

$$\Rightarrow 3) S = \frac{c}{4\pi} |\vec{E}|^2 \vec{n} =$$

$$= \frac{c^2}{4\pi c^3 R^2} |n \times [n \times \dot{V} J J]|^2 = \frac{c^2}{4\pi c^3 R^2} \dot{V}^2 \sin^2 \theta$$

$$1) E \cdot 2\pi r h = 4\pi Q$$

$$(E + dE_r) 2\pi (r + dr) h = 4\pi \int_{r+dr}^r \rho dV$$

$$E_{r+dr} 2\pi (r + dr) h = 4\pi (Q + dQ)$$

$$d(E_{r+dr}) 2\pi h = 4\pi dQ$$

$$dQ = 2\pi r dr \cdot h \cdot \rho$$

$$\frac{1}{r} \frac{d(Er)}{dr} = 4\pi \rho = \nabla \cdot \vec{E} = \nabla \cdot (\nabla \phi) = \Delta \phi =$$

$$= \frac{1}{r} \frac{d}{dr} \left(r \frac{d\phi}{dr} \right)$$

$$\Delta \phi = \frac{1}{r} \frac{d}{dr} \left(r \frac{d\phi}{dr} \right)$$

$$\Rightarrow (dS)^2 = \overbrace{\cos^2 \varphi d\rho^2 + \sin^2 \varphi d\varphi^2 - 2 \sin \varphi \cos \varphi d\rho d\varphi}^{dx^2}$$

$$+ \overbrace{\sin^2 \varphi d\rho^2 + \cos^2 \varphi d\varphi^2 + 2 \sin \varphi \cos \varphi d\rho d\varphi}^{dy^2} + dz^2$$

$$= d\rho^2 + \rho^2 d\varphi^2 + dz^2$$

$$(2) \quad H = \nabla \times A$$

$$\nabla \times A = -\frac{1}{c} \nabla \left(\frac{e}{R} \frac{\partial R}{\partial t} \right) \times \bar{V} + \frac{1}{c} \left(\frac{e}{R} \frac{\partial R}{\partial t} \right) (\nabla \times \bar{V})$$

$$\nabla \times A = \frac{1}{c} (\varphi (\nabla \times \bar{V}) - \bar{V} \times (\nabla \varphi))$$

$$\cancel{\nabla \varphi} \quad \text{und} \quad \cancel{\nabla \times \bar{V}} \quad \text{aufgrund der Identität}$$

$$\nabla \times \bar{V} = \nabla \epsilon_r - \dot{V} \cdot \nabla \epsilon_r$$

$$\nabla \times A = -\frac{1}{c} (\dot{V} \times \nabla \epsilon_r) \varphi + \bar{V} \times (\nabla \varphi)$$

$\nabla \epsilon_r$ u. $\nabla \varphi$ mit normierten Vektoren.

$$\nabla \epsilon_r = -\frac{\bar{n}}{c} \gamma$$

$$\nabla \varphi = -\frac{e}{R^2} \gamma (\bar{n} \gamma + \frac{\gamma V}{c} - \frac{\bar{n} \gamma}{c^2} [R \dot{V} - V^2])$$

folglich:

$$\nabla \times A = -\frac{1}{c} \frac{\bar{R}}{c^3 R^3} \gamma^3 \times \left[\cancel{c \gamma \dot{V}} + (R \cdot \dot{V}) V + (c^2 - V^2) (c \bar{n} - \bar{V}) \right] = -\frac{1}{c} \frac{\bar{n}}{c^3 R^2} \gamma^3 \times$$

$$\times [c R \dot{V} - \dot{V} (R \bar{V}) + \bar{V} (R \dot{V})] + (c^2 - V^2) (c \bar{n} - \bar{V})$$

$$= -\frac{1}{c} \frac{\bar{n}}{c^3 R^2} \gamma^3 \times [c R \dot{V} + (c^2 - V^2) (c \bar{n} - \bar{V}) + \bar{R} \times [\bar{V} \times \dot{V}]]$$

$$= -\frac{1}{c} \bar{n} \times E$$

$$ii) \quad \vec{V}_1 = \frac{4V_0}{T} \left(0; \frac{T}{2}\right); \quad \vec{V}_2 = -\frac{4V_0}{T} \left(\frac{T}{2}, T\right)$$

$$S = \frac{c}{4\pi} |\vec{E}|^2 \vec{n} = \frac{e^2}{4\pi c^3 R^2} \dot{V}^2 \sin^2 \theta =$$

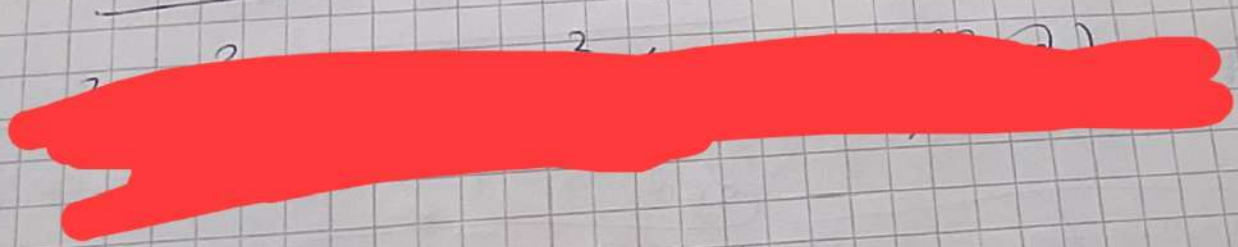
$$= \frac{e^2}{4\pi c^3 R^2} \left(\frac{4V_0}{T}\right)^2 \sin^2 \theta = S = \frac{dP}{R^2 d\Omega}$$

