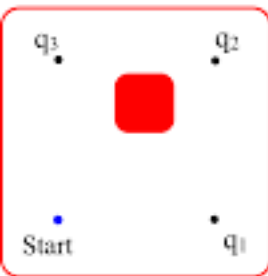
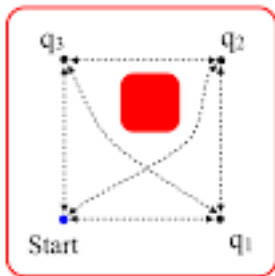


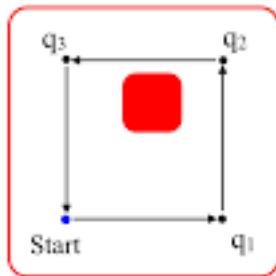
Problem



Path Planning



Task Planning

Problem  
scenarioPath  
Planner

Path costs

Task  
PlannerFinal  
task plan