

# Université Paris-Est Créteil (UPEC)

International Master of Biometrics and Intelligent Vision

## 3D BRAIN MRI FEATURE EXTRACTION

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**FACULTÉ DES SCIENCES  
ET TECHNOLOGIE**

# OUTLINE

## 1. Introduction

## 2. Methods and materials

- Image intensities exploration on 3D volume
- Applying masks
- Applying filters

## 3. Conclusion

# INTRODUCTION

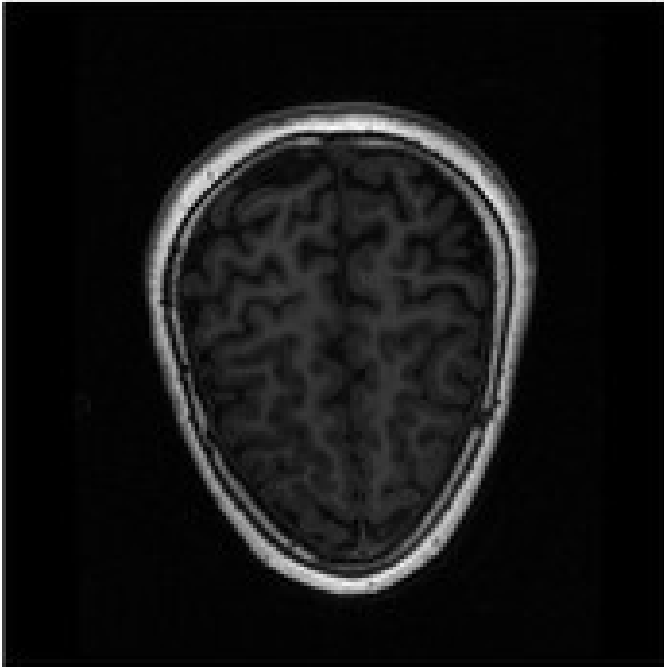
- **Feature extraction** : extract relevant information from an image for medical image analysis;
- 3D brain MRI absorption is highest in dense tissue;

## OBJECTIVES

- Exploit intensity patterns to create a binary mask and apply it to a 3D brain MRI;
- Using convolutional filters to detect interesting features;

# METHODS AND MATERIALS (1)

## IMAGE INTENSITIES EXPLORATION ON 3D VOLUME



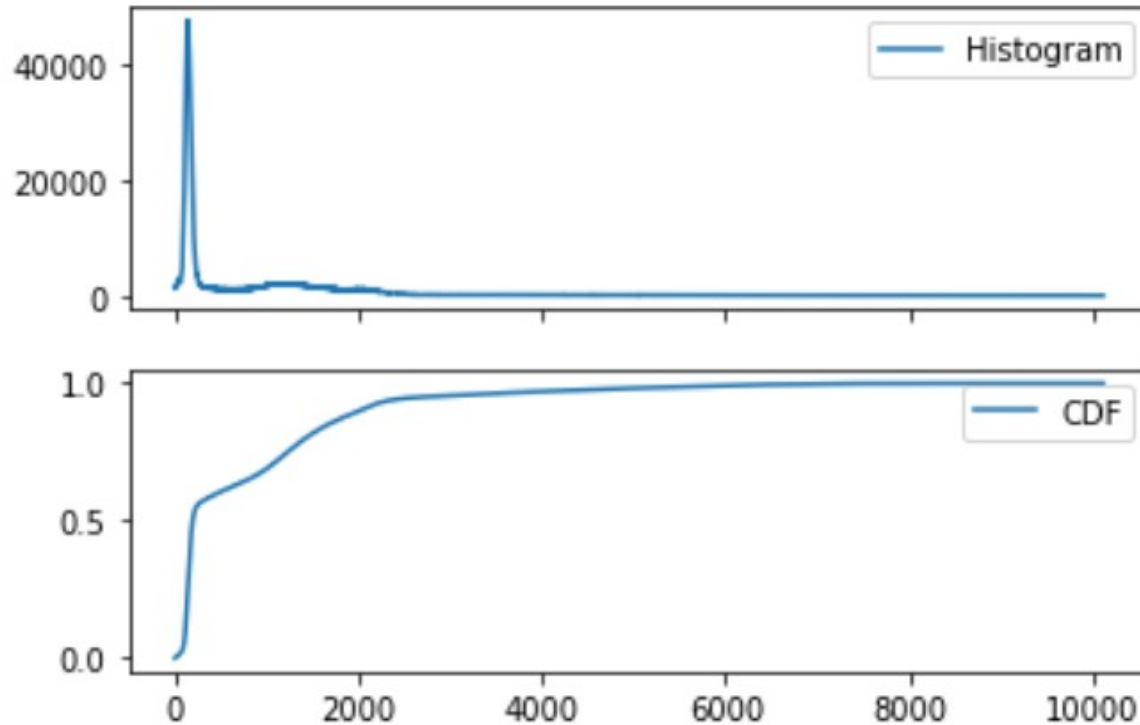
- Loading the image using nibabel `get_fdata()` function;

```
print('[INFOS] Data type           :', im.dtype)
print('[INFOS] Min. intensity value :', im.min())
print('[INFOS] Mean intensity value :', np.round(im.mean(),2))
print('[INFOS] Max. intensity value :', im.max())
print('[INFOS] Size of data          :', im.size)
print('[INFOS] Image data shape      :', im.shape)
```

```
[INFOS] Data type           : int16
[INFOS] Min. intensity value : 0
[INFOS] Mean intensity value : 535.65
[INFOS] Max. intensity value : 10106
[INFOS] Size of data          : 10878976
[INFOS] Image data shape      : (166, 256, 256)
```

