

# Week 6 – Lesson 1: Recurrent Neural Networks (RNNs)

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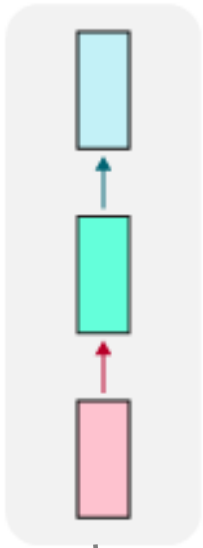


# Topic 1:

## Types of Sequence Problems

So far: Standard  
“Feedforward”  
Neural Networks

one to one

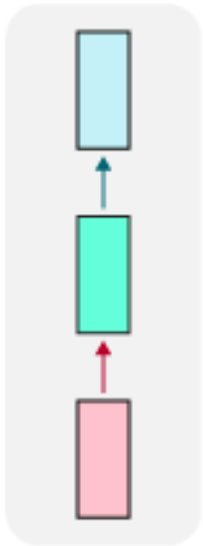


e.g. image classification, house price prediction

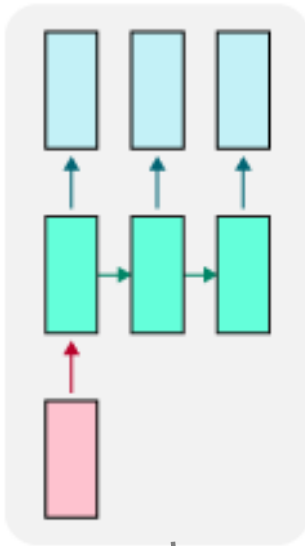
So far: Standard  
“Feedforward”  
Neural Networks

# Types of Sequence Problems

one to one



one to many

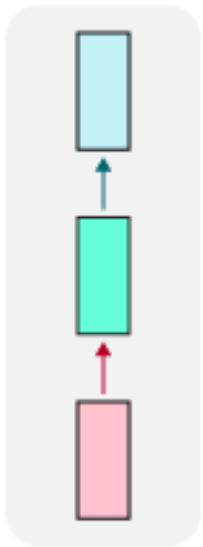


e.g. image captioning

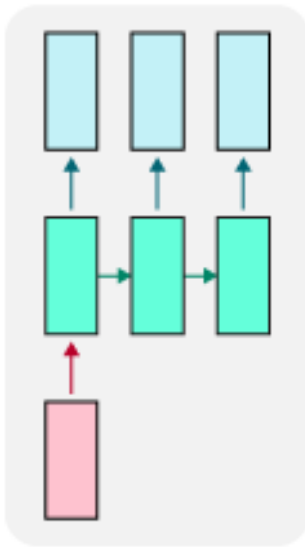
So far: Standard  
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# Types of Sequence Problems

