An introduction to Shallow Water Equations

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Master 2 CEPS, Marseille January - March 2021

Practical informations

• Lectures with me, TP with Thierry Gallouët

- Evaluation
 - ▶ 1/3* CC + 2/3*Exam
 - ightharpoonup CC = TP + Project

Mathematics and fluid mechanics - Motivations

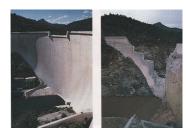


- nearshore hydrodynamics
 - coastal morpho-dynamics and erosion
 - flood-risk prevention

Mathematics and fluid mechanics - Motivations

• hydroelectric dam

wave energy converters





Mathematics and fluid mechanics - More complex flows

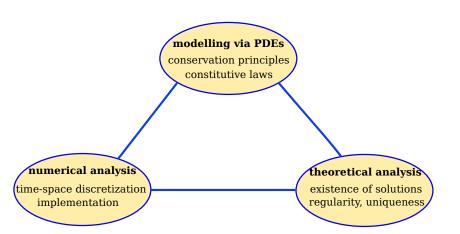
avalanches



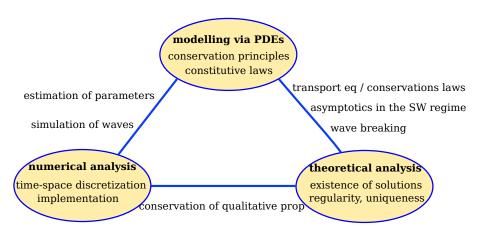
pyroclastic flows



Mathematics and Fluid Mechanics



Shallow Water (SW) equations



Outline

Classical fluid equations and the Shallow Water regime

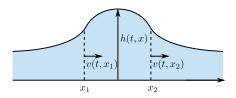
- Theoretical analysis of the Saint-Venant system
 - Classical (regular) solutions
 - Weak solutions

Numerical approximation of the solutions of the Saint-Venant system

Modelling fluid systems

and the Shallow Water regime

Modelling water waves in shallow water - first approach



• conservation of the volume of fluid between x_1 and x_2

$$\frac{\mathrm{d}}{\mathrm{d}t} \int_{x_1}^{x_2} h(t,x) \, \mathrm{d}x = h(t,x_1) v(t,x_1) - h(t,x_2) v(t,x_2)$$

$$\implies \int_{x_1}^{x_2} \partial_t h(t, x) \, \mathrm{d}x = - \int_{x_1}^{x_2} \partial_x (hv) \, \mathrm{d}x \qquad \forall \ x_1, \ x_2$$

conservation law

$$\partial_t h + \partial_x (hv) = 0$$

• we close the system with an ad hoc **velocity law** v = v(h) = h

$$\implies \left| \frac{\partial_t h}{\partial_x (h^2)} = 0 \right| \quad \underline{\text{Burgers equation}}$$

Macroscopic modelling - variables describing the flow

velocity:

- Eulerian standpoint: let t be a given observation time, $\mathbf{x} \in \mathbb{R}^d$ a given position $u(t, \mathbf{x}) \in \mathbb{R}^d$ is the average velocity of the fluid particle located at \mathbf{x} at time t
- Lagrangian standpoint: given a fluid particle located at position \mathbf{y} at t=0, we define its trajectory (or characteristics) $t\mapsto X_{\mathbf{y}}(t)$ and the Lagrangian velocity $U(t,\mathbf{y})$

$$U(t, \mathbf{y}) = \frac{\mathrm{d} \mathbf{X}_{\mathbf{y}}(\mathbf{t})}{\mathrm{d} \mathbf{t}} = \mathbf{u}(\mathbf{t}, \mathbf{X}_{\mathbf{y}}(\mathbf{t}))$$

density:

 $\rho(t, \mathbf{x}) \in \mathbb{R}$ represents the nb of micro. elements in the fluid particle located at (t, \mathbf{x}) we shall assume that the density of the fluid is constant

Other possible variables: temperature, salinity, etc.