# METHODS AND MATERIALS (2)

## HISTOGRAM AND CDF



- Histogram counts the number of pixels at each intensity value;
- Distribution is skewed toward low intensities;
- Cumulative distribution function (CDF) shows proportion of pixels in range;
- 1200 in x-axis could separate distribution;
- **maskHead = im>1200**

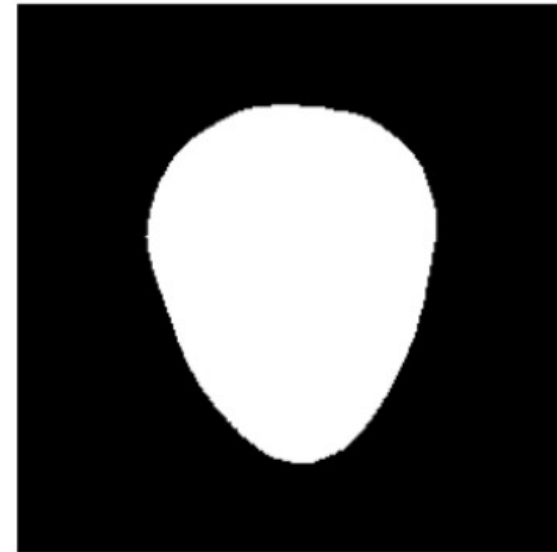
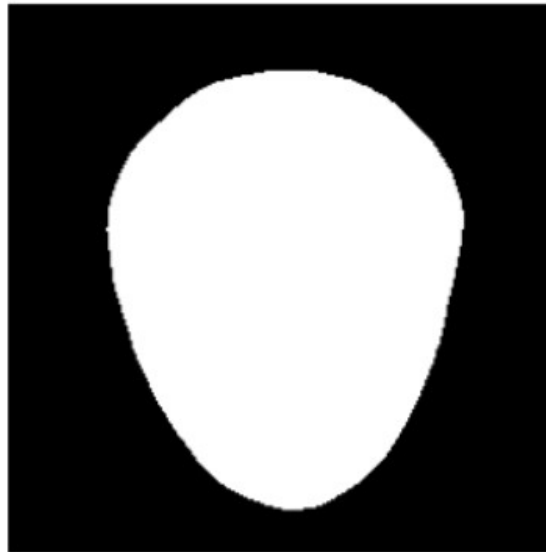
```
# Create a histogram, binned at each possible value
hist = ndi.measurements.histogram(im, min=0, max=10106, bins=10107)

# Create a cumulative distribution function
cdf = hist.cumsum()/hist.sum()
```