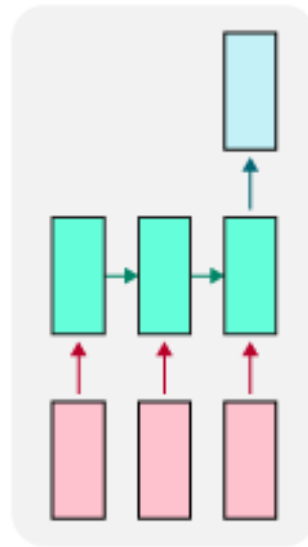
one to one



one to many



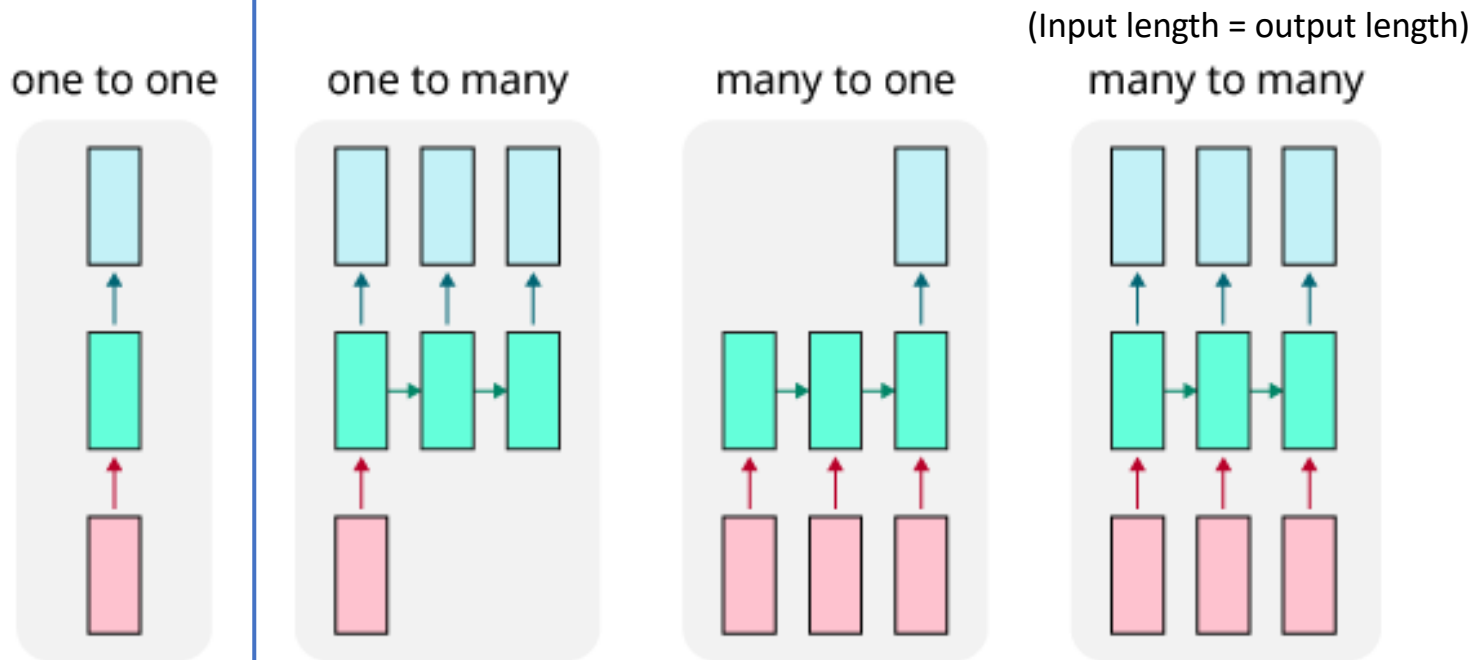
many to one



e.g. video classification, sentiment classification

So far: Standard  
“Feedforward”  
Neural Networks

# Types of Sequence Problems

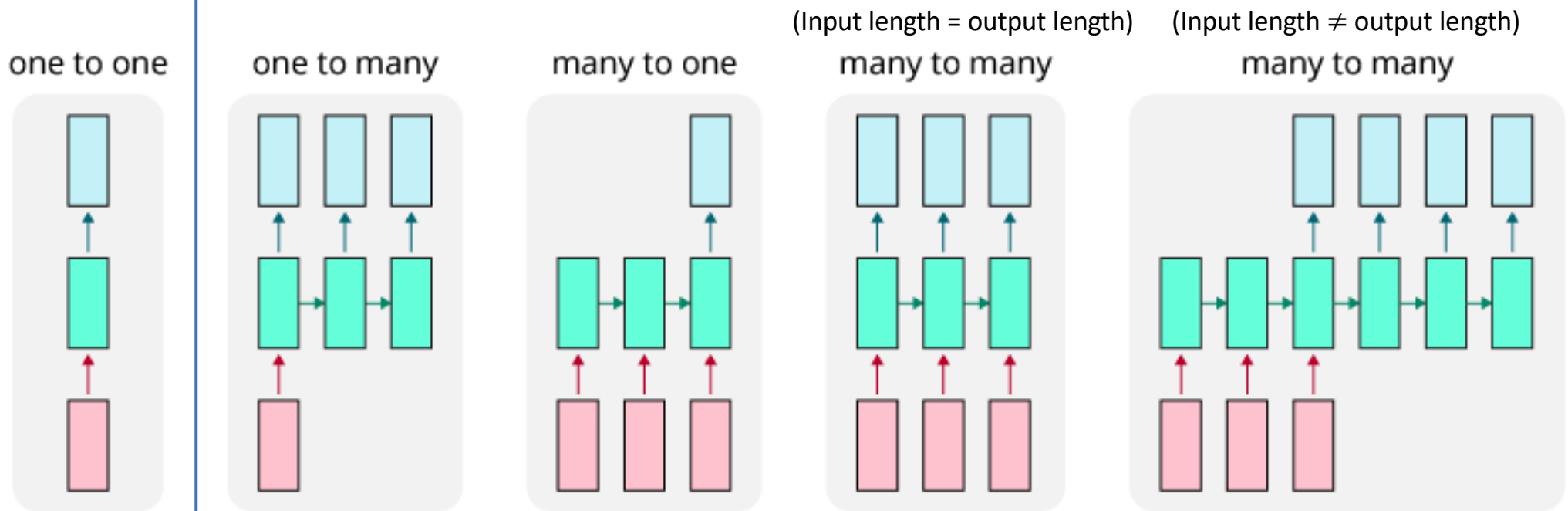


e.g. Per-frame video classification

Image from: <http://karpathy.github.io/2015/05/21/rnn-effectiveness/>

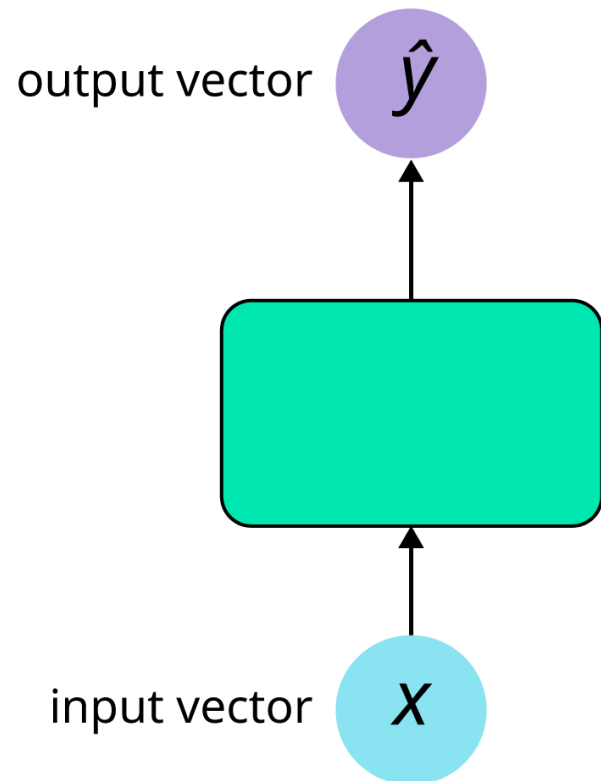
So far: Standard  
“Feedforward”  
Neural Networks

# Types of Sequence Problems



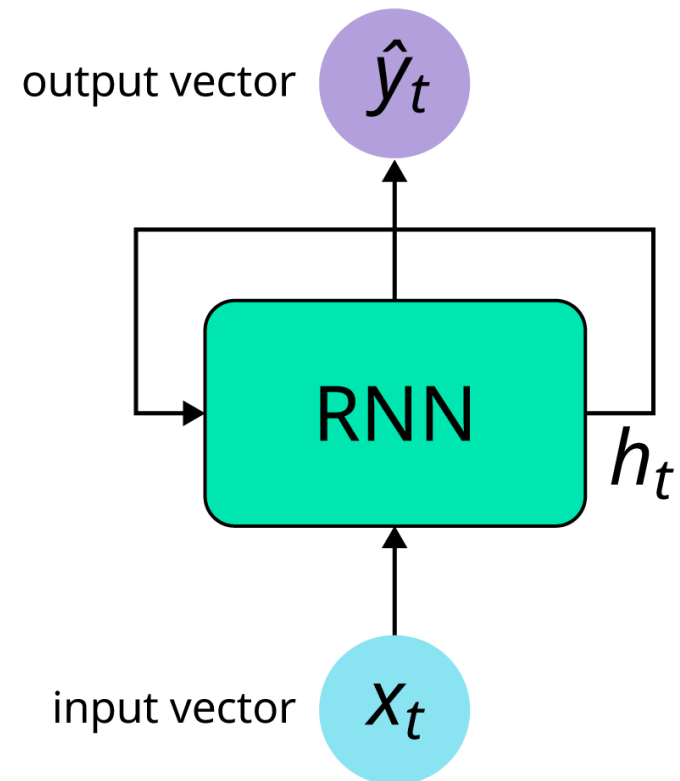
e.g. machine translation, chatbots

So far: Standard “Feedforward”  
Neural Networks



Recurrent Neural Networks (RNNs)  
for sequential modelling

Have an **internal loop**





# Reference for Topic 1

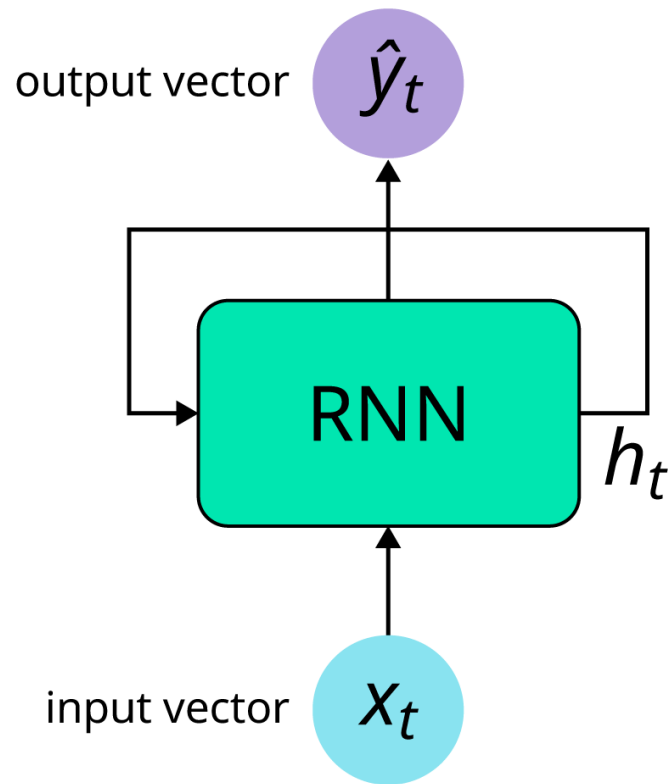
- Blog by Andrej Karpathy: <http://karpathy.github.io/2015/05/21/rnn-effectiveness/>
- Lectures from University of Michigan:  
<https://web.eecs.umich.edu/~justincj/teaching/eecs498/FA2020/schedule.html>
- Video lecture by Alexander Amini: MIT course on Recurrent Neural Networks, YouTube.

# Topic 2:

## Recurrent Neural Networks (RNNs)

# Recurrent Neural Networks (RNNs)

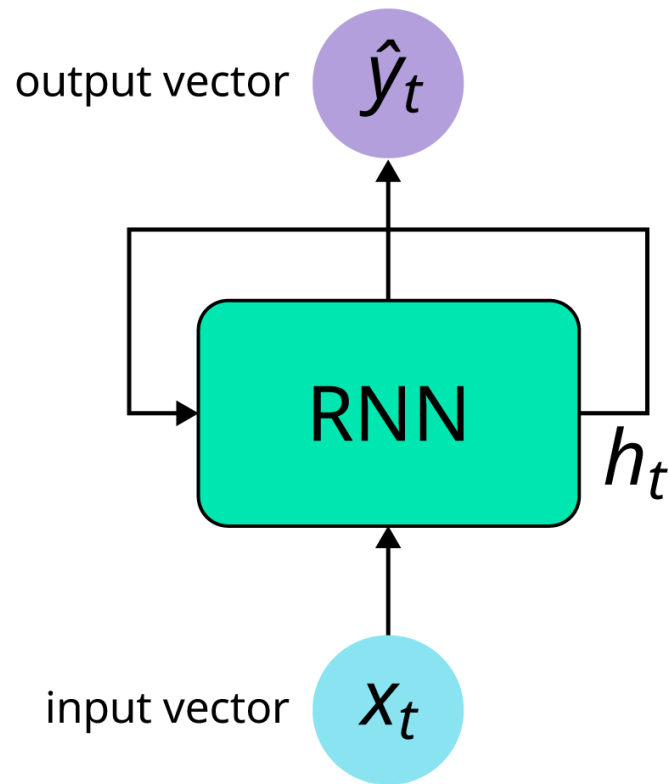
Also called “Vanilla RNNs”



Key idea: RNNs have an **internal/hidden state**  $h_t$  that can represent context information.

The	cat	sat	on	the	mat
$x_0$	$x_1$	$x_2$	$x_3$	$x_4$	$x_5$

# “Recurrent” Neural Networks (RNNs)



Apply a **recurrence formula** at every time step to update the internal/hidden state:

$$h_t = f_W(h_{t-1}, x_t)$$

internal state

Function parameterized by  $W$

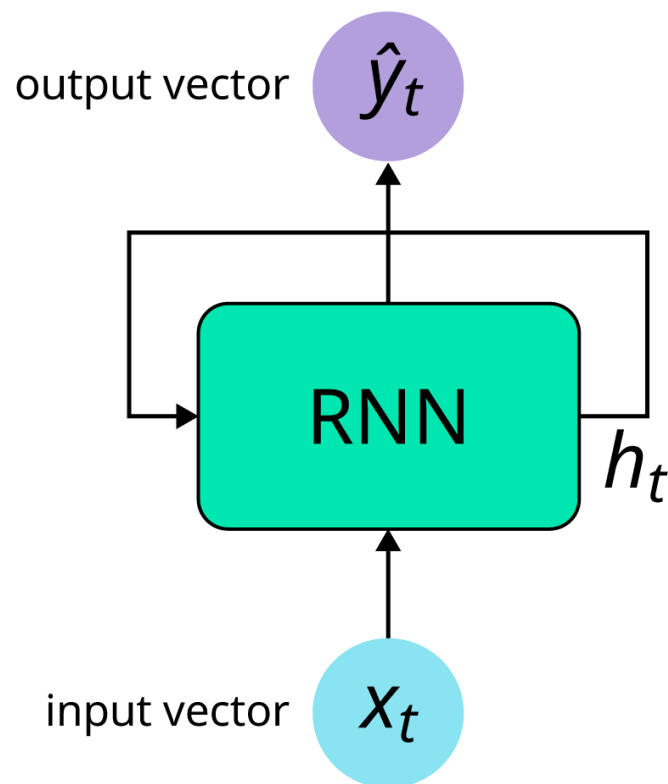
input vector

old state  $h_{t-1} = f_W(h_{t-2}, x_{t-1})$

...