Conservation principles - Constitutive laws

• Conservation of mass for any $\omega \subset \Omega$, we denote n the outer normal to $\partial \omega$

$$\frac{\mathrm{d}}{\mathrm{d}t} \left(\int_{\omega} \rho \, \mathrm{d}x \right) = - \int_{\partial \omega} \rho \, \left(u \cdot \mathbf{n} \right) \mathrm{d}\sigma \underset{\mathsf{Green-Ostrogradsky}}{=} - \int_{\omega} \, \mathrm{div} \left(\rho \mathbf{u} \right) \mathrm{d}x$$

recall: let
$$u = (u^1, \dots, u^n)$$
, div $u = \sum_{i=1}^d \frac{\partial}{\partial x_i} u^i$

 \rightarrow local conservation of mass $\partial_t \rho + \operatorname{div}(\rho u) = 0$

if $\rho \equiv \operatorname{cst} \leadsto \operatorname{incompressibility condition} \mid \operatorname{div} u = 0$

• Balance of momentum: expression of Newton's second law

$$\rho\Big(\partial_t u + (u \cdot \nabla)u\Big) = \operatorname{div} \mathbb{T} + \rho f$$

 \mathbb{T} : Cauchy stress, internal forces acting on the fluid f: external forces

other formulation (using the mass conservation):

$$\partial_t(\rho u) + \operatorname{div}(\rho u \otimes u) = \operatorname{div} \mathbb{T} + \rho f$$

Constitutive laws:

$$\mathbb{T} = 2\mu D(u) + (\lambda \operatorname{div} u - p) \operatorname{Id}$$

where
$$D(u) = \frac{\nabla u + (\nabla u)^T}{2} \in \mathbb{R}^d \times \mathbb{R}^d$$
, μ, λ are the viscosities of the fluid $p = p(\rho)$ is the pressure of the fluid (ex: $p(\rho) = a\rho^{\gamma}$)

Incompressible Navier-Stokes (/ Euler) equations

$$\begin{cases} \operatorname{div} u = 0 \\ \partial_t u + (u \cdot \nabla)u + \nabla \bar{p} - 2\nu \operatorname{div} (D(u)) = f \end{cases}$$

incompressible Euler system if the viscosity $\nu=\frac{\mu}{\rho}=0$

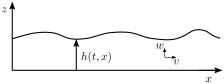
 \bar{p} : Lagrange multiplier associated to the incompressibility constraint $\operatorname{div} u = 0$ in the following, we shall assume that only gravity acts on the fluid

2D Free surface flows, u = (v, w)

$$\partial_x v + \partial_z w = 0 \qquad \leftarrow \text{ incomp. constraint}$$

$$\partial_t v + \partial_x v^2 + \partial_z (wv) + \partial_x \bar{p} - 2\nu \partial_{xx} v - \nu \partial_{zz} v - \nu \partial_{xz} w = 0 \qquad \leftarrow x\text{-momentum eq}$$

$$\partial_t w + \partial_x (vw) + \partial_z w^2 + \partial_z \bar{p} - \nu \partial_{xz} v - \nu \partial_{xx} w - 2\nu \partial_{zz} w = -g \qquad \leftarrow z\text{-momentum eq}$$



Boundary conditions

• at the bottom z=0:

- ▶ no-penetration $w_{|z=0} = 0$
- ▶ wall-law (Navier's condition with no friction) $\partial_z v_{|z=0} + \partial_x w_{|z=0} = 0$
- continuity of the stress tensor at z=h: $(2\nu D(u)-p \text{ Id}).\mathbf{n}=-p_{\mathrm{atm}}\mathbf{n}$ where \mathbf{n} is the unit outward normal to the surface: $\mathbf{n}=\frac{1}{\sqrt{1+(\partial_v h)^2}}\begin{pmatrix} -\partial_x h \\ 1 \end{pmatrix}$

2D Free surface flows, u = (v, w)

