 0$, 得到 $k_1 x_1 (\lambda_1 - \lambda_2) = 0$, 又因为 λ_1, λ_2 不相同, 则造成矛盾.

所以不同特征值对应的特征向量线性相关是错误的.

所以: 不同特征值对应的特征向量是线性无关的

4. 已知

$$A = \begin{bmatrix} 1 & 3 & 3 \\ -3 & -5 & -3 \\ 3 & 3 & 1 \end{bmatrix}$$

求可逆矩阵 P 和对角矩阵 D , 使 $A = PDP^{-1}$

[解答]

4. ① 求解特征值

$$\det(A - \lambda I) = 0 \Rightarrow \begin{vmatrix} 1-\lambda & 3 & 3 \\ -3 & 5-\lambda & -3 \\ 3 & 3 & 1-\lambda \end{vmatrix} = (A - \lambda I)$$

$$\det(A - \lambda I) = \begin{vmatrix} 1-\lambda & 3 & 3 \\ 0 & -2-\lambda & -2-\lambda \\ 3 & 3 & 1-\lambda \end{vmatrix} = \begin{vmatrix} -2-\lambda & 0 & \lambda+2 \\ 0 & 1 & 1 \\ 3 & 3 & 1-\lambda \end{vmatrix} \cdot (2+\lambda)$$

$$= -(2+\lambda)(2+\lambda) \begin{vmatrix} -1 & 0 & 1 \\ 0 & 1 & 1 \\ 3 & 3 & 1-\lambda \end{vmatrix}$$

$$= -(2+\lambda)^2 \begin{vmatrix} -1 & -1 & 0 \\ 0 & 1 & 1 \\ 3 & 3 & 1-\lambda \end{vmatrix} = (2+\lambda)^2 \begin{vmatrix} 1 & 1 & 0 \\ 0 & 1 & 1 \\ 3 & 3 & 1-\lambda \end{vmatrix}$$

$$= (2+\lambda)^2 \begin{vmatrix} 1 & 1 & 0 \\ 0 & 1 & 1 \\ 0 & 0 & 1-\lambda \end{vmatrix} = -(2+\lambda)^2 (1-\lambda)$$

特征值 $\lambda_1 = 1, \lambda_2 = -2, \lambda_3 = -2$. -2 为重根.

② 求解特征向量, $\lambda_1 = 1$ 时, $A - I = \begin{bmatrix} 0 & 3 & 3 \\ -3 & 4 & -3 \\ 3 & 3 & 0 \end{bmatrix} \sim \begin{bmatrix} 0 & 1 & 1 \\ 1 & 2 & 1 \\ 1 & 1 & 0 \end{bmatrix}$

$$\sim \begin{bmatrix} 1 & 1 & 0 \\ 1 & 2 & 1 \\ 0 & 1 & 1 \end{bmatrix} \sim \begin{bmatrix} 1 & 1 & 0 \\ 0 & 1 & 1 \\ 0 & 1 & 1 \end{bmatrix} \sim \begin{bmatrix} 1 & 1 & 0 \\ 0 & 1 & 1 \\ 0 & 0 & 0 \end{bmatrix} \Rightarrow \begin{cases} x_1 + x_2 = 0 \\ x_2 + x_3 = 0 \end{cases} \text{ 取 } \vec{x} = \begin{bmatrix} -1 \\ 1 \\ 1 \end{bmatrix} \text{ 即可}$$

$$\lambda_2 = \lambda_3 = -2 \text{ 时, } [A + 2I] = \begin{bmatrix} 3 & 3 & 3 \\ -3 & -3 & -3 \\ 3 & 3 & 3 \end{bmatrix} \sim \begin{bmatrix} 1 & 1 & 1 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix} \Rightarrow \begin{cases} x_1 + x_2 + x_3 = 0 \\ x_1 = -x_2 - x_3 \end{cases}$$

$$\vec{x} = \begin{bmatrix} -x_2 - x_3 \\ x_2 \\ x_3 \end{bmatrix} = x_2 \begin{bmatrix} -1 \\ 1 \\ 0 \end{bmatrix} + x_3 \begin{bmatrix} -1 \\ 0 \\ 1 \end{bmatrix} \Rightarrow \begin{bmatrix} -1 \\ 1 \\ 0 \end{bmatrix}, \begin{bmatrix} -1 \\ 0 \\ 1 \end{bmatrix} \text{ 线性无关}$$

③ 构造矩阵 P 和 D .