$$h_1 = f_W(h_0, x_1)$$

# State update and output



**Output vector**

$$\hat{y}_t = W_{hy}h_t$$



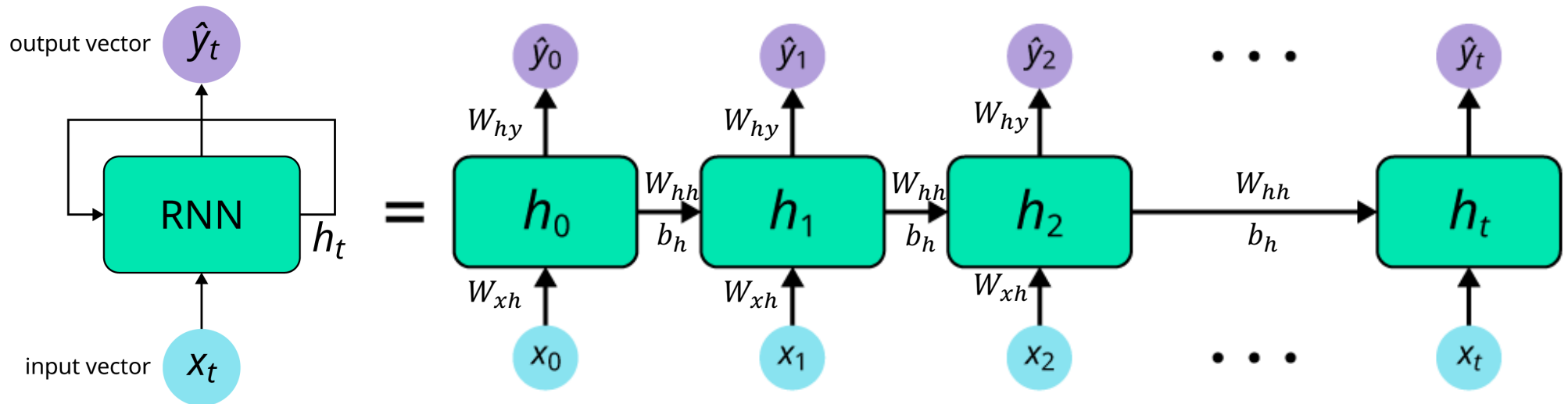
**Update the hidden state**

$$h_t = \tanh(W_{hh}h_{t-1} + W_{xh}x_t + b_h)$$

# Unfolding an RNN

$$h_t = \tanh(W_{hh}h_{t-1} + W_{xh}x_t + b_h)$$

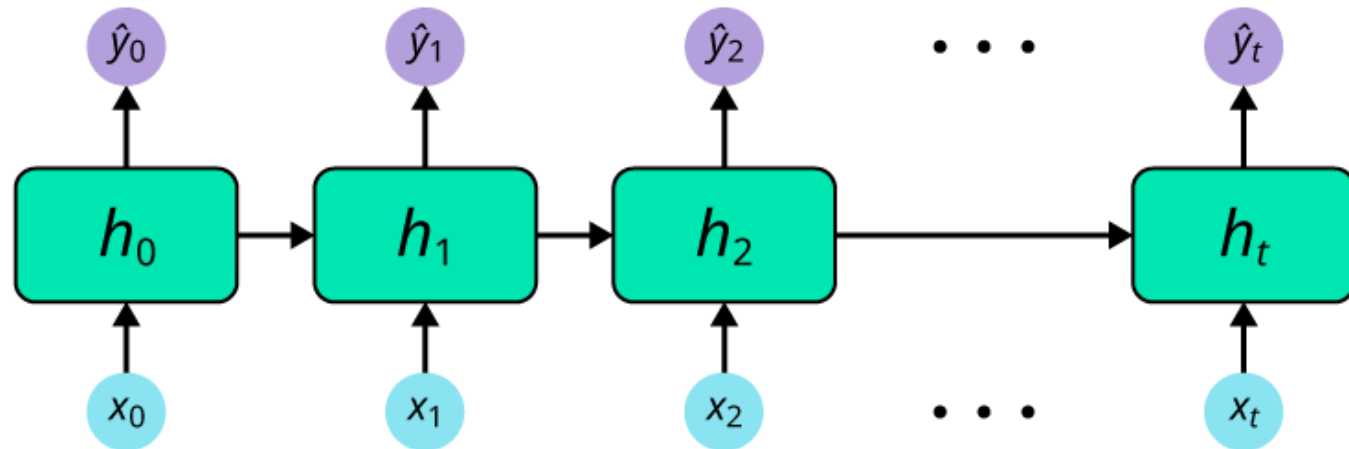
$$\hat{y}_t = W_{hy}h_t$$



The **same weight matrices** are used at every time-step

# Summary of RNNs

- Main feature of RNNs is its **hidden state**, considered as the **memory** of the network.
- **Sharing parameters** across all time steps.
- We may not need inputs or output at every time step, depending on the task.



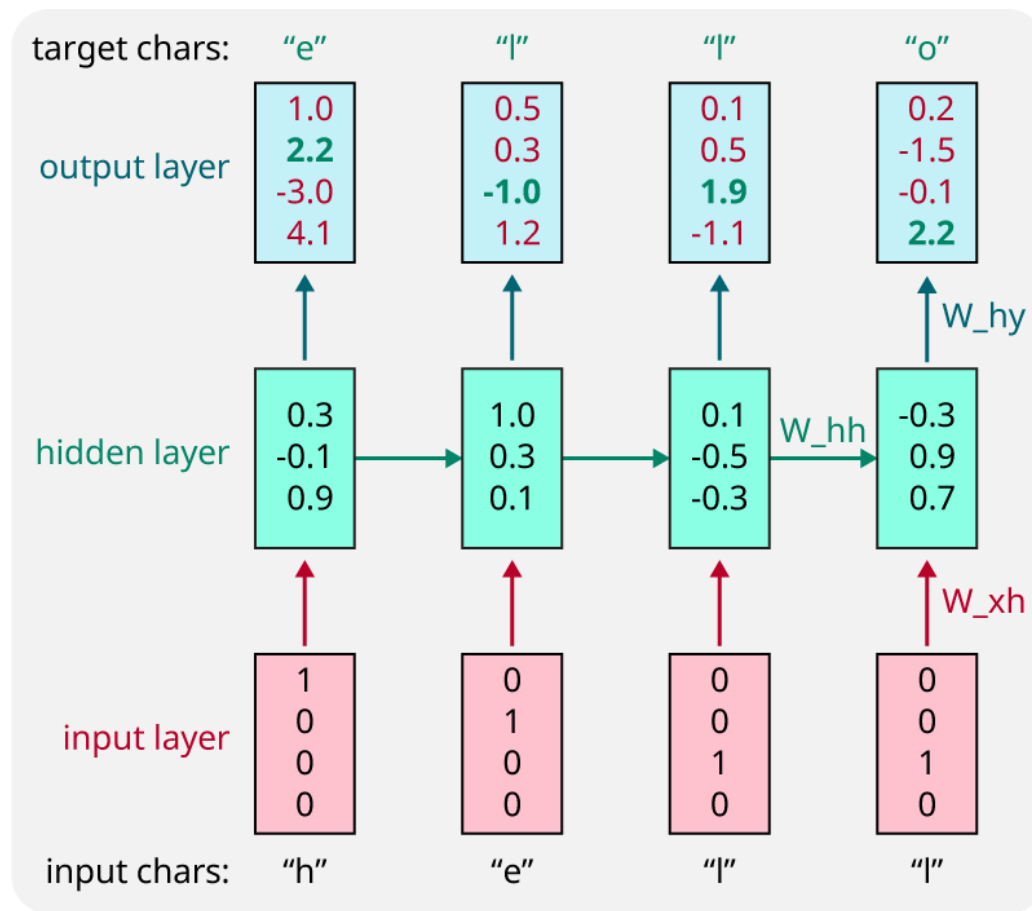
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- Video lecture by Alexander Amini: MIT course on Recurrent Neural Networks, YouTube.
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- Lectures from University of Michigan:  
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# Topic 3: A Simple Language- Modelling Example