Boundary conditions

- at the bottom z = 0:
 - ▶ no-penetration $w_{|z=0} = 0$
 - wall-law (Navier's condition with no friction) $\partial_z v_{|z=0} + \partial_x w_{|z=0} = 0$
- at the free surface z = h(t, x):

$$\begin{cases} (\bar{p}_{|z=h} - p_{\mathrm{atm}})\partial_x h + \nu \left(\partial_z v_{|z=h} + \partial_x w_{|z=h} - 2\partial_x v_{|z=h}\partial_x h\right) = 0 \\ \bar{p}_{|z=h} - p_{\mathrm{atm}} + \nu \left(\partial_z v_{|z=h}\partial_x h + \partial_x w_{|z=h}\partial_x h - 2\partial_z w_{|z=h}\right) = 0 \end{cases}$$

Conservation of mass

We introduce the indicator function of the fluid region

$$\varphi(t, x, z) = \begin{cases} 1 & \text{if } z \in [0, h(t, x)] \\ 0 & \text{otherwise} \end{cases}$$

• the fluid is transported at velocity u = (v, w)

$$\partial_t \varphi + v \partial_x \varphi + w \partial_z \varphi = 0 \Longrightarrow_{\text{incomp. cond.}} \left[\partial_t \varphi + \partial_x (v \varphi) + \partial_z (w \varphi) = 0 \right]$$

• integration over $z \in [0, +\infty[$

$$0 = \int_0^\infty \partial_t \varphi \, dz + \int_0^\infty \left[\partial_x (v\varphi) + \partial_z (w\varphi) \right] dz$$
$$= \partial_t \left(\int_0^\infty \varphi \, dz \right) + \partial_x \left(\int_0^\infty (v\varphi) \, dz \right) - \underbrace{[w\varphi]_{|z=0}}_{=0}$$
$$= \partial_t h + \partial_x \left(\int_0^{h(t,x)} v \, dz \right)$$

$$\boxed{\partial_t h + \partial_x (h \bar{v}) = 0} \quad \text{with} \quad \bar{v}(t, x) = \frac{1}{h(t, x)} \left(\int_0^{h(t, x)} v(t, z) \, \mathrm{d}z \right)$$

Kinematic condition at the free surface

Coming back to the transport equation satisfied by φ

$$\partial_t \varphi + \partial_x (v\varphi) + \partial_z (w\varphi) = 0$$

• integration over the height of the fluid $z \in [0, h(t, x)]$

$$0 = \int_{0}^{h(t,x)} \partial_{t} \varphi \, dz + \int_{0}^{h(t,x)} \left[\partial_{x} (v\varphi) + \partial_{z} (w\varphi) \right] dz$$

$$= \partial_{t} \left(\int_{0}^{h(t,x)} \varphi \, dz \right) - \partial_{t} h \, \varphi_{|z=h} + \partial_{x} \left(\int_{0}^{h(t,x)} v \, dz \right)$$

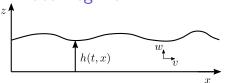
$$- \left[v\varphi \right]_{|z=h} \partial_{x} h + \left[w\varphi \right]_{|z=h} - \underbrace{\left[w\varphi \right]_{|z=0}}_{=0}$$

$$= \underbrace{\partial_{t} h + \partial_{x} (h\overline{v})}_{=0} - \partial_{t} h - v_{|z=h} \partial_{x} h + w_{|z=h}$$

$$\partial_t h + v_{|z=h} \partial_x h - w_{|z=h} = 0$$
 kinema

kinematic equation

Scaling - Shallow water regime



 \bullet H: characteristic height of the flow, L: characteristic length in the x-direction

$$\varepsilon := \frac{H}{L} \ll 1$$

• other characteristic dimensions (recall that the density is equal to 1)

$$V, \quad W = \varepsilon V, \quad T = \frac{L}{V}, \quad P = V^2$$

dimensionless quantities

$$\widetilde{v} = \frac{v}{V}, \quad \widetilde{w} = \frac{w}{W}, \quad \widetilde{x} = \frac{x}{L}, \quad \widetilde{z} = \frac{z}{H}, \quad \widetilde{t} = \frac{t}{T}, \quad \widetilde{p} = \frac{p}{P}$$

characteristic numbers: Reynolds nb $\mathrm{Re} := \frac{VL}{\nu}$, Froude nb $\mathrm{Fr} := \frac{V}{\sqrt{gH}}$

