Graph Theory and Optimization Parameterized Algorithms

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What is it about?

- Goal:
 - Find "efficient" exact algorithms for difficult problems (NP-hard).
 - For some (NP-hard) problems, the difficulty is not due to the size of the input, but to... the structure of the input, the size of the solution...
- Introduction to Parameterized Algorithms through Vertex Cover

A very nice book:

M. Cygan, F.V. Fomin, L. Kowalik, D. Lokshtanov, D. Marx, M. Pilipczuk, M. Pilipczuk, S. Saurabh:

Parameterized Algorithms, Springer 2015, ISBN 978-3-319-21274-6, pp. 3-555









Outline

- Vertex Cover: from exponential to polynomial
- Vertex Cover: a first FPT Algorithm
- Parameterized Complexity
- Vertex Cover: a first Kernelization Algorithm
- Mernelization
- 6 Linear kernel for Vertex Cover via Linear Programming
- Conclusion











pprox Cover 1^{st} FPT Parameterized Complexity 1^{st} Kernel Kernelization Linear Kernel via LP Conclusio

Reminder on Minimum Vertex Cover

Let G = (V, E) be a graph

Vertex Cover: set $K \subseteq V$ such that $\forall e \in E, e \cap K \neq \emptyset$

set of vertices that "touch" every edge

Finding a Vertex Cover of minimum size is "difficult"

Compute a Min. Vertex Cover is NP-complete [Garey,Johnson 1979]



of size 7 (in blue)









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Naive Exact Algo. for Min. Vertex Cover

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For k = 1 to |V| - 1 do

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If S is a vertex cover of G

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Time-complexity: $O(2^{|V|}|E|)$

 $2^{|V|}$ · number of subsets of vertices O(|E|): time to check if vertex cover

⇒ Exponential in the size of the graph.











Toward "polynomial" algorithms

Complexity of deciding if a graph has a vertex cover of size 1? of size 2?...









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fixed parameter: $k \in \mathbb{N}$ **input:** graph G = (V, E)

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Remark: the algorithm is still exponential (in the size *k* of the solution)









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Vertex Cover of size $\leq k$? Two simple Lemmas

$$G = (V, E)$$
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vc(G) = min. size of a vertex cover in G

Lemma 1:
$$vc(G) \le k \Rightarrow |E| \le k(|V|-1)$$

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Lemma 2: Let $\{x,y\} \in E$. $vc(G) = min\{vc(G \setminus x), vc(G \setminus y)\} + 1$ "for any edge xy, any minimum vertex cover contains at least one of x or y..."









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proof:

- Let $S \subseteq V$ be any vertex cover of $G \setminus x$. Then $S \cup \{x\}$ is a vertex cover of G. Hence $vc(G) < vc(G \setminus x) + 1$ (symmetrically for $G \setminus y$)
- Let $S \subseteq V$ be any vertex cover of G. At least one of x or y is in S. If $x \in S$ then $S \setminus x$ vertex cover of $G \setminus x$. Hence $vc(G \setminus x) < vc(G) - 1$. Otherwise, if $y \in S$, then $S \setminus y$ vertex cover of $G \setminus y$ and $vc(G \setminus y) \leq vc(G) - 1$.









Lemma 2 proves the correctness of the following algorithm

Rec: Branch & Bound Algorithm for computing Minimum size Vertex Cover

input: graph G = (V, E)

If |E| = 0, Return 0. Else if |E| = 1, Return 1

Else Let $\{x,y\} \in E$, let $A = \text{Rec}(G \setminus x)$, $B = \text{Rec}(G \setminus y)$, Return min $\{A,B\} + 1$





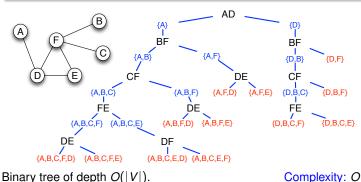




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Alg2: Branch & Bound Algorithm for deciding if $vc(G) \le k$

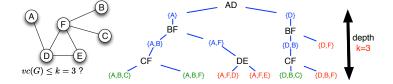
input: graph G = (V, E), integer $\ell \le k$.

If |E| > 0 and $\ell = 0$, Return ∞ . Else if |E| = 0, Return 0.

Else if |E| = 1, Return 1

Else Let $\{x,y\} \in E$, let $A = \text{Alg2}(G \setminus x, \ell - 1)$, $B = \text{Alg2}(G \setminus y, \ell - 1)$, Return

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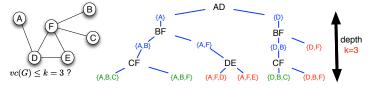
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Binary tree of depth O(k): Complexity: $O(2^k|E|)$. By Lem. 1, |E| = O(k|V|),

Alg2 decides if $vc(G) \le k$ in time $O(2^k \cdot k|V|)$ (linear in |G|) |V| and k are "separated" ⇒ Fixed Parameterized Tractable (FPT)





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Parameterized Complexity in brief

Parameterized Problem

A parameterized problem is a language $L \subseteq \Sigma^* \times \Sigma^*$, where Σ is a finite alphabet. The first component corresponds to the input. The second component is called the parameter of the problem.