④ 验证 $AP = PD$, 自行验证!

$$P = \begin{bmatrix} 1 & -1 & -1 \\ -1 & 1 & 0 \\ 1 & 0 & 1 \end{bmatrix} \quad D = \begin{bmatrix} 1 & 0 & 0 \\ 0 & -2 & 0 \\ 0 & 0 & -2 \end{bmatrix}$$

There are four steps to implement the description in Theorem 5.

Step 1. Find the eigenvalues of A . As mentioned in Section 5.2, the mechanics of this step are appropriate for a computer when the matrix is larger than 2×2 . To avoid unnecessary distractions, the text will usually supply information needed for this step. In the present case, the characteristic equation turns out to involve a cubic polynomial that can be factored:

$$\begin{aligned} 0 &= \det(A - \lambda I) = -\lambda^3 - 3\lambda^2 + 4 \\ &= -(\lambda - 1)(\lambda + 2)^2 \end{aligned}$$

The eigenvalues are $\lambda = 1$ and $\lambda = -2$.

Step 2. Find three linearly independent eigenvectors of A . Three vectors are needed because A is a 3×3 matrix. This is the critical step. If it fails, then Theorem 5 says that A cannot be diagonalized. The method in Section 5.1 produces a basis for each eigenspace:

$$\text{Basis for } \lambda = 1: \quad \mathbf{v}_1 = \begin{bmatrix} 1 \\ -1 \\ 1 \end{bmatrix}$$

Basis for $\lambda = -2$: $\mathbf{v}_2 = \begin{bmatrix} -1 \\ 1 \\ 0 \end{bmatrix}$ and $\mathbf{v}_3 = \begin{bmatrix} -1 \\ 0 \\ 1 \end{bmatrix}$

You can check that $\{\mathbf{v}_1, \mathbf{v}_2, \mathbf{v}_3\}$ is a linearly independent set.

Step 3. Construct P from the vectors in step 2. The order of the vectors is unimportant. Using the order chosen in step 2, form

$$P = [\mathbf{v}_1 \quad \mathbf{v}_2 \quad \mathbf{v}_3] = \begin{bmatrix} 1 & -1 & -1 \\ -1 & 1 & 0 \\ 1 & 0 & 1 \end{bmatrix}$$

Step 4. Construct D from the corresponding eigenvalues. In this step, it is essential that the order of the eigenvalues matches the order chosen for the columns of P . Use the eigenvalue $\lambda = -2$ twice, once for each of the eigenvectors corresponding to $\lambda = -2$:

$$D = \begin{bmatrix} 1 & 0 & 0 \\ 0 & -2 & 0 \\ 0 & 0 & -2 \end{bmatrix}$$

It is a good idea to check that P and D really work. To avoid computing P^{-1} , simply verify that $AP = PD$. This is equivalent to $A = PDP^{-1}$ when P is invertible. (However, be sure that P is invertible!) Compute

$$\begin{aligned} AP &= \begin{bmatrix} 1 & 3 & 3 \\ -3 & -5 & -3 \\ 3 & 3 & 1 \end{bmatrix} \begin{bmatrix} 1 & -1 & -1 \\ -1 & 1 & 0 \\ 1 & 0 & 1 \end{bmatrix} = \begin{bmatrix} 1 & 2 & 2 \\ -1 & -2 & 0 \\ 1 & 0 & -2 \end{bmatrix} \\ PD &= \begin{bmatrix} 1 & -1 & -1 \\ -1 & 1 & 0 \\ 1 & 0 & 1 \end{bmatrix} \begin{bmatrix} 1 & 0 & 0 \\ 0 & -2 & 0 \\ 0 & 0 & -2 \end{bmatrix} = \begin{bmatrix} 1 & 2 & 2 \\ -1 & -2 & 0 \\ 1 & 0 & -2 \end{bmatrix} \end{aligned}$$

5. (选做)请仔细阅读下面的证明过程:

$$T = \begin{bmatrix} 1 & a & a^2 \\ 1 & b & b^2 \\ 1 & c & c^2 \end{bmatrix}$$

Show that $\det T = (b-a)(c-a)(c-b)$.