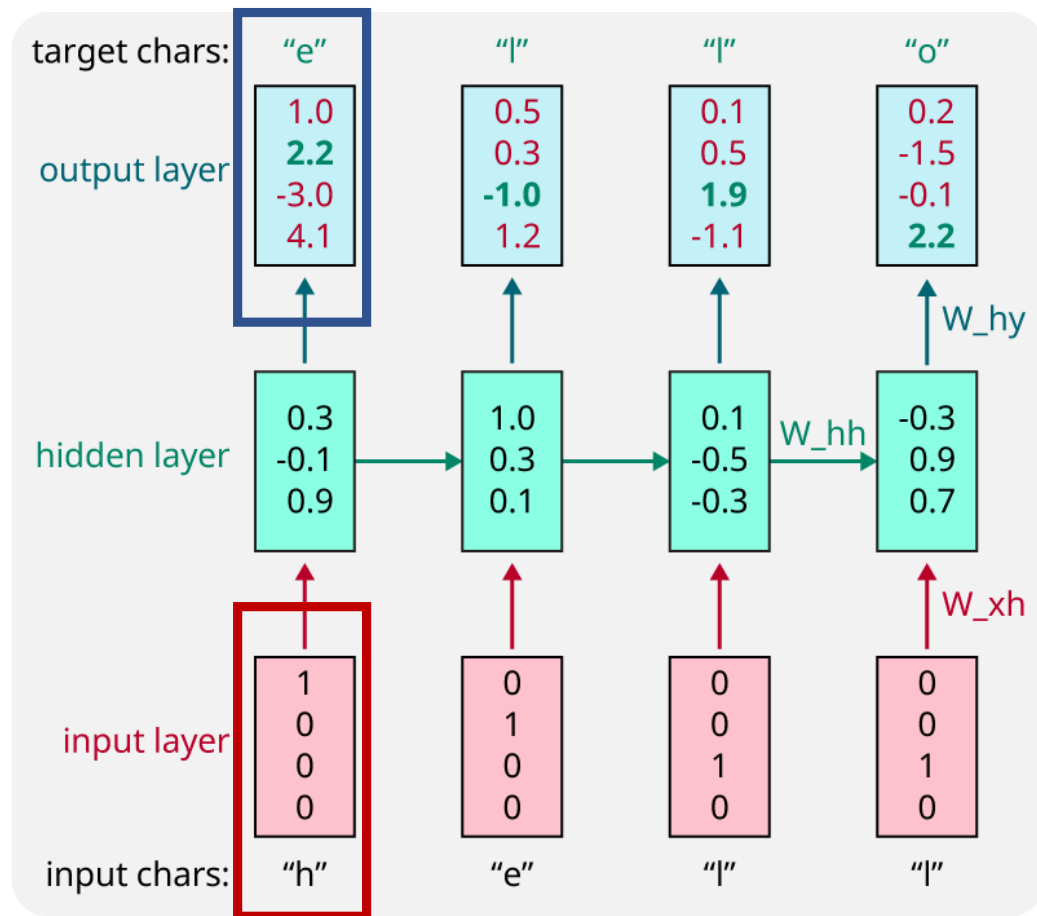
# Example: Character-level Language Modelling



**Task:** Given characters at time 1, 2, ..., t, predicts the next character (at time t+1)

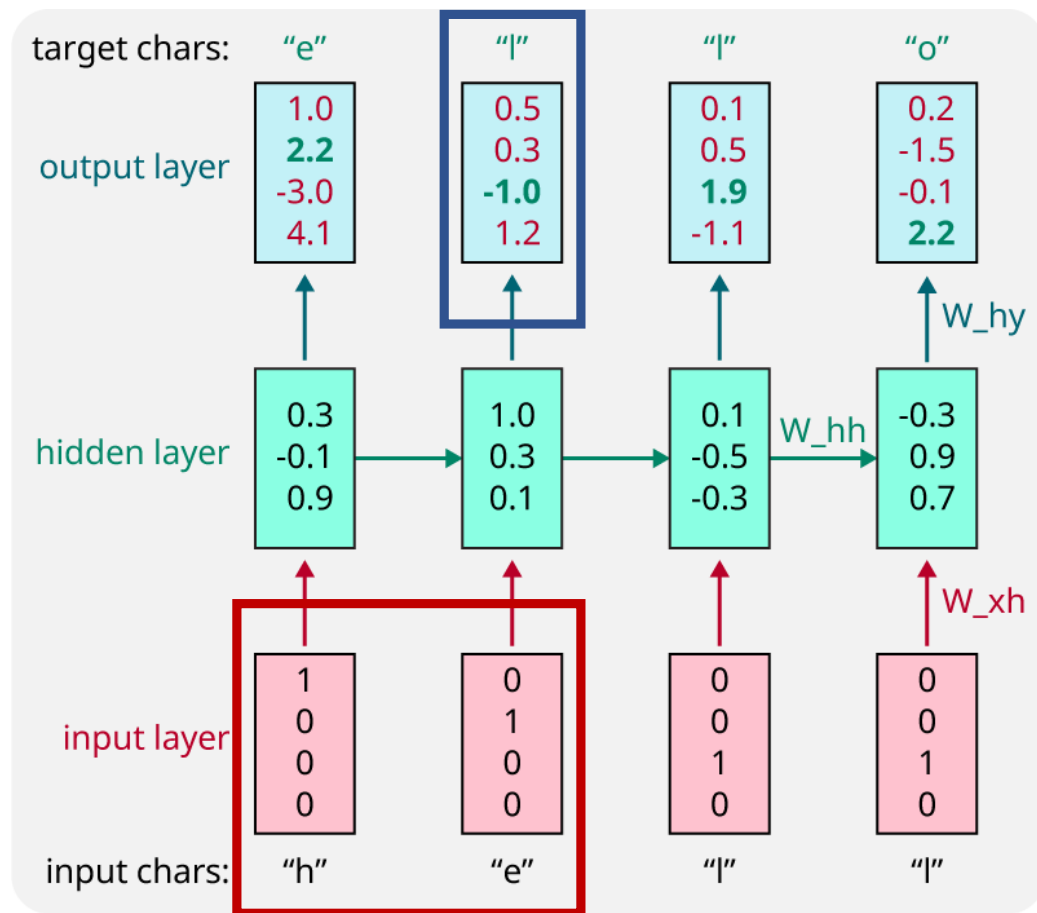
Example from: <http://karpathy.github.io/2015/05/21/rnn-effectiveness/>

Given "h", target output: "e"



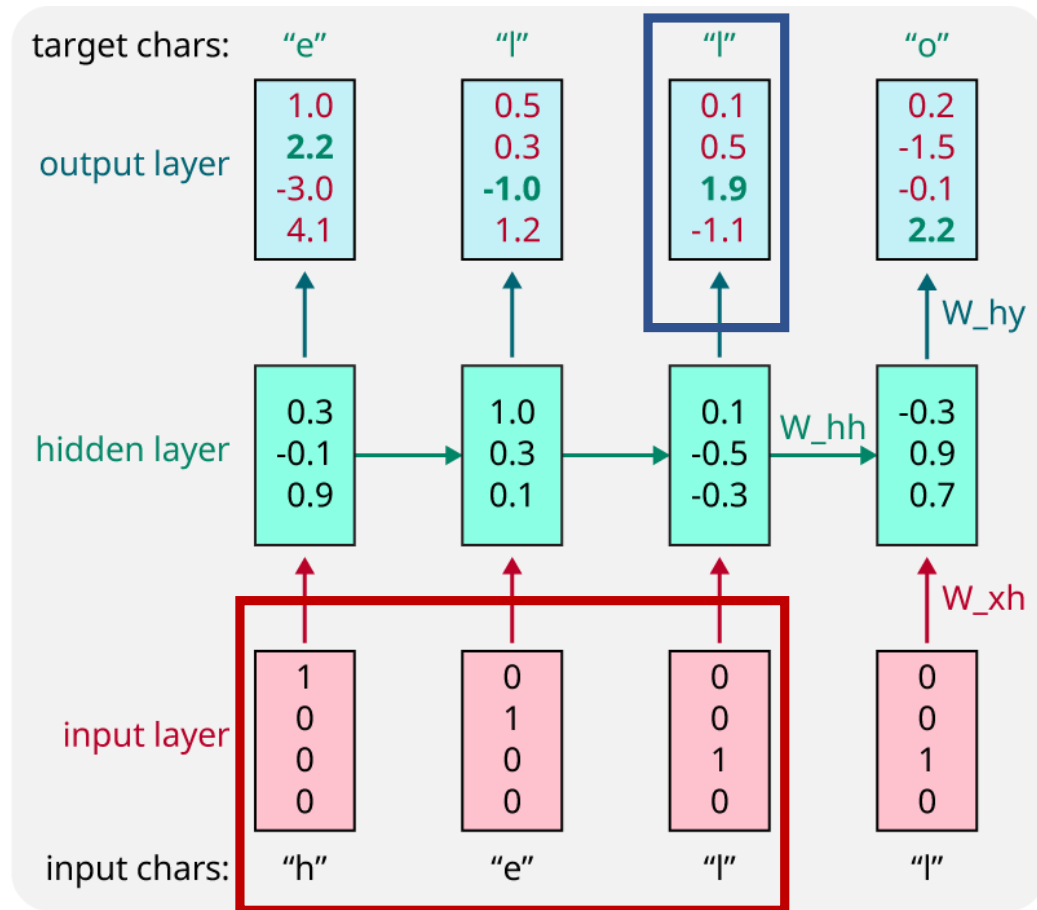
**Task:** Given characters at time 1, 2, ..., t, predicts the next character (at time t+1)

Given "he", target output: "l"



