

# Linear Algebra

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## 一、判断正误

1. Every matrix is row equivalent to a unique matrix in echelon form.(F)

[解析]教材13页定理一

每个矩阵行等价于唯一的简化阶梯型矩阵。

### THEOREM 1

#### Uniqueness of the Reduced Echelon Form

Each matrix is row equivalent to one and only one reduced echelon matrix.

2. If  $A$  is an invertible  $n \times n$  matrix, then the equation  $Ax = b$  is consistent for each  $b$  in  $\mathbb{R}^n$ .(T)

[解析]教材104页定理五

- d. True. This follows from Theorem 5, which also says that the solution of  $Ax = b$  is unique, for each  $b$ .

### THEOREM 5

If  $A$  is an invertible  $n \times n$  matrix, then for each  $b$  in  $\mathbb{R}^n$ , the equation  $Ax = b$  has the unique solution  $x = A^{-1}b$ .

## 二、计算

1. Find bases for  $NulA$  and  $ColA$ .

a.

$$A = \begin{bmatrix} -2 & 4 & -2 & -4 \\ 2 & -6 & -3 & 1 \\ -3 & 8 & 2 & -3 \end{bmatrix}$$

[解析]

- 化为阶梯型矩阵，含有主元列的构成列空间。
- 求解矩阵的零空间--->解  $Ax = 0$

3. **13.**  $A = \begin{bmatrix} -2 & 4 & -2 & -4 \\ 2 & -6 & -3 & 1 \\ -3 & 8 & 2 & -3 \end{bmatrix}, B = \begin{bmatrix} 1 & 0 & 6 & 5 \\ 0 & 2 & 5 & 3 \\ 0 & 0 & 0 & 0 \end{bmatrix}$

13. Since  $B$  is a row echelon form of  $A$ , we see that the first and second columns of  $A$  are its pivot columns. Thus a basis for  $\text{Col } A$  is

$$\left\{ \begin{bmatrix} -2 \\ 2 \\ -3 \end{bmatrix}, \begin{bmatrix} 4 \\ -6 \\ 8 \end{bmatrix} \right\}.$$

To find a basis for  $\text{Nul } A$ , we find the general solution of  $A\mathbf{x} = \mathbf{0}$  in terms of the free variables:  $x_1 = -6x_3 - 5x_4$ ,  $x_2 = (-5/2)x_3 - (3/2)x_4$ , with  $x_3$  and  $x_4$  free. So

$$\mathbf{x} = \begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \end{bmatrix} = x_3 \begin{bmatrix} -6 \\ -5/2 \\ 1 \\ 0 \end{bmatrix} + x_4 \begin{bmatrix} -5 \\ -3/2 \\ 0 \\ 1 \end{bmatrix},$$

and a basis for  $\text{Nul } A$  is

$$\left\{ \begin{bmatrix} -6 \\ -5/2 \\ 1 \\ 0 \end{bmatrix}, \begin{bmatrix} -5 \\ -3/2 \\ 0 \\ 1 \end{bmatrix} \right\}.$$

b.

$$A = \begin{bmatrix} 1 & 2 & 0 & 4 & 5 \\ 0 & 0 & 5 & -7 & 8 \\ 0 & 0 & 0 & 0 & -9 \\ 0 & 0 & 0 & 0 & 0 \end{bmatrix}$$

$$14. \quad A = \begin{bmatrix} 1 & 2 & -5 & 11 & -3 \\ 2 & 4 & -5 & 15 & 2 \\ 1 & 2 & 0 & 4 & 5 \\ 3 & 6 & -5 & 19 & -2 \end{bmatrix},$$

$$B = \begin{bmatrix} 1 & 2 & 0 & 4 & 5 \\ 0 & 0 & 5 & -7 & 8 \\ 0 & 0 & 0 & 0 & -9 \\ 0 & 0 & 0 & 0 & 0 \end{bmatrix}$$

14. Since  $B$  is a row echelon form of  $A$ , we see that the first, third, and fifth columns of  $A$  are its pivot columns. Thus a basis for  $\text{Col } A$  is

$$\left\{ \begin{bmatrix} 1 \\ 2 \\ 1 \\ 3 \end{bmatrix}, \begin{bmatrix} -5 \\ -5 \\ 0 \\ -5 \end{bmatrix}, \begin{bmatrix} -3 \\ 2 \\ 5 \\ -2 \end{bmatrix} \right\}.$$

To find a basis for  $\text{Nul } A$ , we find the general solution of  $A\mathbf{x} = \mathbf{0}$  in terms of the free variables, mentally completing the row reduction of  $B$  to get:  $x_1 = -2x_2 - 4x_4$ ,  $x_3 = (7/5)x_4$ ,  $x_5 = 0$ , with  $x_2$  and  $x_4$  free. So

$$\mathbf{x} = \begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \\ x_5 \end{bmatrix} = x_2 \begin{bmatrix} -2 \\ 1 \\ 0 \\ 0 \\ 0 \end{bmatrix} + x_4 \begin{bmatrix} -4 \\ 0 \\ 7/5 \\ 1 \\ 0 \end{bmatrix},$$

and a basis for  $\text{Nul } A$  is

$$\left\{ \begin{bmatrix} -2 \\ 1 \\ 0 \\ 0 \\ 0 \end{bmatrix}, \begin{bmatrix} -4 \\ 0 \\ 7/5 \\ 1 \\ 0 \end{bmatrix} \right\}.$$

2.

