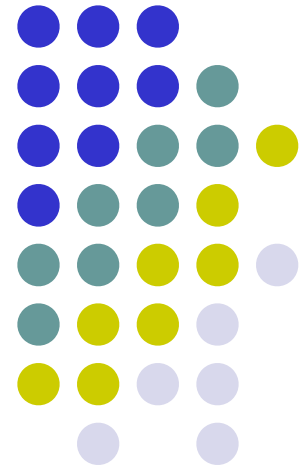
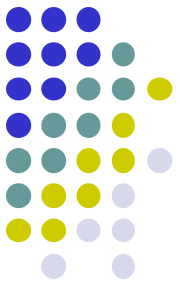


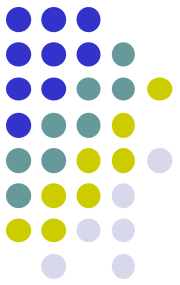
# Web Algorithms

Eng. Fabio Persia, PhD





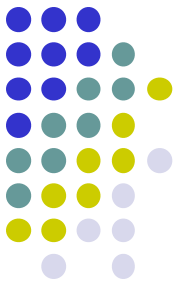
# Algorithmic techniques: dynamic programming (Part 1)



# Characteristics

- Like **divide-and-conquer paradigm**, break up a problem into smaller subproblems, solve recursively each subproblem, and combine solutions of subproblems to form solution to original problem.
- Easy-to-compute recurrence that allows one to determine the solution to a subproblem from the solution to smaller subproblems.
- Differently from divide-and-conquer, **subproblems** are not independent, but **overlap**, that is during the decompositions same subproblems occur frequently
- **Idea**: each subproblems is solved only once, thus reducing time complexity
- Differently from divide-and-conquer, usually **bottom-up** approach instead of top-down, that is starting from smaller subproblems solving in progress bigger ones, till the initial problem

# Applications



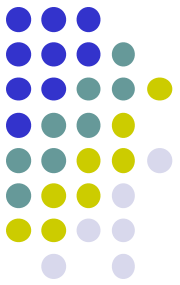
## Areas

- Computer science: theory, graphics, AI, compilers, systems,...
- Bioinformatics
- Control theory
- Information theory
- Operations research
- ...

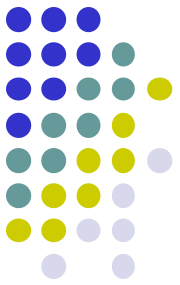
## Some famous dynamic programming algorithms

- Unix diff for comparing two files
- genetic sequence alignment (Smith-Waterman)
- shortest paths in networks (Bellman-Ford)
- ...

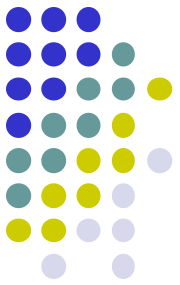
# Let's give a closer look ...



- The *Divide-and-Conquer* paradigm is based on the decomposition of problems in smaller subproblems:
  - recursively solves subproblems
  - combines the solutions of the subproblems to determine the solution of the initial problem
- If a problem of size  $n$  is decomposed in  $k$  subproblems of sizes  $n_1, \dots, n_k < n$ , respectively, then the time complexity can be expressed by the recurrence
$$T(n) = T(n_1) + \dots + T(n_k) + C(n),$$
with  $C(n)$  time of combining the  $k$  subsolutions
- The recurrence can be solved with different methods, as for instance resorting on the famous *Master Theorem*



- A classical example of application of *Divide-and-Conquer* is the computation of *Fibonacci* numbers
- The algorithm comes directly from the recursive definition of such numbers:
  - base case ( $n \leq 2$ ):  $F(1)=F(2)=1$
  - inductive case ( $n > 2$ ):  $F(n)=F(n-1)+F(n-2)$ ,  $n$
- Let's see the resulting algorithm....