Shallow water regime - rescaled Navier-Stokes equations

$$\begin{split} \partial_{\widetilde{x}}\widetilde{v} + \partial_{\widetilde{z}}\widetilde{w} &= 0 \\ \partial_{\widetilde{t}}\widetilde{v} + \partial_{\widetilde{x}}\widetilde{v}^2 + \partial_{\widetilde{z}}\big(\widetilde{w}\widetilde{v}\big) + \partial_{\widetilde{x}}\widetilde{p} &= \frac{1}{\mathrm{Re}}\left(2\partial_{xx}v + \frac{1}{\varepsilon^2}\partial_{\widetilde{z}\widetilde{z}}\widetilde{v} + \partial_{\widetilde{x}\widetilde{z}}\widetilde{w}\right) \\ \varepsilon\Big(\partial_{\widetilde{t}}\widetilde{w} + \partial_{\widetilde{x}}\big(\widetilde{v}\widetilde{w}\big) + \partial_{\widetilde{z}}\widetilde{w}^2\Big) + \frac{1}{\varepsilon}\partial_{\widetilde{z}}\widetilde{p} &= -\frac{1}{\varepsilon\mathrm{Fr}^2} + \frac{1}{\varepsilon\mathrm{Re}}\left(\partial_{x\widetilde{z}}\widetilde{v} + \varepsilon^2\partial_{x\widetilde{x}}\widetilde{w} + 2\partial_{\widetilde{z}\widetilde{z}}\widetilde{w}\right) \end{split}$$

Boundary conditions

- at the bottom $\tilde{z} = 0$:
 - ▶ no-penetration $\widetilde{w}_{|\widetilde{z}=0} = 0$
 - wall-law (Navier's condition with no friction) $\frac{1}{\varepsilon}\partial_{\widetilde{z}}\widetilde{v}_{|\widetilde{z}=0} + \varepsilon\partial_{\widetilde{x}}\widetilde{w}_{|\widetilde{z}=0} = 0$
- at the free surface z = h(t, x):

$$\begin{cases} \varepsilon(\tilde{p}_{|z=h} - p_{\text{atm}})\partial_{\tilde{x}}\tilde{h} + \frac{1}{\text{Re}}\left(\frac{1}{\varepsilon}\partial_{\tilde{z}}\tilde{v}_{|\tilde{z}=\tilde{h}} + \varepsilon\partial_{\tilde{x}}\tilde{w}_{|\tilde{z}=\tilde{h}} - 2\varepsilon\partial_{\tilde{x}}\tilde{v}_{|\tilde{z}=\tilde{h}}\partial_{\tilde{x}}\tilde{h}\right) = 0\\ \tilde{p}_{|z=h} - p_{\text{atm}} + \frac{1}{\text{Re}}\left(\partial_{\tilde{z}}\tilde{v}_{|\tilde{z}=\tilde{h}}\partial_{\tilde{x}}\tilde{h} + \varepsilon^{2}\partial_{\tilde{x}}\tilde{w}_{|\tilde{z}=\tilde{h}}\partial_{\tilde{x}}\tilde{h} - 2\partial_{\tilde{z}}\tilde{w}_{|\tilde{z}=\tilde{h}}\right) = 0 \end{cases}$$

Shallow water regime - rescaled Navier-Stokes equations

we drop all the $\widetilde{\,\cdot\,}$

$$\begin{split} \partial_x v + \partial_z w &= 0 \\ \partial_t v + \partial_x v^2 + \partial_z (wv) + \partial_x p &= \frac{1}{\mathrm{Re}} \left(2 \partial_{xx} v + \frac{1}{\varepsilon^2} \partial_{zz} v + \partial_{xz} w \right) \\ \varepsilon^2 \Big(\partial_t w + \partial_x (vw) + \partial_z w^2 \Big) + \partial_z p &= -\frac{1}{\mathrm{Fr}^2} + \frac{1}{\mathrm{Re}} \left(\partial_{xz} v + \varepsilon^2 \partial_{xx} w + 2 \partial_{zz} w \right) \end{split}$$