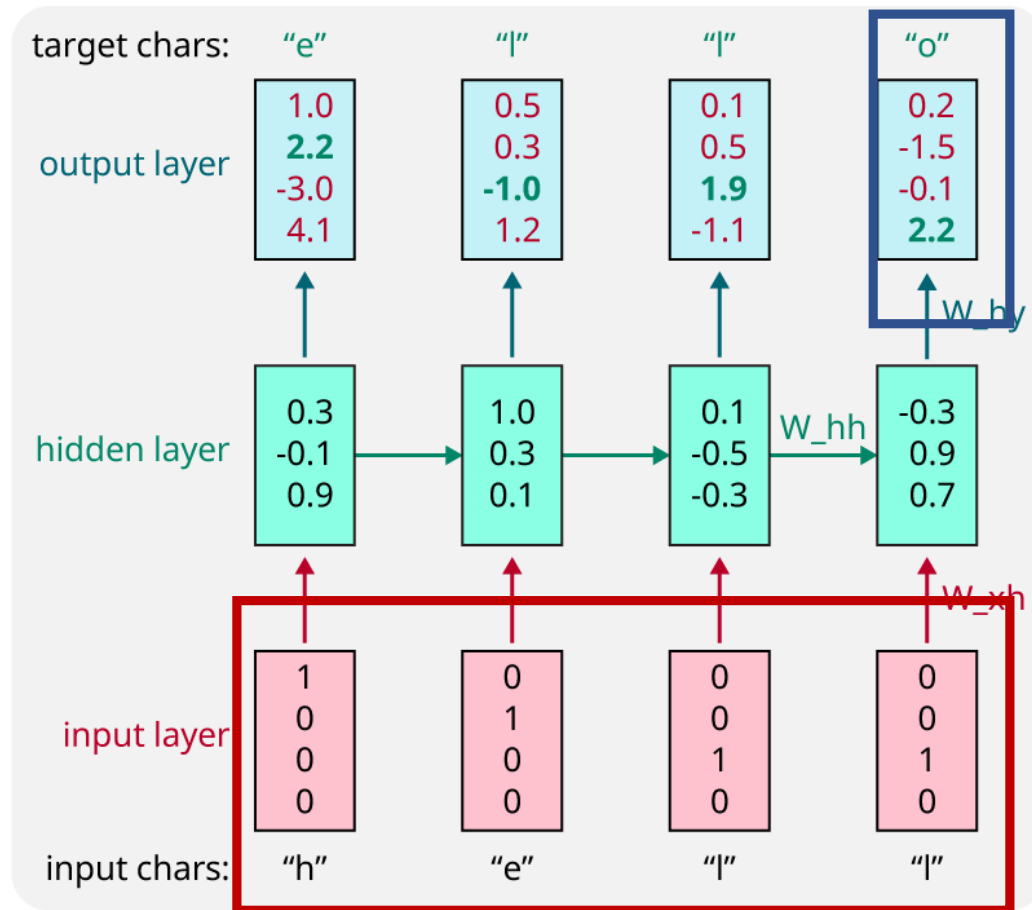
**Task:** Given characters at time 1, 2, ..., t, predicts the next character (at time t+1)

Given "hel", target output: "l"



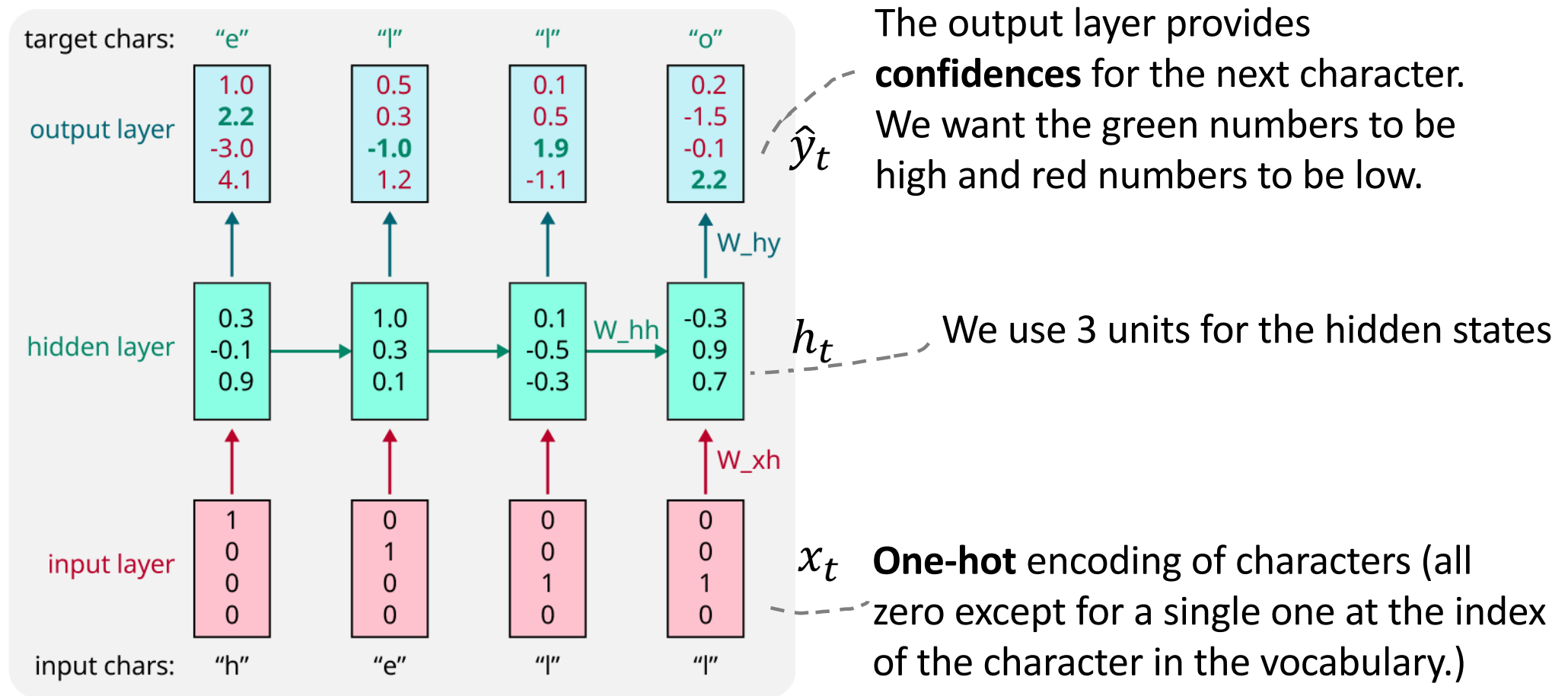
**Task:** Given characters at time 1, 2, ..., t, predicts the next character (at time t+1)

Given "hell", target output: "o"

