(a)

Obs. 1:

$$\sqrt{(v-0)^2 + (3-7)^2 + (v-0)^2} = 3$$

obs. 2:

$$\sqrt{(2-0)^2+(0-0)^2+(0-0)^2}=2$$

obs. 3:

$$\sqrt{|x|^2+|x|^2+3^2} = \sqrt{10} \approx 3.16$$

665. 4:

$$\sqrt{0+1^2+2^2} = \sqrt{6} \approx 2.45$$

obs 5:

$$\sqrt{(-1)^2 + 0 + 1^2} = \sqrt{2} \approx 1.41$$

$$\sqrt{|^2+|^2+|^2} = \sqrt{3} \approx 1.73$$

(b) For the case k=1, we will only consider the clastest neighbour. From question a we know the dost neighbour is observation 5, with a Euclidean distance of 1.41. Therefore. prediction is green.

## (C) Similar to (b), we took at 3 clossest neighborns:

obs. t: distance = 1.41 Green

obs. b : distance = 1.73 Red

obs. 2: distance = 2 Rod

>> Red is more >> Prediction is Red.

## (d) small.

## Reason:

highly non-linear means more complex.

If k is large, the model is less curvy and less flexible, missing out complex patterns.

If k is small, it gets more easily adaptive to local variations in the data, which is what we want.