Boundary conditions

- at the bottom z = 0:
 - ▶ no-penetration $w_{|z=0} = 0$
 - wall-law $\partial_z v_{|z=0} + \varepsilon^2 \partial_x w_{|z=0} = 0$
- at the free surface z = h(t, x):

$$\left\{ \begin{array}{l} (p_{|z=h}-p_{\mathrm{atm}})\partial_x h + \frac{1}{\mathrm{Re}} \Big(\frac{1}{\varepsilon^2}\partial_z v_{|z=h} + \partial_x w_{|z=h} - 2\partial_x v_{|z=h}\partial_x h \Big) = 0 \\ p_{|z=h}-p_{\mathrm{atm}} + \frac{1}{\mathrm{Re}} \Big(\partial_z v_{|z=h}\partial_x h + \varepsilon^2 \partial_x w_{|z=h}\partial_x h - 2\partial_z w_{|z=h} \Big) = 0 \end{array} \right.$$

Shallow water regime - hydrostatic pressure

• z-momentum equation and conditions at the free surface

$$\begin{split} & \varepsilon^{2} \Big(\partial_{t} w + \partial_{x} (vw) + \partial_{z} w^{2} \Big) + \partial_{z} p = -\frac{1}{\operatorname{Fr}^{2}} + \frac{1}{\operatorname{Re}} \left(\partial_{xz} v + \varepsilon^{2} \partial_{xx} w + 2 \partial_{zz} w \right) \\ & \left\{ \begin{array}{l} (p_{|z=h} - p_{\operatorname{atm}}) \partial_{x} h + \frac{1}{\operatorname{Re}} \Big(\frac{1}{\varepsilon^{2}} \partial_{z} v_{|z=h} + \partial_{x} w_{|z=h} - 2 \partial_{x} v_{|z=h} \partial_{x} h \Big) = 0 \\ p_{|z=h} - p_{\operatorname{atm}} + \frac{1}{\operatorname{Re}} \Big(\partial_{z} v_{|z=h} \partial_{x} h + \varepsilon^{2} \partial_{x} w_{|z=h} \partial_{x} h - 2 \partial_{z} w_{|z=h} \Big) = 0 \end{array} \right. \end{split}$$

• neglecting the terms of order ε^2 :

$$\begin{cases} \partial_z p = -\frac{1}{\operatorname{Fr}^2} + \frac{1}{\operatorname{Re}} \left(\partial_{xz} v + 2 \partial_{zz} w \right) \\ \partial_z v_{|z=h} = 0 \\ p_{|z=h} - p_{\operatorname{atm}} - \frac{2}{\operatorname{Re}} \partial_z w_{|z=h} = 0 \end{cases}$$

Shallow water regime - hydrostatic pressure

$$\begin{cases} \partial_z p = -\frac{1}{\operatorname{Fr}^2} + \frac{1}{\operatorname{Re}} \left(\partial_{xz} v + 2 \partial_{zz} w \right) \\ \partial_z v_{|z=h} = 0 \\ \rho_{|z=h} - \rho_{\operatorname{atm}} - \frac{2}{\operatorname{Re}} \partial_z w_{|z=h} = 0 \end{cases}$$

• integration for ξ between h(t,x) and z

$$\begin{split} \rho(t,x,z) = & p(t,x,h) + \frac{1}{\operatorname{Fr}^2}(h-z) + \frac{1}{\operatorname{Re}} \int_h^z \partial_z \left(\partial_x v + 2 \partial_z w \right) \, \mathrm{d}\xi \\ = & p_{\operatorname{atm}} + \frac{2}{\operatorname{Re}} \partial_z w_{|\xi=h} + \frac{1}{\operatorname{Fr}^2}(h-z) + \frac{1}{\operatorname{Re}} \left(\partial_x v_{|\xi=z} - \partial_x v_{|\xi=h} \right) \\ & + \frac{2}{\operatorname{Re}} \left(\partial_z w_{|\xi=z} - \partial_z w_{|\xi=h} \right) \end{split}$$