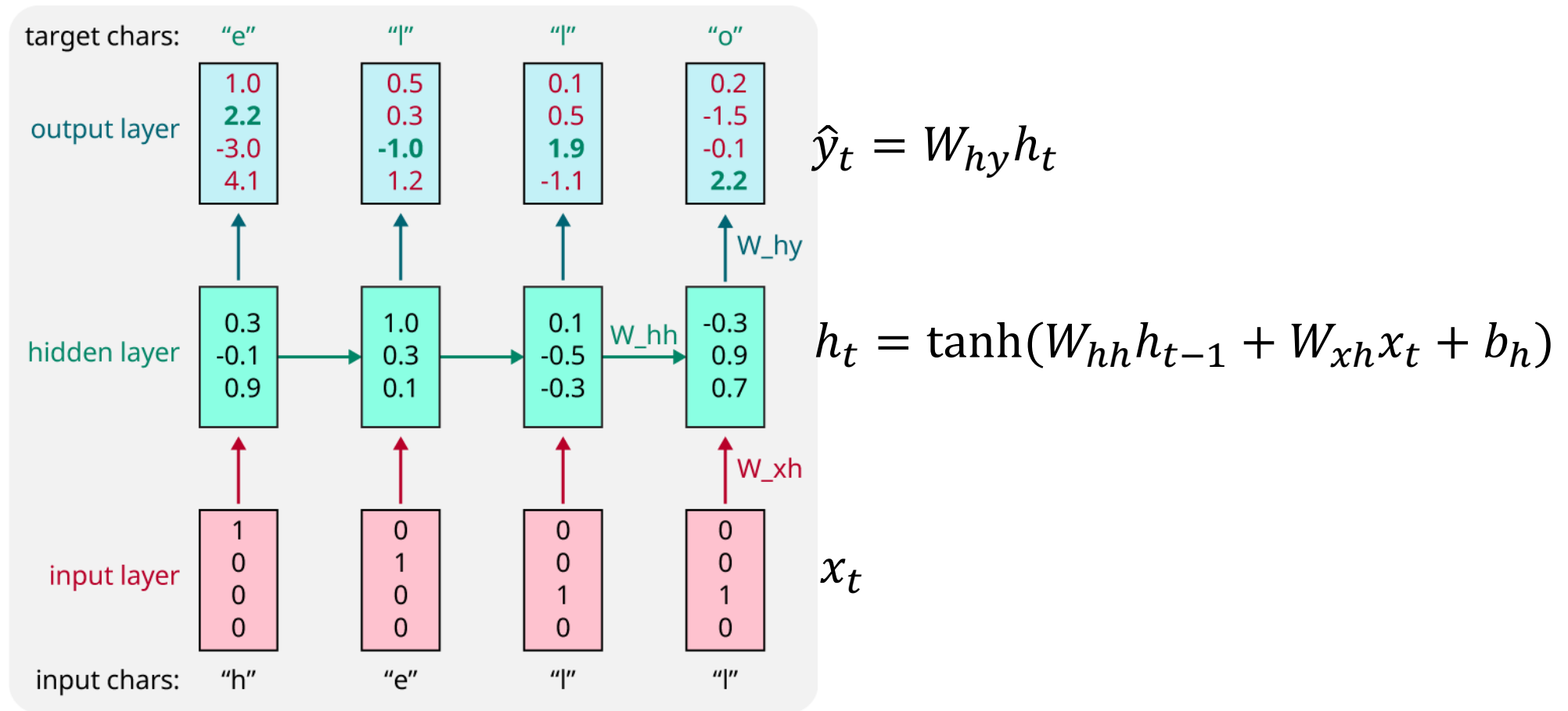


**Task:** Given characters at time 1, 2, ..., t, predicts the next character (at time t+1)

# Example: Character-level Language Modelling

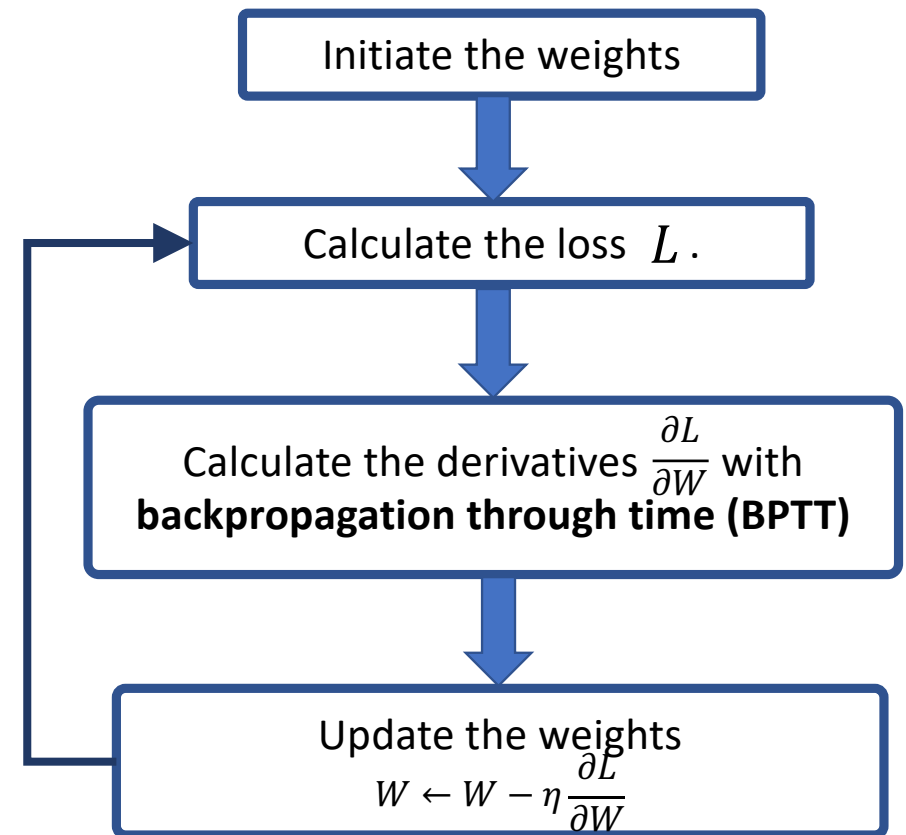
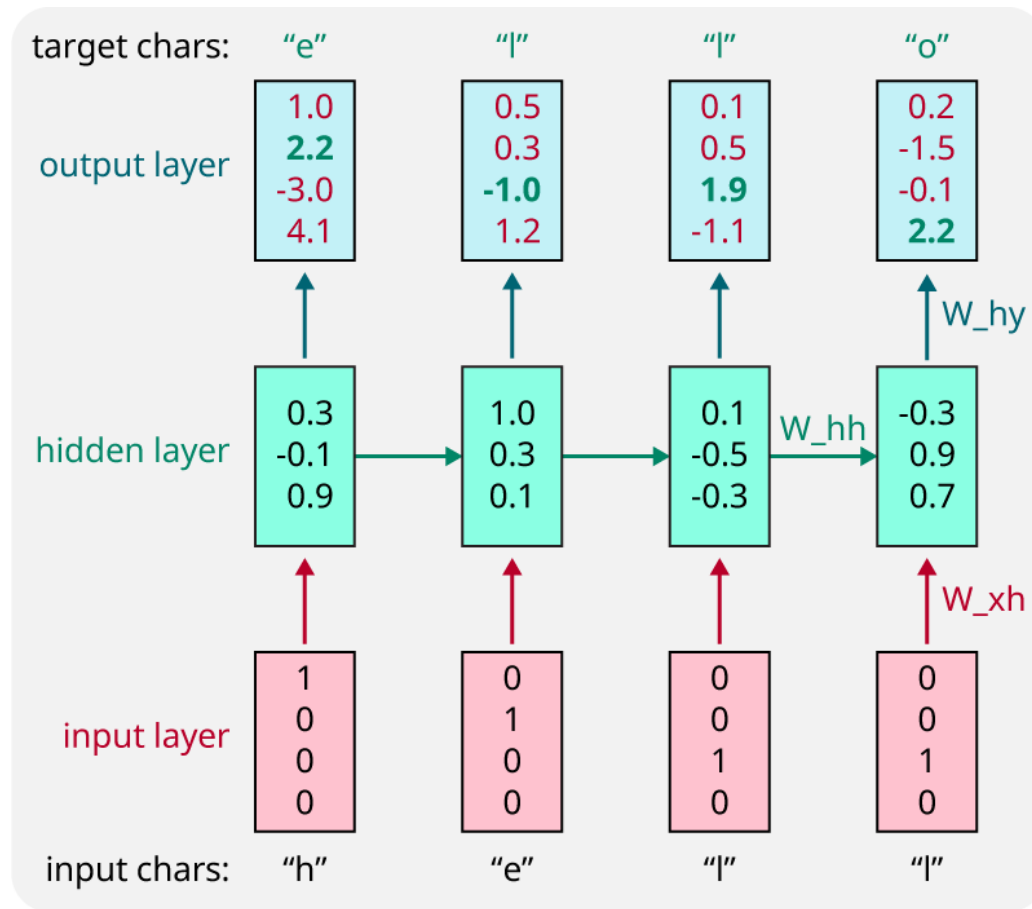


# Example: Character-level Language Modelling





# Training process

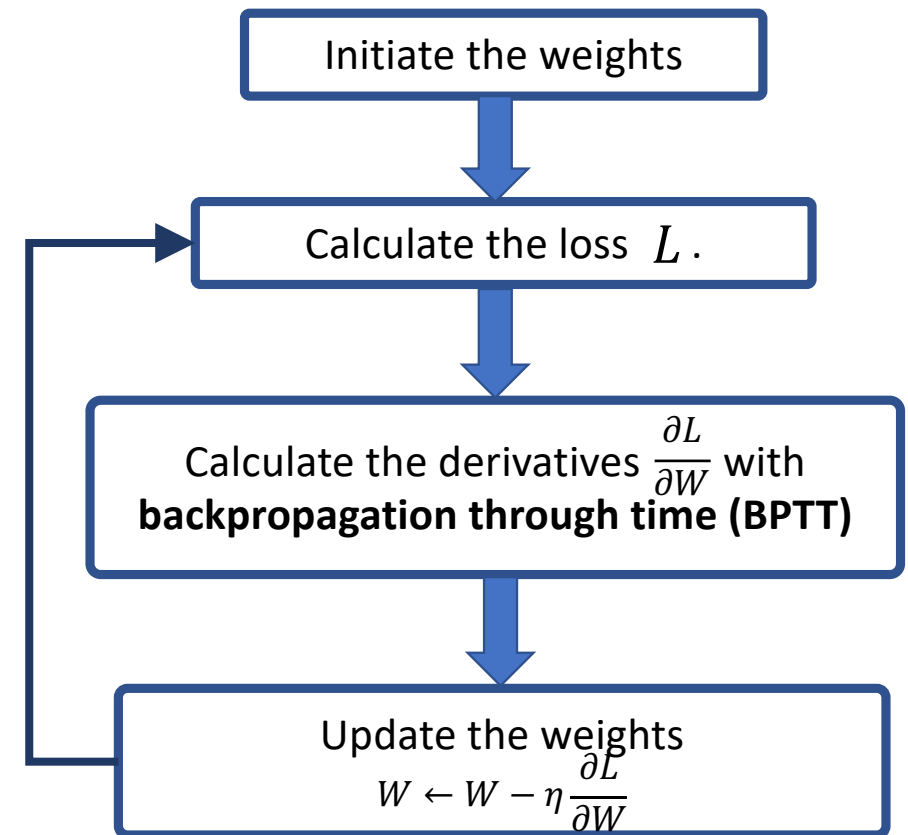
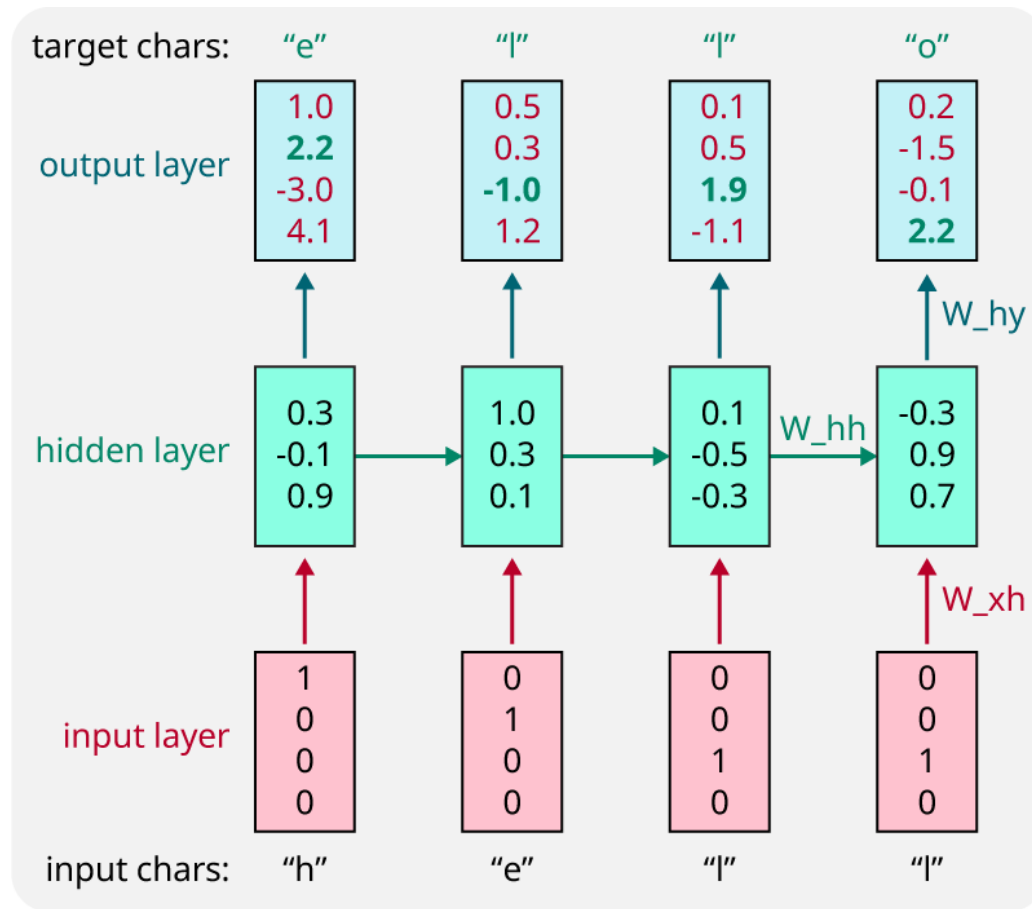