Class FPT

A parameterized problem is fixed-parameter tractable (FPT) if it can be determined in time $f(k) \cdot |x|^{O(1)}$ whether $(x,k) \in L$, where f is a computable function only depending on k.

The corresponding complexity class is called FPT.

In other words:

Given a (NP-hard) problem with input of size n and a parameter k, a **FPT** algorithm runs in time $f(k) \cdot n^{O(1)}$ for some computable function f.

Examples: *k*-Vertex Cover, *k*-Longest Path...









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Data Reduction

A general GOOD idea: Data reduction

Find simple rules to reduce the size of the input

From input G, compute (in polynomial-time) another instance G' s.t.

|G'| < |G| and a solution for G can be deduced from a solution for G'.

Hence, it is sufficient to solve the problem on the (smaller) instance G'













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Rule: If *G* has a vertex *v* of degree > k, $vc(G) \le k \Leftrightarrow vc(G \setminus v) \le k-1$.











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Lemma 4: G = (V, E). If $vc(G) \le k$ and no vertex of degree > kThen $|E| < k^2$

proof: Each of the $\leq k$ vertices of a Vertex Cover covers at most k edges.







Vertex Cover of size < k? First Kernelization algorithm

Alg3: Kernelization Algorithm for deciding if $vc(G) \le k$

input: graph G = (V, E), integer $\ell \le k$.

Remove isolated vertices

If |E| = 0, Return TRUE. Else if $\ell = 0$, Return FALSE

Else if no vertex of degree $> \ell$ and $|V| > \ell^2$, Return FALSE

Else if no vertex of degree $> \ell$, Apply $Alg2(G, \ell)$

Else Let v be a vertex of degree $> \ell$. Apply $Alg(G \setminus v, \ell - 1)$.

While there is a "high" degree node, add it to the solution. When there are no such nodes, either it remains too much edges to have a small vertex cover. Otherwise, apply brute force algorithm (e.g., Alg2) to the remaining "small" graph











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Time-complexity: $O(2^k \cdot k^2 + |V| \cdot k)$

(It is a FPT algorithm!!)

 $O(|V| \cdot k)$: find at most k vertices of "high" degree **Reduction Rule** $O(2^k \cdot k^2)$: application of Alg2 to a graph with $O(k^2)$ edges "Brute Force"







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Kernelization: Apply reduction rule(s) until the instance has constant (only dependent on k) size. Then apply "brute force"







Vertex Cover Comparison of previous algorithms

Problem: Let $k \in \mathbb{N}$ be a fixed integer. Given G = (V, E), $vc(G) \le k$?

	time-complexity	numerical example $ V = 10^4$ and $k = 10$
brute-force for Min. Vertex Cover	$O(E \cdot 2^{ V })$	>> 10 ³⁰⁰⁰
brute-force, <i>k</i> fixed (<i>Alg</i> 1)	$O(E V ^k)$	10 ⁴⁸
bounded Branch & Bound (Alg2)	$O(2^k \cdot k V)$	10 ⁸
first kernelization (Alg3)	$O(2^k \cdot k^2 + k V)$	2·10 ⁵











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Kernelization

Problem Kernel

Let L be a parameterized problem, that is, L consists of (I, k), where I is the problem instance and k is the parameter.

Reduction to a problem kernel then means to replace instance (I, k) by a "reduced" instance (I', K') (called problem kernel) such that

- \bullet $k' \leq k$, $|I'| \leq g(k)$ for some function g only depending on k,
- $(I,k) \in L$ if and only if $(I',k') \in L$, and
- 3 reduction from (I, k) to (I', k') has to be computable in polynomial time.











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A Kernelization algorithm consists in

- reduce the size of the instance I in time polynomial in |I| = n
- 2 solve the problem on the reduced instance l' with size O(g(k))

Time-complexity: $O(f(g(k)) + n^{O(1)})$

where function f is the time-complexity for solving the problem on I' (e.g., brute force)

It is a FPT algorithm!!









Theorem: [Bodlaender et al. 2009]

A parameterized problem is FPT if and only if

it is decidable and has a kernelization algorithm.

$$g(k) = O(k)$$

$$(k) = O(k^2)$$













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proof: \Leftarrow see previous slide ("decidable" implies that function f exists) \Rightarrow Kernelization: Apply the FPT algorithm. The kernel is the answer $\in \{YES, NO\}$.

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It is desirable (if possible) to compute "small" kernel, e.g.,

linear kernel

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Example: Alg3 for Vertex Cover













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In what follows: kernelization algorithm for Vertex Cover with linear kernel











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Let G = (V, E) be a graph

Integer Linear programme (ILP) for Vertex Cover:

$$\begin{array}{llll} \text{Min.} & \displaystyle \sum_{v \in V} x_v \\ \text{s.t.:} & \displaystyle x_v + x_u & \geq & 1 & \forall \{u,v\} \in E \\ & \displaystyle x_v & \in & \{0,1\} & \forall v \in V \end{array}$$

Fractional relaxation (LP) for Vertex Cover:

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Theorem: From Fractional to Integral Solution

Let $(x_v)_{v \in V}$ be a fractional optimal solution.