Let  $\mathbf{b}_1 = \begin{bmatrix} 1 \\ -3 \end{bmatrix}$ ,  $\mathbf{b}_2 = \begin{bmatrix} -2 \\ 4 \end{bmatrix}$ ,  $\mathbf{c}_1 = \begin{bmatrix} -7 \\ 9 \end{bmatrix}$ ,  $\mathbf{c}_2 = \begin{bmatrix} -5 \\ 7 \end{bmatrix}$ , and consider the bases for  $\mathbb{R}^2$  given by  $\mathcal{B} = \{\mathbf{b}_1, \mathbf{b}_2\}$  and  $\mathcal{C} = \{\mathbf{c}_1, \mathbf{c}_2\}$ .

- Find the change-of-coordinates matrix from  $\mathcal{C}$  to  $\mathcal{B}$ .
- Find the change-of-coordinates matrix from  $\mathcal{B}$  to  $\mathcal{C}$ .

[解答]

这里我们知道

a. Notice that  ${}_{B \leftarrow C}P$  is needed rather than  ${}_{C \leftarrow B}P$ , and compute

$$[\mathbf{b}_1 \quad \mathbf{b}_2 \mid \mathbf{c}_1 \quad \mathbf{c}_2] = \left[ \begin{array}{cc|cc} 1 & -2 & -7 & -5 \\ -3 & 4 & 9 & 7 \end{array} \right] \sim \left[ \begin{array}{cc|cc} 1 & 0 & 5 & 3 \\ 0 & 1 & 6 & 4 \end{array} \right]$$

So

$${}_{B \leftarrow C}P = \begin{bmatrix} 5 & 3 \\ 6 & 4 \end{bmatrix}$$

b. By part (a) and property (6) above (with  $B$  and  $C$  interchanged),

$${}_{C \leftarrow B}P = ({}_{B \leftarrow C}P)^{-1} = \frac{1}{2} \begin{bmatrix} 4 & -3 \\ -6 & 5 \end{bmatrix} = \begin{bmatrix} 2 & -3/2 \\ -3 & 5/2 \end{bmatrix} \quad \blacksquare$$

Another description of the change-of-coordinates matrix  ${}_{C \leftarrow B}P$  uses the change-of-coordinate matrices  $P_B$  and  $P_C$  that convert  $B$ -coordinates and  $C$ -coordinates, respectively, into standard coordinates. Recall that for each  $\mathbf{x}$  in  $\mathbb{R}^n$ ,

$$P_B[\mathbf{x}]_B = \mathbf{x}, \quad P_C[\mathbf{x}]_C = \mathbf{x}, \quad \text{and} \quad [\mathbf{x}]_C = P_C^{-1}\mathbf{x}$$

Thus

$$[\mathbf{x}]_C = P_C^{-1}\mathbf{x} = P_C^{-1}P_B[\mathbf{x}]_B$$

In  $\mathbb{R}^n$ , the change-of-coordinates matrix  ${}_{C \leftarrow B}P$  may be computed as  $P_C^{-1}P_B$ . Actually, for matrices larger than  $2 \times 2$ , an algorithm analogous to the one in Example 3 is faster than computing  $P_C^{-1}$  and then  $P_C^{-1}P_B$ . See Exercise 12 in Section 2.2.

### 三、证明

1. 设  $A$  是  $n$  阶矩阵, 若  $A^2 = A$ , 证明  $A + E$  可逆.

[解答]

证明: 由于  $A^2 - A = 0$ , 我们想要证明  $(A + E)(?) = E$ , 那么如何求解? 处的表达式呢? 我们知道这样的因式分解是可以配凑的, 于是  $(A + E)(A - 2E) = -2E$ , 这里的配凑我们显然需要利用  $A^2 - A = 0$  这个现成的表达式来证明. 那么我们可以找到  $(?) = \frac{A-2E}{-2}$ , 说明  $A + E$  可逆, 证毕.

大家可以思考本题是否还有其他解法, 采用特征值证明??

2. 设  $A$  是  $m \times n$  矩阵,  $B$  是  $n \times s$  矩阵, 若  $AB = O$ , 证明  $\text{rank}(A) + \text{rank}(B) \leq n$ .

[解答]

分析: 总体思路: 采用矩阵分块的方式求解. 题目具有一定难度.

证明:

对矩阵  $B$  按照列分块, 我们记  $B = [\beta_1 \quad \beta_2 \quad \beta_3 \quad \cdots \quad \beta_s]$   
那么有

$$\begin{aligned} AB &= A[\beta_1 \quad \beta_2 \quad \beta_3 \quad \cdots \quad \beta_s] \\ &= [A\beta_1 \quad A\beta_2 \quad A\beta_3 \quad \cdots \quad A\beta_s] \\ &= [\vec{0} \quad \vec{0} \quad \vec{0} \quad \cdots \quad \vec{0}] \end{aligned}$$

于是我们有  $A\beta_j = \vec{0}, j = 1, 2, 3, \cdots, s$ ,

所以  $B$  的列向量都是齐次方程组  $A\vec{x} = \vec{0}$  的解, 由于方程组  $A\vec{x} = \vec{0}$  的解向量的  $\text{rank}(\vec{x}) = n - \text{rank}(A)$ , 这里的  $\vec{x}$  与  $\beta_j$  含义等价, 所以

$$\text{rank}(\beta_1, \beta_2, \beta_3, \dots, \beta_s) \leq n - \text{rank}(A)$$

我们又知道

$$\text{rank}(\beta_1, \beta_2, \beta_3, \dots, \beta_s) = \text{rank}(B)$$

所以:  $\text{rank}(A) + \text{rank}(B) \leq n$ .