# Reference for Topic 3

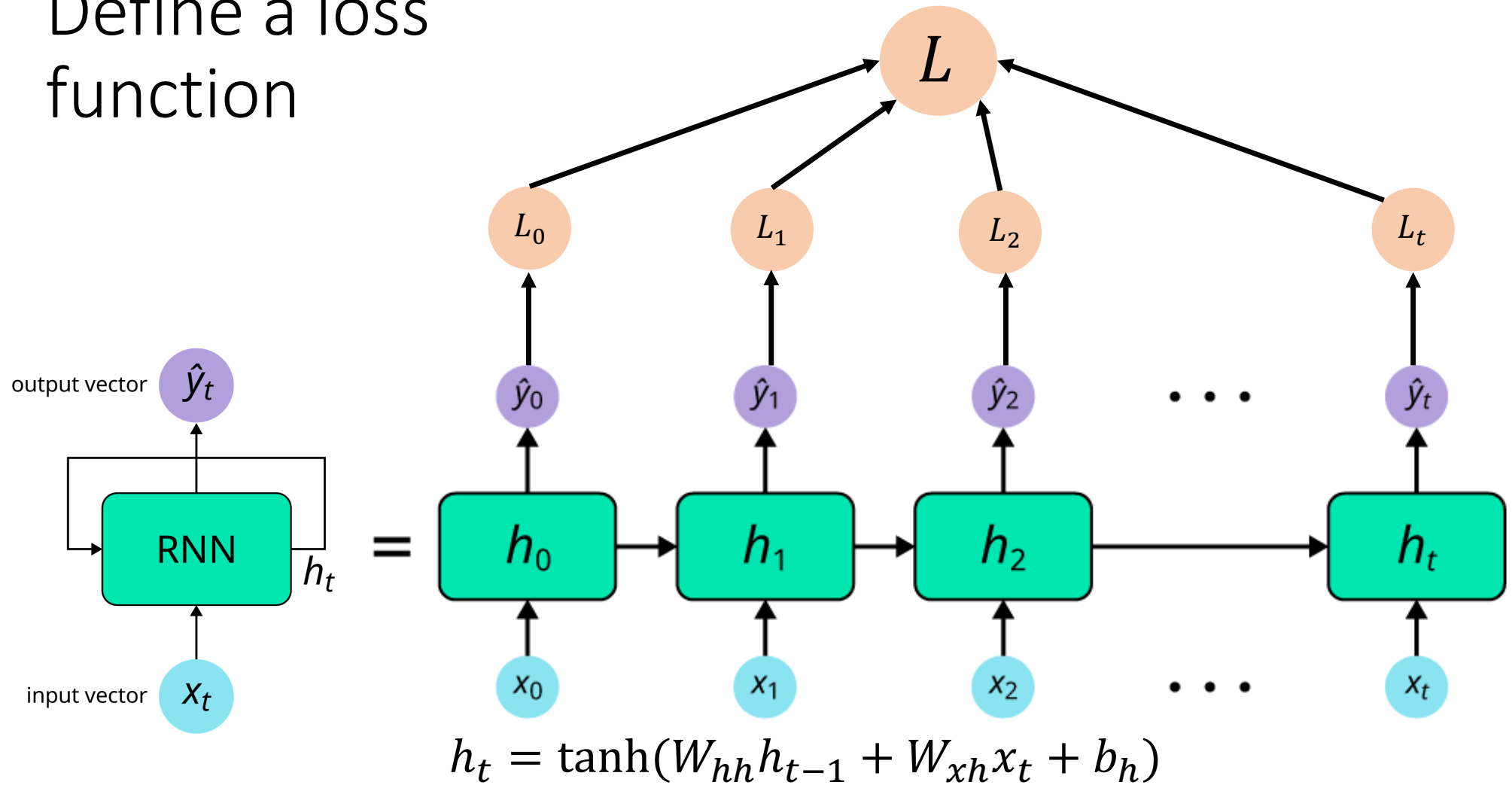
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# Topic 4: Backpropagation Through Time (BPTT)

# Training process

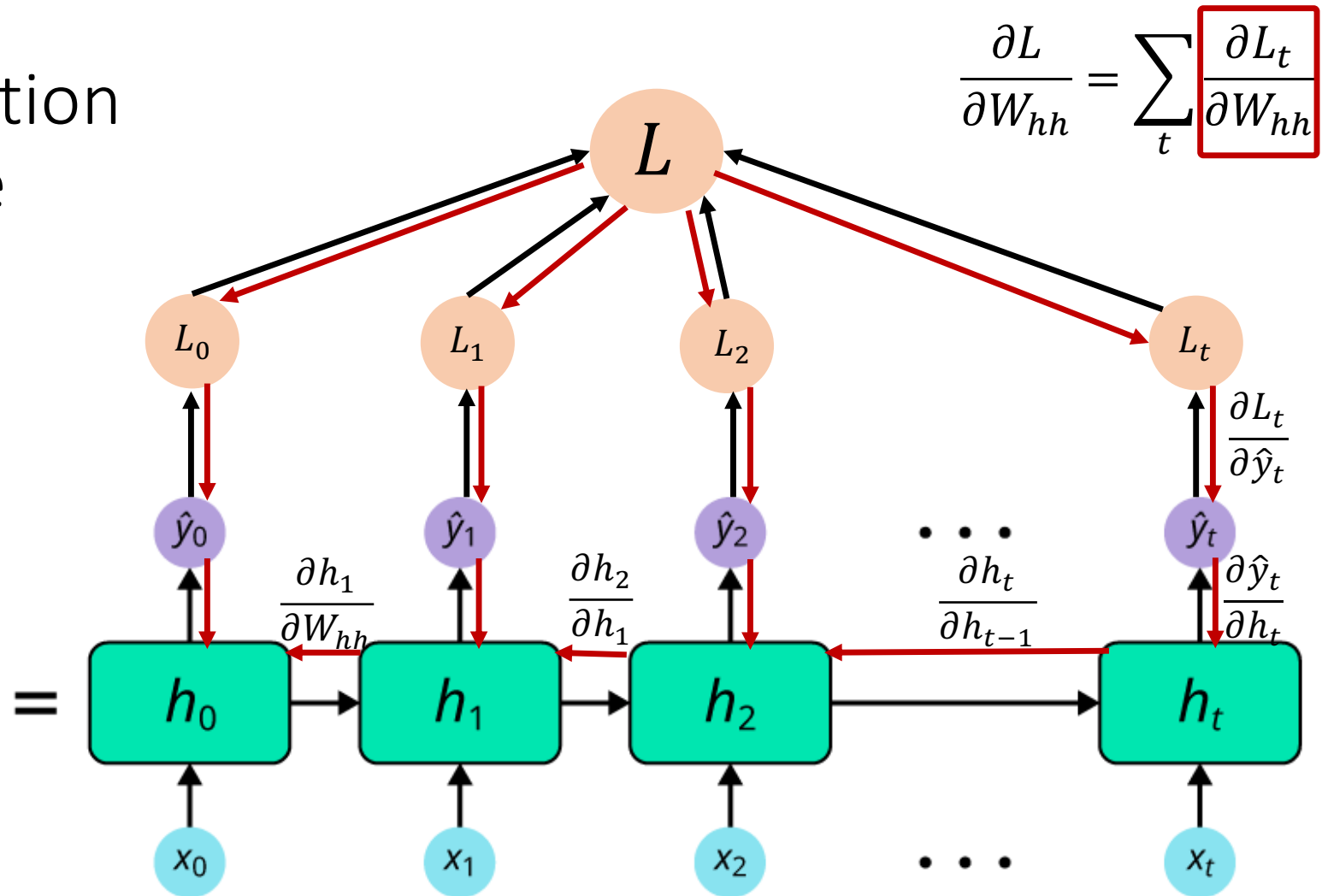
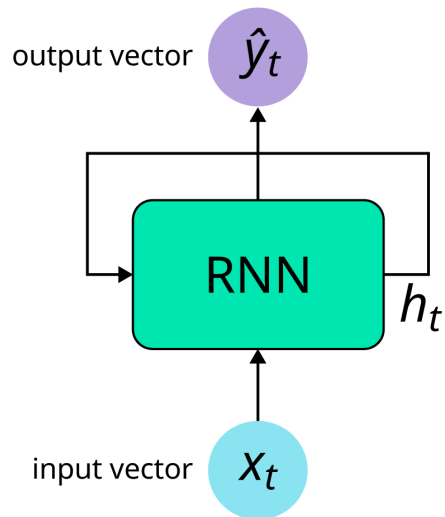