• we finally use the incompressibility condition $\partial_z w = -\partial_x v$

$$\boxed{p(t,x,z) = p_{\rm atm} + \frac{1}{{\rm Fr}^2}(h-z) - \frac{1}{{\rm Re}} (\partial_x v_{|\xi=z} + \partial_x v_{|\xi=h})}$$

if we neglect the viscosity o usual hydrostatic pressure $p(t,x,z)=p_{\mathrm{atm}}+rac{1}{\Gamma_{\mathrm{P}}^2}(h-z)$

Vertical averaging of the x-momentum equation

$$\partial_t v + \partial_x v^2 + \partial_z (wv) + \partial_x p = \frac{1}{\mathrm{Re}} \left(2 \partial_{xx} v + \frac{1}{\varepsilon^2} \partial_{zz} v + \partial_{xz} w \right) \qquad \leftarrow \text{ x-mom. eq}$$

$$\partial_t h + \partial_x h \ v_{|z=h} - w_{|z=h} = 0 \qquad \leftarrow \text{ kinematic cond.}$$

$$(p_{|z=h} - p_{\mathrm{atm}}) \partial_x h + \frac{1}{\mathrm{Re}} \left(\frac{1}{\varepsilon^2} \partial_z v_{|z=h} + \partial_x w_{|z=h} - 2 \partial_x v_{|z=h} \partial_x h \right) = 0$$

$$w_{|z=0} = 0, \quad \partial_z v_{|z=0} + \varepsilon^2 \partial_x w_{|z=0} = 0 \qquad \leftarrow \text{ cond. at } z = 0$$

integration of the 1st eq between 0 and h using the boundary conditions

$$\begin{split} \partial_{t} \left(\int_{0}^{h} v \, \mathrm{d}z \right) &+ \partial_{x} \left(\int_{0}^{h} v^{2} \, \mathrm{d}z \right) + \left(\int_{0}^{h} \partial_{x} p \, \mathrm{d}z \right) - \frac{2}{\mathrm{Re}} \partial_{x} \left(\int_{0}^{h} \partial_{x} v \, \mathrm{d}z \right) \\ &= \partial_{t} h v_{|z=h} + \partial_{x} h \left(v_{|z=h} \right)^{2} - w_{|z=h} v_{|z=h} + w_{|z=0} v_{|z=0} \\ &+ \frac{1}{\mathrm{Re}} \left(-2 \partial_{x} h \partial_{x} v_{|z=h} + \frac{1}{\varepsilon^{2}} \partial_{z} v_{|z=h} + \partial_{x} w_{|z=h} \right) + \frac{1}{\mathrm{Re}} \left(\frac{1}{\varepsilon^{2}} \partial_{z} v_{|z=0} + \partial_{x} w_{|z=0} \right) \\ &= - \left(\rho_{|z=h} - \rho_{\mathrm{atm}} \right) \partial_{x} h \end{split}$$

Closure - The Saint-Venant system

$$\begin{cases} \partial_t h + \partial_x \left(\int_0^h v \, \mathrm{d}z \right) = 0 \\ \partial_t \left(\int_0^h v \, \mathrm{d}z \right) + \partial_x \left(\int_0^h v^2 \, \mathrm{d}z \right) + \left(\int_0^h \partial_x p \, \mathrm{d}z \right) \\ - \frac{2}{\mathrm{Re}} \partial_x \left(\int_0^h \partial_x v \, \mathrm{d}z \right) = -(p_{|z=h} - p_{\mathrm{atm}}) \partial_x h \end{cases}$$

• setting $\bar{v} = \frac{1}{h} \int_{\hat{r}}^{h} v \, dz$, the 1st equation rewrites

$$\partial_t h + \partial_x (h\bar{v}) = 0$$

- we assume that $\operatorname{Re} \sim \mathcal{O}(\varepsilon^{-1})$ (viscosity very small)
- from the x-momentum eq. + boundary cond. at z = h:

$$\partial_{zz}v = O(\varepsilon), \quad \partial_z v_{|z=\hbar} = O(\varepsilon)$$

$$\implies \partial_z v = O(\varepsilon) \implies v(t, x, z) = v(t, x, 0) + O(\varepsilon)$$

$$v(t,x,z) = \bar{v}(t,x) + O(\varepsilon)$$
 "motion by slices", uniform profile

$$\implies \overline{(v^2)} = \overline{v}^2$$
 at first order

Closure - The Saint-Venant system

$$\partial_t (h\bar{v}) + \partial_x (h\bar{v}^2) + \left(\int_0^h \partial_x p \,dz\right) = -(p_{|z=h} - p_{\rm atm})\partial_x h + O(\varepsilon)$$