# METHODS AND MATERIALS (3)

## APPLYING MASKS

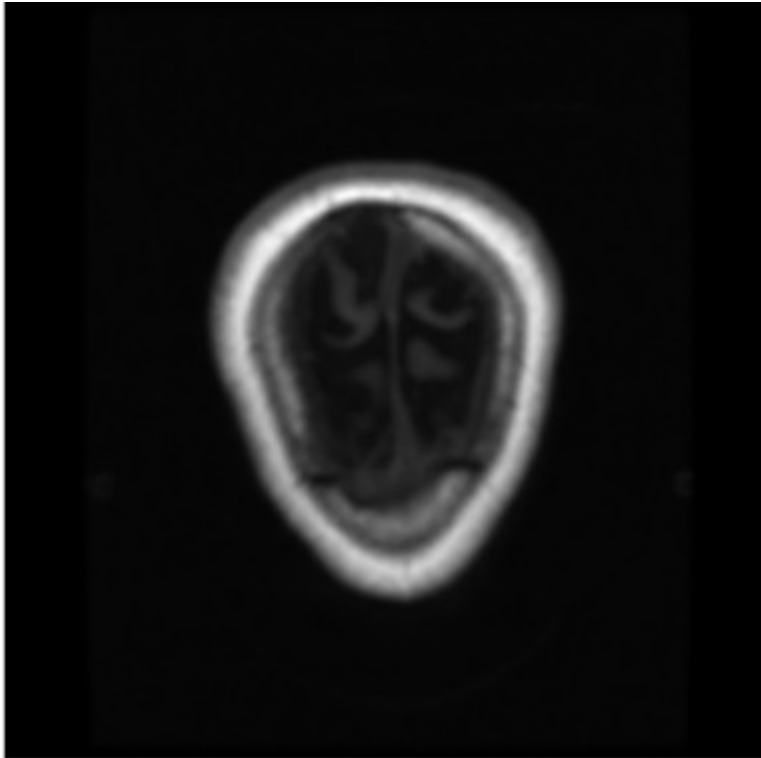
```
imHead = np.where(maskHead, im, 0)
imHead = ndi.binary_dilation(imHead, iterations=8)
imHead = ndi.binary_closing(imHead, iterations=8)
viewPlot(imHead)
```



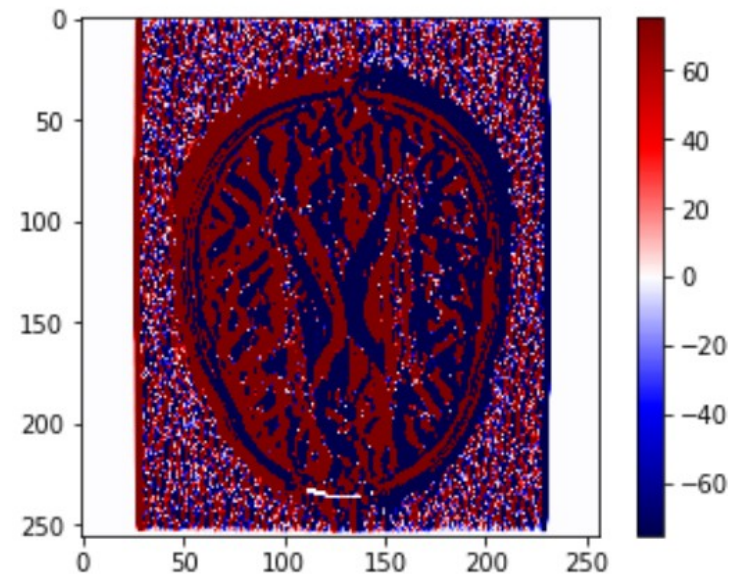
# METHODS AND MATERIALS (4)

## APPLYING FILTERS

```
w = 0.11 * np.ones([3,3,3])  
imFilt = ndi.convolve(im, w)
```



```
k = np.zeros([3, 3, 3])  
k[0] = np.array([[1, 0, -1], [1, 0, -1], [1, 0, -1]])  
k[1] = np.array([[1, 0, -1], [1, 0, -1], [1, 0, -1]])  
k[2] = np.array([[1, 0, -1], [1, 0, -1], [1, 0, -1]])  
  
imEdge = ndi.convolve(im, k)
```



# CONCLUSION

- Exploiting intensities patterns helps us selecting sub-region of an array for feature extraction;
- Using convolutional filter enabled the detection of interesting feature such as edges;
- Scipy's ndimage module has been the main package used for this lab;



# THANKS FOR YOUR ATTENTION

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# METHODS AND MATERIALS (1)

## IMAGE INTENSITIES EXPLORATION ON 3D VOLUME