~~$\frac{dP}{d\Omega}$~~

$$\int dP = \int \frac{e^2}{4\pi c^3} \left(\frac{4V_0}{T}\right)^2 \sin^2 \theta d\Omega =$$

$$= \frac{e}{4\pi c^2} \left(\frac{4V_0}{T}\right)^2 \int_S \sin^3 \theta d\theta d\varphi =$$

$$= \frac{2}{3} \frac{e^2}{c^3} \dot{V}^2 \cdot \left(\frac{4V_0}{T}\right)^2 \left(\frac{d m}{c}\right)$$



$$5) \quad r_0(t) = v \cdot t$$

$$|R| = |r - r_0(t)| = c(t - t')$$

$$r^2 - 2\vec{r} \cdot \vec{v} t' + v^2 t'^2 = c^2(t^2 - 2t t' + t'^2)$$

$$r^2 - 2\vec{r} \cdot \vec{v} t' + v^2 t'^2 = c^2(t^2 - 2t t' + t'^2)$$

$$R(1 - \frac{\vec{r} \cdot \vec{v}}{c}) = c(t - t') \left[1 - \frac{v}{c} \frac{(r - vt')}{c(t - t')} \right] =$$

$$= c(t - t') - \frac{\vec{r} \cdot \vec{v}}{c} + \frac{v^2}{c} t' = \frac{1}{c}$$

$$= \frac{1}{c} [c^2 t - \vec{r} \cdot \vec{v} - (c^2 - v^2) t']$$

$$r_0(t) = v \cdot t' + v^2 t'$$

$$|R| = |r - r_0(t)| = c(t - t')$$

$$r^2 - 2\vec{r} \cdot \vec{v} t' + v^2 t'^2 = c^2(t^2 - 2t t' + t'^2)$$

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$$(t') = \frac{(c^2 t - \vec{r} \cdot \vec{v}) - \sqrt{(c^2 t - \vec{r} \cdot \vec{v})^2 + (c^2 - v^2)(r^2 - c^2 t^2)}}{c^2 - v^2}$$

$$R(1 - \frac{\vec{r} \cdot \vec{v}}{c}) = \frac{1}{c} \sqrt{(c^2 t - \vec{r} \cdot \vec{v})^2 + (c^2 - v^2)(r^2 - c^2 t^2)}$$

$$R = \frac{1}{c} \sqrt{(c^2 t - \vec{r} \cdot \vec{v})^2 + (c^2 - v^2)(r^2 - c^2 t^2)}$$

$$\begin{aligned}
& (c^2 t - \vec{r} \cdot \vec{V})^2 + (c^2 - v^2)(r^2 - c^2 t^2) = \\
& = -2c^2(\vec{r} \cdot \vec{V}t) + (\vec{r} \cdot \vec{V})^2 + (c^2 - v^2)r^2 + c^2/v^2 \\
& = -2c^2(\vec{r} \cdot [\vec{r} - \vec{R}]) + (\vec{r} \cdot \vec{V})^2 + (c^2 - v^2)r^2 + \\
& + c^2/(\vec{r} - \vec{R})^2 = \\
& = -2c^2 r^2 + 2c^2 \vec{r} \cdot \vec{R} + (\vec{r} \cdot \vec{V})^2 + c^2 r^2 - \vec{V}^2 r^2 + c^2 r^2 \\
& - 2c^2 \vec{r} \cdot \vec{R} + c^2 R^2 = (\vec{r} \cdot \vec{V})^2 - v^2 r^2 + c^2 R^2 = \\
& = (cR + v\cancel{t}) \cdot \vec{V}^2 - v^2 [R + v\cancel{t}]^2 + c^2 R^2 = \\
& = (\vec{R} \cdot \vec{V})^2 + 2(\vec{R} \cdot \vec{V})v^2 \cancel{t} + v^4 \cancel{t}^2 - v^2 R^2 - \\
& - 2\cancel{t}v^2(\vec{R} \cdot \vec{V}) - v^4 \cancel{t}^2 + (cR)^2 = \\
& = (R^2 v^2 \cos^2 \theta) + (c\cancel{t})^2 - \cancel{t}^2 - v^2 R^2 = \\
& = -R^2 v^2 (\cancel{t}^2 - 1 - \cos^2 \theta) + (cR)^2 = \\
& = \underline{c^2 R^2 \left(1 - \frac{v^2}{c^2} \sin^2 \theta\right)}
\end{aligned}$$

$$\begin{aligned}
R \left(1 - \frac{\vec{r} \cdot \vec{V}}{c}\right) &= \\
&= \cancel{t} R \sqrt{1 - \frac{v^2}{c^2} \sin^2 \theta}
\end{aligned}$$

$$\cancel{E} = \frac{e c \left(1 - \frac{v^2}{c^2}\right)}{\cancel{R}^3 \left(1 - \frac{\vec{r} \cdot \vec{V}}{c}\right)^3} \cdot (\vec{R} - \frac{v}{c} \cancel{t}) =$$

$$\frac{e}{\cancel{R}^3 \left(1 - \frac{v^2}{c^2} \sin^2 \theta\right)^{3/2}} \cdot \vec{R} \cancel{t}$$

$$\begin{aligned}
\vec{R} - \frac{v}{c} \cancel{t} &= \\
&= \vec{R} - v\cancel{t} = \vec{R}^*
\end{aligned}$$