*Algorithm Fibonacci(n)*

*Begin*

*if (n=1) or (n=2) return 1*

*else return Fibonacci(n-1)+Fibonacci(n-2)*

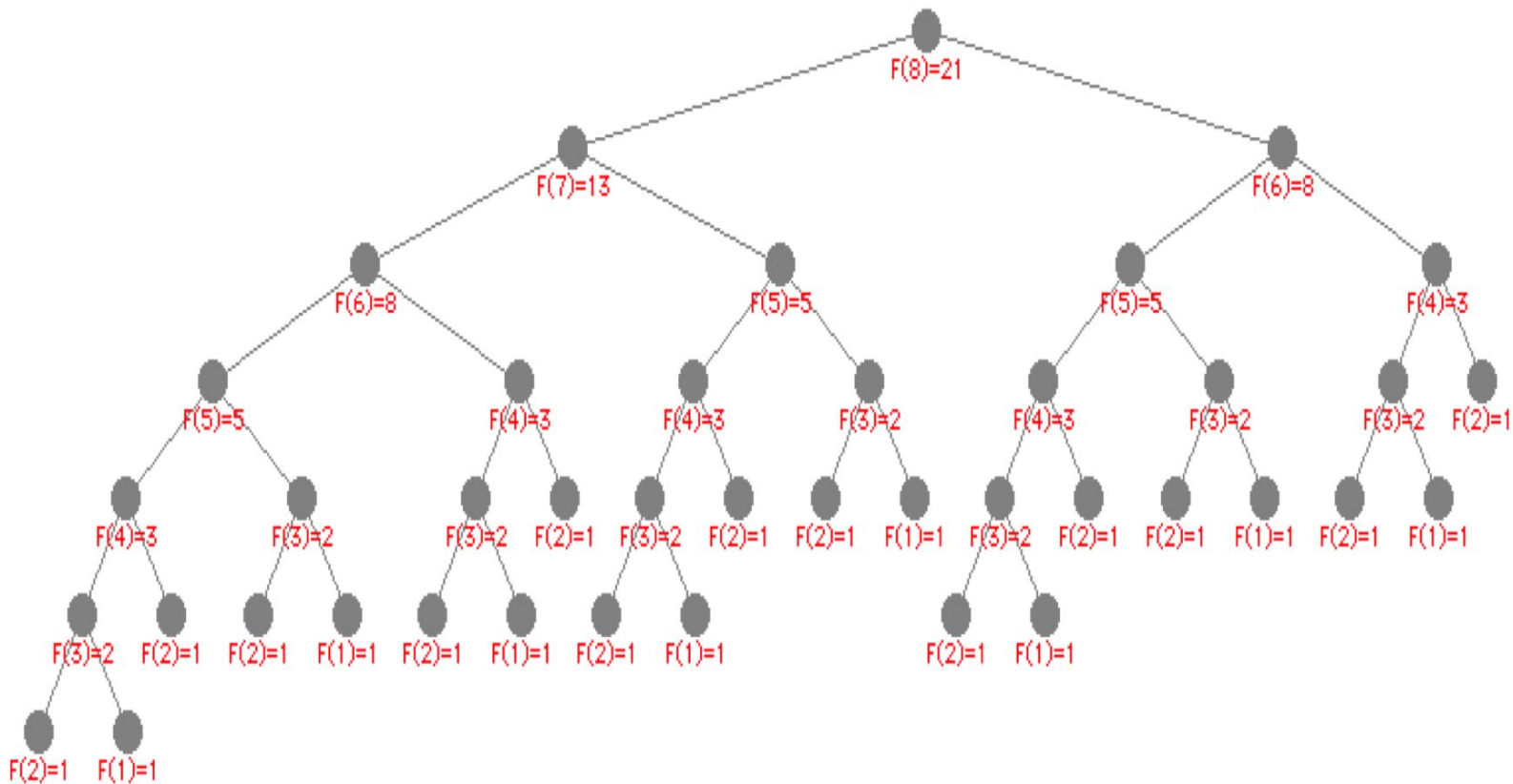
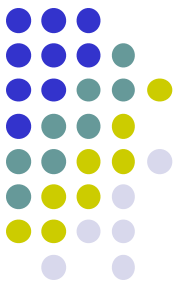
*End*

Time Complexity:

- $T(n) = T(n-1) + T(n-2) + \Theta(1)$ , that gives

$$T(n)=O(2^n)$$

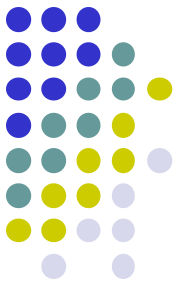
Let's have a look to the tree of the recursive calls:



### Remark:

- inefficient: same subproblems are solved again many times
- **dynamic programming**: store the **solution** of every **subproblem** in a **table** or **array**, thus avoiding solving it again
- in the resulting algorithm,  $F$  is an external global array visible to all the recursive calls:





*Algorithm Fibonacci2(n)*

*Begin*

*if (n=1) or (n=2) let  $F[n]=1$  and return  $F[n]$*

*else*

*if  $F[n]$  has been already assigned return  $F[n]$*

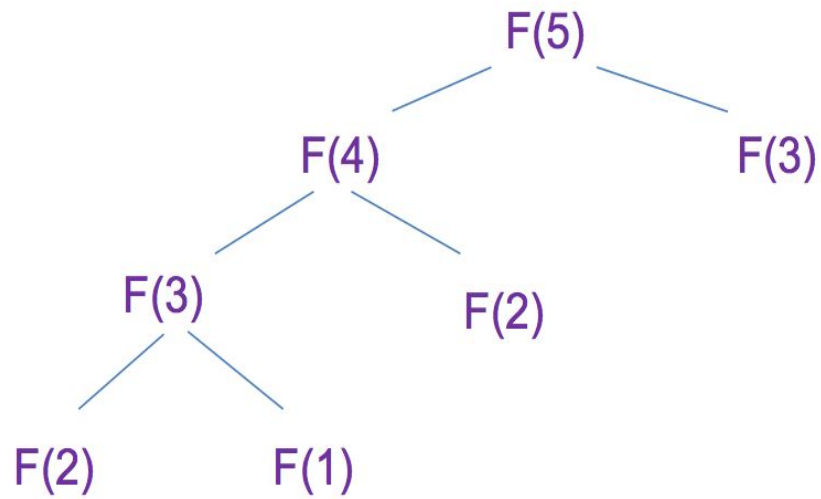
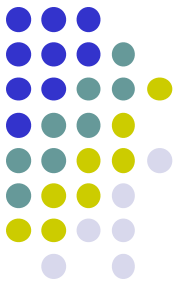
*else*

*let  $F[n]=\text{Fibonacci2}(n-1)+\text{Fibonacci2}(n-2)$*

*return  $F[n]$*

*End*

Let us see the new tree of the recursive calls for  $n=5$



1	1	2	3	5
---	---	---	---	---

1	1	2	3	
---	---	---	---	--

1	1	2		
---	---	---	--	--

1	1			
---	---	--	--	--

	1			
--	---	--	--	--

--	--	--	--	--

nstant

## Algorithm Fibonacci3(n)

Begin

$F[1]=1$

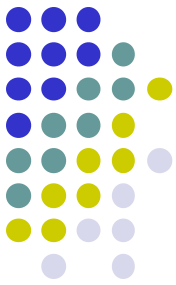
$F[2]=1$

For  $i=3$  to  $n$

$F[i]=F[i-1]+F[i-2]$

return  $F[n]$

End



Example  $n=5$

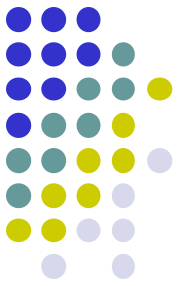
1				
---	--	--	--	--

1	1			
---	---	--	--	--

1	1	2		
---	---	---	--	--

1	1	2	3	
---	---	---	---	--

1	1	2	3	5
---	---	---	---	---

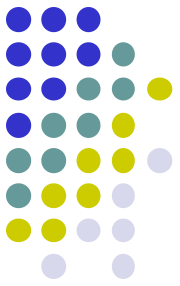


# Performance comparison

Actual running time on different platforms:

	<i>Fibonacci(58)</i>	<i>Fibonacci2(58)</i>
<b><i>Pentium IV 1700MHz</i></b>	<b><i>15820 s (<math>\approx</math> 4 hours)</i></b>	<b><i>0.7 millionths of s</i></b>
<b><i>Pentium III 450 MHz</i></b>	<b><i>43518 s (<math>\approx</math> 12 hours)</i></b>	<b><i>2.4 millionths of s</i></b>
<b><i>PowerPC G4 500 MHz</i></b>	<b><i>58321 s (<math>\approx</math> 16 hours)</i></b>	<b><i>2.8 millionths of s</i></b>

# Summarizing...



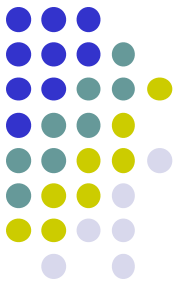
In dynamic programming:

- the initial problem can be recursively decomposed in subproblems
- same subproblems occur many times and are solved once
- the solution of a subproblem can be obtained combining the ones of smaller subproblems

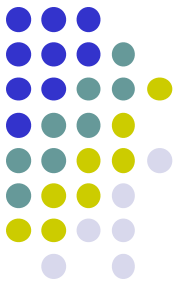
Two possible implementations:

- *top-down* with table annotation (**memoization**)
- *bottom-up*

# Top-down versus bottom-up



- Top-down
  - exploits table annotation
  - pros: solves only the strictly needed subproblems
  - cons: overhead of recursive chain of calls
- Bottom-up
  - is the typical choice in dynamic programming
  - cons: solves also unnecessary subproblems
  - pros: it is anyway generally more efficient because it eliminates the weight of recursion, which affects more the overall performance



# Divide-and-Conquer versus dynamic progr.

## Divide-and-Conquer:

- Recursive technique
- **Top-down** approach (problems split in subproblems)
- Profitable when **subproblems are independent** (i.e. different)
- Otherwise, same subproblems solved multiple times

## Dynamic programming:

- Iterative technique
- Typically **bottom-up** approach
- Profitable when **subproblems overlap** (i.e. coincide)
- Each subproblem solved only once