Approximation Algorithms

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Review: Decision Problems vs Optimization Problems in NP

Given any **Opt** Problem **Min-P** = (X, Y(x), m(x, Y(x)), MIN/MAX) we can always define the corresponding **Decision Problem** k-P = $(X, Y(x), m(x, Y(x)), <= k \ (>= k)$

FACT (Definition).

the corresponding **Opt** problem **Min-P** is **NP-hard IFF**the decision problem **k-P** is **NP-Hard**

COR. IF P # NP and Min-P is NP-hard, THEN there is no poly-time deterministic algorithm for it.

Proof. By contradiction, if Min-P would have a poly-time algo A(x) then it can be used to decide k-P, for any k on the same tance:

Approximation Ratio (Error)

Optimization Problem

Given an optimization problem P = (X, Y(x), m(x, Y(x)), MIN/MAX), we say A is an r-approximation algorithm for P if, for any instance $x \in X$, the computation A(x) returns a <u>feasible</u> solution y^A such that:

$$\frac{m(x, y^A)}{\text{opt}(x)} \le r \ge 1$$
 (in the case of **MIN**)



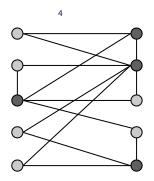
DEFINITIONS 2/1

Min-Vertex Cover

k-VC: Given a graph G = (V, E) and an integer k, is there a **k-size VC**, i.e., a subset of vertices $S \subseteq V$ such that $|S| \le k$, and for each edge, at least one of its endpoints is in S?

Min-VC: Given a graph G = (V, E), find a VC S^* for G of minimum size

Ex. there min-VC for the graph below has size 4.





A lower bound for optimal VC via Maximal Matchings

DEF. Given G(V, E), a Maximal Matching $M \subseteq E$ is a maximal subset of edges that share no vertex of V.

FACT 1: Given any graph G(V, E), consider any **Maximal Matching** $M \subseteq E$. Then, any **VC** for G must contain at least **1** vertex for every edge in M. Proof.

immediate consequence of def.s of **Matching** and **VC**.

FACT 2 (Lower Bound for the Optimum): $opt(G) \ge |M|$

An apx algorithm for Min VC

Matching Algorithm M-ALG

- ▶ Input: *G*(*V* , *E*);
- ► Find (any) Maximal Matching M;
- ▶ Return C = { all nodes touched by M};



DEFINITIONS

An apx algorithm for Min VC

Matching Algorithm M—ALG

- ▶ Input: G(V, E);
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THM 3. M-ALG is a 2-apx algorithm for Min-VC.



FEINITIONS

Proof of THM 3.

FACT 4. The returned solution **C** is:

- (1) always a **VC** for **G** AND **(2)** |C| = 2|M|.
- Proof. (1) Immediate consequence of the fact that **M** is <u>Maximal</u>.
- (2) is trivial. □

Recall **FACT 2**: opt
$$(G) \ge |M|$$
 (3)

From (2) and (3), it follows that:

$$|C|/opt(G) \le 2|M|/|M| = 2$$