[证明]

$$\begin{aligned} \det T &= \begin{vmatrix} 1 & a & a^2 \\ 1 & b & b^2 \\ 1 & c & c^2 \end{vmatrix} = \begin{vmatrix} 1 & a & a^2 \\ 0 & b-a & b^2-a^2 \\ 0 & c-a & c^2-a^2 \end{vmatrix} = \begin{vmatrix} 1 & a & a^2 \\ 0 & b-a & (b-a)(b+a) \\ 0 & c-a & (c-a)(c+a) \end{vmatrix} \\ &= (b-a)(c-a) \begin{vmatrix} 1 & a & a^2 \\ 0 & 1 & b+a \\ 0 & 1 & c+a \end{vmatrix} = (b-a)(c-a) \begin{vmatrix} 1 & a & a^2 \\ 0 & 1 & b+a \\ 0 & 0 & c-b \end{vmatrix} = (b-a)(c-a)(c-b) \end{aligned}$$

请仿照上述的证明思路及证明过程, 证明如下结论:

$$\mathbf{A} = \begin{bmatrix} 1 & a_1 & a_1^2 & \cdots & a_1^{n-1} \\ 1 & a_2 & a_2^2 & \cdots & a_2^{n-1} \\ \vdots & \vdots & \vdots & & \vdots \\ 1 & a_n & a_n^2 & \cdots & a_n^{n-1} \end{bmatrix}$$

Show that $\det A = \prod_{0 \leq i < j \leq n} (x_j - x_i)$.

[证明]

[范德蒙行列式 - 知乎 \(zhihu.com\)](#)

现在我们证明 $A = \begin{bmatrix} 1 & a_1 & \dots & a_1^{n-1} \\ \vdots & a_2 & \dots & a_2^{n-1} \\ \vdots & \vdots & \dots & \vdots \\ 1 & a_n & \dots & a_n^{n-1} \end{bmatrix} \Rightarrow \det A = |A| \neq 0$

证: 为了表达方便,
我们直接对 A 进行转置, 令 $B = A^T = \begin{bmatrix} 1 & 1 & 1 & \dots & 1 \\ a_1 & a_2 & \dots & a_n \\ a_1^2 & a_2^2 & \dots & a_n^2 \\ \vdots & \vdots & \dots & \vdots \\ a_1^{n-1} & a_2^{n-1} & \dots & a_n^{n-1} \end{bmatrix}$

拿第 3 行减去第 2 行的 a_1 倍, 后面同理

$$= \begin{bmatrix} a_1 - a_1 & a_2 - a_1 & a_3 - a_1 & \dots & a_n - a_1 \\ a_1^2 - a_1^2 & a_2^2 - a_1^2 & a_3^2 - a_1^2 & \dots & a_n^2 - a_1^2 \\ a_1^3 - a_1 \cdot a_1^2 & a_2^3 - a_1 \cdot a_1^2 & a_3^3 - a_1 \cdot a_1^2 & \dots & a_n^3 - a_1 \cdot a_1^2 \\ \vdots & \vdots & \vdots & \dots & \vdots \\ a_1^{n-1} - a_1 \cdot a_1^{n-2} & a_2^{n-1} - a_1 \cdot a_1^{n-2} & a_3^{n-1} - a_1 \cdot a_1^{n-2} & \dots & a_n^{n-1} - a_1 \cdot a_1^{n-2} \end{bmatrix} \rightarrow \begin{bmatrix} 1 & 1 & 1 & \dots & 1 \\ a_1 & a_2 & \dots & a_n \\ a_1^2 - a_1^2 & a_2^2 - a_1 \cdot a_2 & \dots & a_n^2 - a_1 \cdot a_n \\ \vdots & \vdots & \dots & \vdots \\ a_1^{n-1} - a_1^{n-1} & a_2^{n-1} - a_1 \cdot a_2^{n-2} & \dots & a_n^{n-1} - a_1 \cdot a_n^{n-2} \end{bmatrix}$$

$$\rightarrow \begin{bmatrix} 1 & (a_2 - a_1) \cdot 1 & \dots & (a_n - a_1) \cdot 1 \\ 0 & (a_2 - a_1) a_2 & \dots & (a_n - a_1) \cdot a_n \\ 0 & (a_2 - a_1) a_2^2 & \dots & (a_n - a_1) \cdot a_n^2 \\ \vdots & \vdots & \dots & \vdots \\ 0 & (a_2 - a_1) a_2^{n-2} & \dots & (a_n - a_1) a_n^{n-2} \end{bmatrix}$$

$$= (a_2 - a_1)(a_3 - a_1) \cdots (a_n - a_1) \begin{bmatrix} 1 & 1 & \cdots & 1 \\ 0 & a_2 & & a_n \\ 0 & a_2^2 & & a_n^2 \\ \vdots & \vdots & \ddots & \vdots \\ 0 & a_2^{n-2} & & a_n^{n-2} \end{bmatrix}$$