 $V_0 = \{ v \in V \mid x_v < 1/2 \}$, $V_1 = \{ v \in V \mid x_v > 1/2 \}$ and $V_{1/2} = \{ v \in V \mid x_v = 1/2 \}$ There exists a Minimum (Integral) vertex cover S such that $\dot{V}_1 \subseteq S \subseteq V_1 \cup V_{1/2}$









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Fractional relaxation (LP) for Vertex Cover:

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$$\sum_{v \in V} x_v$$
s.t.:
$$x_v + x_u \ge 1 \quad \forall \{u, v\} \in E$$

$$x_v \ge 0 \quad \forall v \in V$$

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proof: S^* be an optimal (integral) solution of Vertex Cover. Let $S = (S^* \setminus V_0) \cup V_1$. Clearly S is a vertex cover. By contradiction, if S is not optimal, $|S^* \cap V_0| < |V_1 \setminus S^*|$. Let $v \in V_1 \cup V_0$ be a vertex with x_v as close as possible from 1/2 (exists by assumption). Let $\varepsilon = |x_v - 1/2|$. Remove ε to x_w for any $w \in V_1 \setminus S^*$ and add ε to x_w for any $w \in V_0 \cap S^*$. We get a smaller feasible fractional solution, a contradiction.







Let G = (V, E) be a graph

Integer Linear programme (ILP) for Vertex Cover:

$$\begin{array}{llll} \text{Min.} & \sum_{v \in V} x_v \\ \text{s.t.:} & x_v + x_u & \geq & 1 & \forall \{u,v\} \in E \\ & x_v & \in & \{0,1\} & \forall v \in V \end{array}$$

Fractional relaxation (LP) for Vertex Cover:

$$\begin{array}{ccccc} \text{Min.} & \sum_{v \in V} x_v \\ \text{s.t.:} & x_v + x_u & \geq & 1 & \forall \{u,v\} \in E \\ & x_v & \geq & \mathbf{0} & \forall v \in V \end{array}$$

Theorem: From Fractional to Integral Solution

Let $(x_v)_{v \in V}$ be a fractional optimal solution.

 $V_0 = \{ v \in V \mid x_v < 1/2 \}$, $V_1 = \{ v \in V \mid x_v > 1/2 \}$ and $V_{1/2} = \{ v \in V \mid x_v = 1/2 \}$ There exists a Minimum (Integral) vertex cover S such that $\dot{V}_1 \subseteq S \subseteq V_1 \cup V_{1/2}$

Corollary: reduction Rule using LP for Vertex Cover

Let $(x_v)_{v \in V}$ be a fractional optimal solution.

Then $vc(G) \le k$ if and only if $vc(G \setminus V_1) \le k - |V_1|$.











Linear Kernel for Vertex Cover

Alg4: Linear Kernel for $vc(G) \leq k$

input: graph G = (V, E), integer $\ell \le k$.

If |E| = 0, Return TRUE

Remove isolated vertices

Let $(x_v)_{v \in V}$ be an optimal solution obtained by LP

If optimal fractional solution $> \ell$, Return FALSE

Else let $V_1 = \{ v \in V \mid x_v > 1/2 \}.$

If $V_1 \neq \emptyset$ then Return Alg4($G \setminus V_1, \ell - |V_1|$).

Else Apply $Alg2(G, \ell)$









Alg4: Linear Kernel for $vc(G) \le k$

input: graph G = (V, E), integer $\ell \le k$.

If |E| = 0, Return TRUE

Remove isolated vertices

Let $(x_v)_{v \in V}$ be an optimal solution obtained by LP

If optimal fractional solution $> \ell$, Return FALSE

Else let $V_1 = \{ v \in V \mid x_v > 1/2 \}.$

If $V_1 \neq \emptyset$ then Return Alg4($G \setminus V_1, \ell - |V_1|$).

Else Apply $Alg2(G,\ell)$

While possible, apply LP and add to the solution the vertices w with $x_w > 1/2$.

When it is not possible anymore, then all vertices v are such that $x_v = 1/2$ (check it). Hence $|V| \le 2k$ (Linear kernel).

Then, apply brute force algorithm (e.g., Alg2) to the remaining "small" graph









Outline

- Vertex Cover: from exponential to polynomial
- Vertex Cover: a first FPT Algorithm
- Parameterized Complexity
- Vertex Cover: a first Kernelization Algorithm
- 6 Kernelization
- 6 Linear kernel for Vertex Cover via Linear Programming
- Conclusion









Take Aways

- Parameterized Problem: input (size n) + parameter k
- FPT algorithm: in time $f(k)n^{O(1)}$
- Kernelization: Data reduction
- Kernelization ⇔ FPT
- Linear Kernel for Vertex Cover