Define a loss function



# Backpropagation through time (BPTT)

→ Forward pass  
 ← Backward pass



$$h_t = \tanh(W_{hh}h_{t-1} + W_{xh}x_t + b_h)$$

See Weberna's blog for detailed equations: <https://weberna.github.io/blog/2017/11/15/LSTM-Vanishing-Gradients.html>

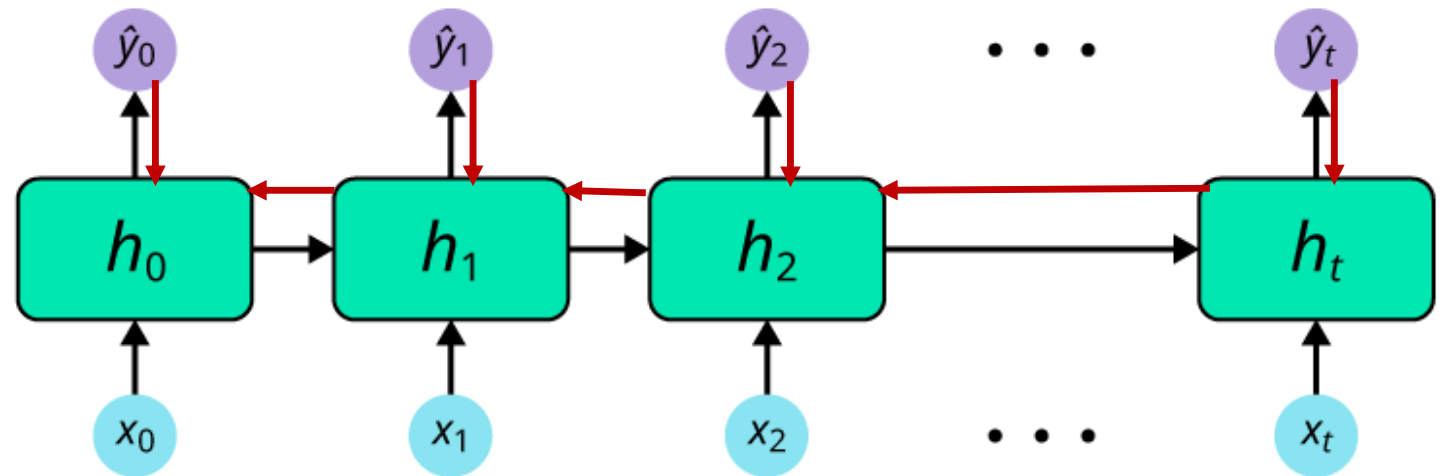
# RNN gradient flow

Many values  $> 1$ :  
**exploding gradients**

**Gradient clipping:** scale big gradients

Computing the gradient  
wrt  $W$  involves  
multiplying many factors

Many values  $< 1$ :  
**vanishing gradients**



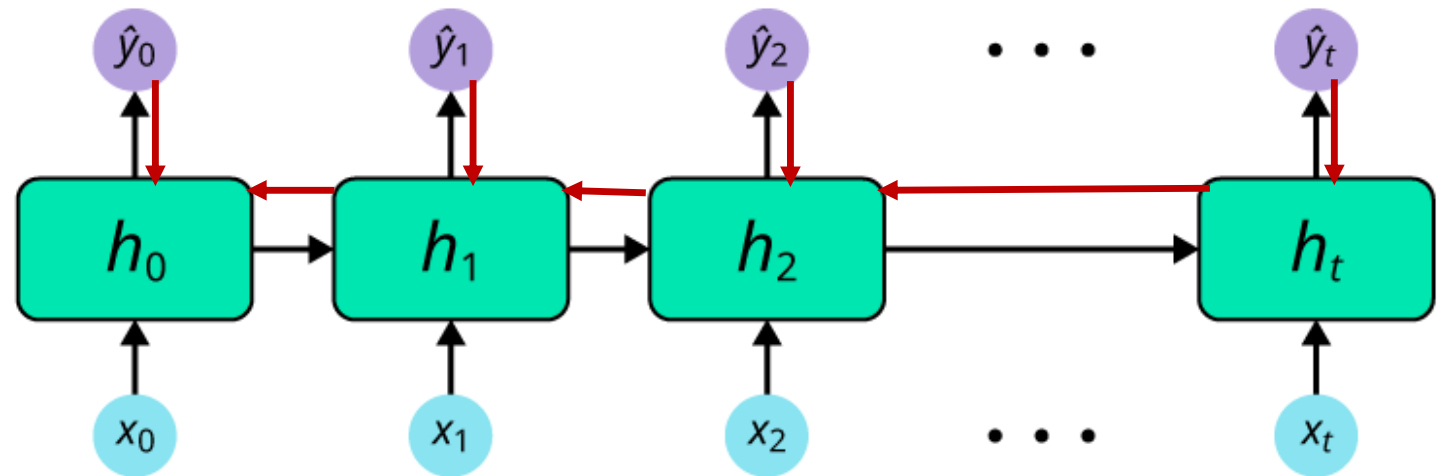
# RNN gradient flow

Many values  $> 1$ :  
**exploding gradients**

Computing the gradient  
wrt  $W$  involves  
multiplying many factors

Many values  $< 1$ :  
**vanishing gradients**

Change RNN architecture

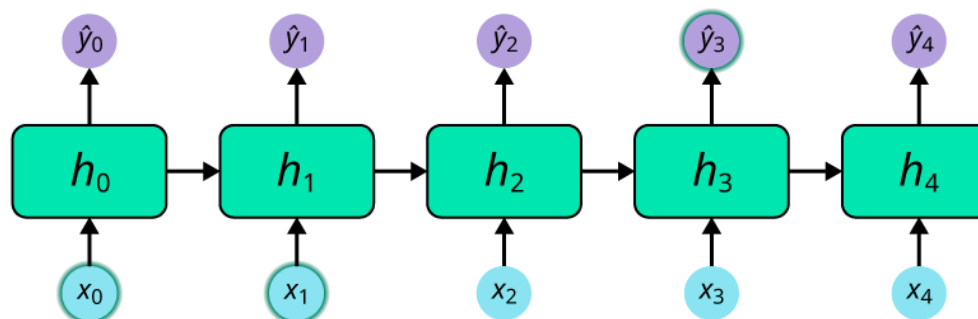




# The vanishing gradient problem

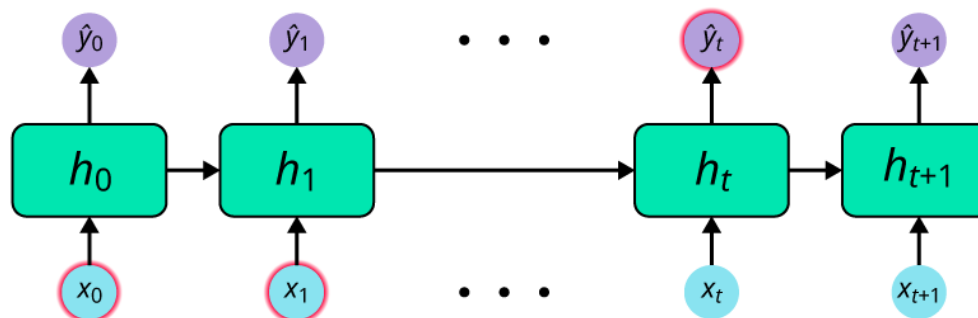
- Short term dependencies:

May I have some water to drink




- Long term dependencies:

It started raining. Mia still played in the garden, with her cloth all wet



Standard RNNs have **difficulties in modelling long-term dependencies** because of vanishing gradient problem.

# Solutions

- Key idea: use a **more complex recurrent unit** with **gates** to control the flow of information.
  - Long Short Term Memory (LSTM)  **Next topic**
    - ❑Sepp Hochreiter et al., “Long short-term memory”, 1997.
  - Gated Recurrent Units (GRU)
    - ❑Cho et al “Learning phrase representations using RNN encoder-decoder for statistical machine translation”, 2014

# Reference for Topic 4

- Video lecture by Alexander Amini: MIT course on Recurrent Neural Networks, YouTube.
- Blog by Denny Brits: <http://www.wildml.com/2015/10/recurrent-neural-networks-tutorial-part-3-backpropagation-through-time-and-vanishing-gradients/>
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