我们不妨继续考察 $A_2 = \begin{bmatrix} 1 & 1 & \cdots & 1 \\ a_2 & a_3 & & a_n \\ a_2^2 & a_3^2 & & a_n^2 \\ \vdots & \vdots & \ddots & \vdots \\ a_2^{n-2} & a_3^{n-2} & & a_n^{n-2} \end{bmatrix}$

采取同样的方式，后一行减去前一行的 a_2 倍

$$= \begin{bmatrix} 1 & 1 & \cdots & 1 \\ a_2 - a_2 & a_3 - a_2 & & a_n - a_2 \\ a_2^2 - a_2 \cdot a_2 & a_3^2 - a_2 \cdot a_3 & & a_n^2 - a_2 \cdot a_n \\ a_2^3 - a_2 \cdot a_2^2 & a_3^3 - a_2 \cdot a_3^2 & & a_n^3 - a_2 \cdot a_n^2 \\ \vdots & \vdots & \ddots & \vdots \\ a_2^{n-2} - a_2 \cdot a_2^{n-3} & a_3^{n-2} - a_2 \cdot a_3^{n-3} & & a_n^{n-2} - a_2 \cdot a_n^{n-3} \end{bmatrix}$$

$$= \begin{bmatrix} 1 & (a_3 - a_2) \cdot 1 & \cdots & (a_n - a_2) \cdot 1 \\ 0 & (a_3 - a_2) a_3 & & (a_n - a_2) a_n \\ 0 & (a_3 - a_2) a_3^2 & & (a_n - a_2) a_n^2 \\ \vdots & \vdots & \ddots & \vdots \\ 0 & (a_3 - a_2) a_3^{n-3} & & (a_n - a_2) a_n^{n-3} \end{bmatrix}$$

$$= (a_3 - a_2)(a_4 - a_2) \cdots (a_n - a_2) \begin{bmatrix} 1 & 1 & \cdots & 1 \\ 0 & a_3 & & a_n \\ 0 & a_3^2 & & a_n^2 \\ \vdots & \vdots & \ddots & \vdots \\ 0 & a_3^{n-3} & & a_n^{n-3} \end{bmatrix}$$

递归执行 $n-5$ 次后，我们得到

$$(a_2 - a_1)(a_3 - a_1) \cdots (a_n - a_1) \cdot (a_3 - a_2)(a_4 - a_2) \cdots (a_n - a_2) \cdot (a_4 - a_3)(a_5 - a_3) \cdots (a_n - a_3) \cdots (a_{n-1} - a_{n-2})(a_n - a_{n-2}) = \prod_{1 \leq i < j \leq n} (x_i - x_j)$$

$$A_{n-1} = \begin{bmatrix} 1 & 1 & 1 \\ a_{n-2} & a_{n-1} & a_n \\ a_{n-2}^2 & a_{n-1}^2 & a_n^2 \end{bmatrix} \rightarrow \begin{bmatrix} 1 & 1 & 1 \\ a_{n-2} - a_{n-2} & a_{n-1} - a_{n-2} & a_n - a_{n-2} \\ a_{n-2}^2 - a_{n-2} a_{n-2} & a_{n-1}^2 - a_{n-2} a_{n-2} & a_n^2 - a_{n-2} a_{n-2} \end{bmatrix}$$

所以 $|A| =$

$$\begin{bmatrix} 1 & 1 & 1 \\ 0 & a_{n-1} & a_n \\ 0 & a_{n-1}^2 & a_n^2 \end{bmatrix} = (a_{n-1} - a_{n-2}) \begin{bmatrix} 1 & 1 & 1 \\ 0 & a_{n-1} & a_n \\ 0 & a_{n-1}^2 & a_n^2 \end{bmatrix} = (a_{n-1} - a_{n-2}) \cdot (a_n - a_{n-2}) \cdot (a_n - a_{n-1})$$