• at order ε : $p(t,x,z) = p_{\rm atm} + \frac{1}{{\rm Fr}^2}(h-z) + O(\varepsilon)$

$$\implies p_{|z=h} = p_{ ext{atm}} + O(arepsilon) \ \ ext{and} \ \ \partial_x p = rac{1}{ ext{Fr}^2} \partial_x h + O(arepsilon)$$

ullet the resulting Saint-Venant system (at first order in arepsilon) reads

$$\begin{cases} \partial_t h + \partial_x (h \bar{v}) = 0 \\ \partial_t (h \bar{v}) + \partial_x (h \bar{v}^2) + \frac{1}{2 \operatorname{Fr}^2} \partial_x (h^2) = 0 \end{cases}$$

- $h\bar{v}$: flow rate
- structural analogy with the compressible Euler equations

$$\begin{cases} \partial_t \rho + \partial_x (\rho u) = 0 \\ \partial_t (\rho u) + \partial_x (\rho u^2) + \partial_x p(\rho) = 0 \end{cases}$$

The Saint-Venant (Shallow Water) system - Summary

$$\Big[exttt{2D incomp. Euler eq} + exttt{BC } (3+3 exttt{ Eqs}) \Big] \longrightarrow exttt{1D Shallow Water eq} \ (2 exttt{ Eqs}) \Big]$$

Recap:

- nondimensionalization of incompressible Euler equations
- hydrostatic approximation giving the pressure profile
- vertical averaging
- closure of the model by assuming a uniform velocity profile at leading order

$$\begin{cases} \partial_t h + \partial_x (h\bar{v}) = 0 \\ \partial_t (h\bar{v}) + \partial_x (h\bar{v}^2) + \frac{1}{2\mathrm{Fr}^2} \partial_x (h^2) = 0 \end{cases}$$

Extensions / Alternatives:

- other starting system (ex: Euler eq.), other forces (ex: Coriolis)
- other boundary conditions at the top (ex: $p_{\rm atm}(t,x)$, surface tension, etc.) or at the bottom (ex: topography, no-slip or friction law, etc.)
- other reference velocity profile (ex: linear, semi-parabolic)

Rmk: Large range of applications in geophysics

 \rightarrow models for avalanches, atmospheric flows, sediment transport, etc.

Some theoretical math. issues around Shallow Water eq.

- existence of solutions to the Shallow Water equations?
 what regularity? global existence / blow up in finite time?
- rigorous justification of the asymptotics

Main references for the course

- D. Serre, Systems of Conservation Laws T.1
- L. C. Evans, Partial Differential Equations
- (C. Dafermos, Hyperbolic Conservation Laws in Continuum Physics)

see also other master courses

- "Hyperbolic models for complex flows application to sustainable energies" by E. Godlewski, J. Sainte-Marie
- "Shallow-water models for water waves" by V. Duchêne

and books, survey papers

- D. Lannes, The Water Waves Problem, Mathematical Analysis and Asymptotics
- D. Bresch, "Shallow Water equations and Related Topics"
- C. Mascia, "A dive into shallow water"

Propositions of projects

• format: work in pairs small report (\sim 10-15 pages) + defense in March 15min (+ questions)

possible subjects:

- Complex flows in the shallow water regime
 → modeling of complex geophysical flows (avalanches, mud flows, etc.)
- ▶ erosion model(s) → sediment transport, coastal morpho-dynamics
- lacktriangle partially constrained free surface flows ightarrow subsurface flows, WEC models
- viscous Saint-Venant equations
- kinetic point of view on the Saint-Venant equations
- **.**...