

# **Synchronous and deterministic distributed communication computing model by message passing**

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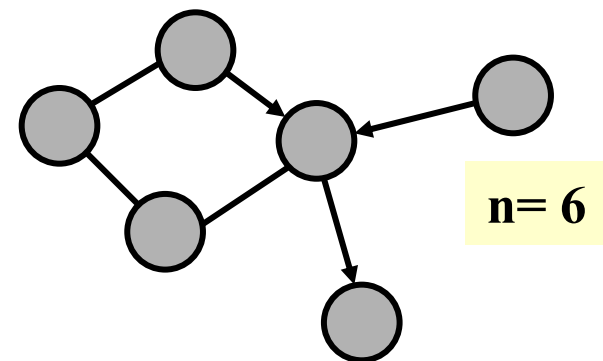
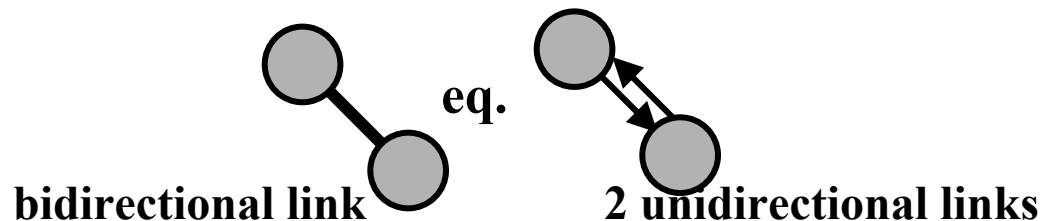
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Reference book: Distributed Algorithms N. Lynch

# Communication network graph (1)

Represented by a directed graph  $G(V,E)$ :

- the set  $V$  of nodes in the network represents the computing and communicating entities, called *processes*
- the set  $E = \{(i,j) : i,j \in V\}$  of directed edges represents the unidirectional **communication links/channels**
- $|V| = n$



# Communication network graph (2)

- Each directed edge in  $E$  (representing a communication link) may contain:
  - either a single message of the alphabet (set)  $M$  (at a time)
  - or an empty message named *null*
- For each process  $p_i$ , we denote by:
  - *out\_nbrs<sub>i</sub>* the set of successor nodes of  $p_i$   
 $\{j: (i,j) \in E\}$
  - *in\_nbrs<sub>i</sub>* the set of predecessor nodes of  $p_i$   
 $\{j: (j,i) \in E\}$
  - In a non-directed graph  $G$ :  
 $\text{out\_nbrs}_i = \text{in\_nbrs}_i = \text{nbrs}_i$

# A $p_i$ process consists of:

**$states_i$** : set of all possible **states** of  $p_i$

- can be infinite
- defined by the program (algorithm) variable types of  $p_i$

**$start_i$**   $\subseteq states_i$ : set of **initial states**

**$msgs_i$** : message generation function

$msgs_i : states_i \times out\_nbrs_i \rightarrow M \cup \{null\}$

**$trans_i$** : transition function

$trans_i : states_i \times [M \cup \{null\}]^{in\_nbrs_i} \rightarrow states_i$

**Note:** functions **msgs** and **trans** are single-valued in output  $\rightarrow$

- computation model (transitions) is **deterministic**
- from a given initial configuration (for a given G)  
the **execution is unique**

# Synchronous execution

**Starts with:**

- processes in the **initial states**
- they **wake up simultaneously**
- the **communication** links are **empty**

**Afterwards, the processes operate together**  
**in synchronous rounds (phases)**

**In each round, each process  $p_i$ :**

- 1. Apply  $msgs_i$**  to generate new messages on each link to  $out\_nbrs_i$  and put these messages on the corresponding links.
- 2. Apply  $trans_i$**  on the current state and the messages in the  $in\_nbrs_i$  links to switch to the new state. Cleans up the links (to  $out\_nbrs_i$ ) of any messages.

A **round** (the 2 steps) is assumed to execute **without interruption, i.e. instantaneously.**

An *execution* is an infinite repetition of rounds.

# Why a perfectly synchronous model?

## 1. Ease of design and analysis

- single execution for a given initial configuration and graph

## 2. There are synchronisers

- algorithms that simulate a synchronous network on an asynchronous one, thus
- allowing synchronous algorithms to be executed on asynchronous networks

## 3. Useful for impossibility proofs

- the set of all asynchronous executions includes all synchronous executions →
- impossibility results for synchronous networks apply for asynchronous ones

# Formal definitions

**Configuration:** is a vector of states of all processes  $[s_1, s_2, s_3, \dots, s_n]$  (or a assignment of states to processes  $C: V \rightarrow \text{states}$ )

**Execution:** is an **infinite sequence**  $C_0, M_1, C_1, M_2, C_2, M_3, C_3, \dots$  in which:

- $C_r$  is a configuration after round  $r$
- $M_r$  is a vector of messages on all communication links (directed edges), or an assignment of messages to links ( $M_r: E \rightarrow M \cup \{\text{null}\}$ )

**Terminal configuration:** is a configuration such that for any process  $p_i$ :

1. application of  $\text{trans}_i$  does not change the state of  $p_i$  (for every  $p_i$ ), and
2.  $\text{msgs}_i$  generates only null messages

**Termination is said to be reached** when a terminal configuration is reached

**Problem** is a predicate  $P$  on the executions (which defines the set of admissible executions)

**Algorithm/System A solves a problem P** if any execution of A satisfies the predicate  $P$  (is in the set  $P$ )

# Complexity measures

## **Worst case (default)**

- **Time complexity:** in (the maximum) number of rounds to termination
- **Message complexity:** in (the maximum) number of non-null messages sent (generated) during an execution
- **Bit complexity:** in number of generated bits

## **Algorithm complexities are generally expressed:**

- **in terms (or as a function) of the parameters that describe the size of the problem:**  
 $n$ ,  $|E|$ , etc.

- **in order of magnitude**

Let  $f$  and  $g$  be two functions from integers to integers.

- $f = O(g)$ , if there is a constant  $c > 0$  s.t. for all  $n$  from  $n > n'$ ,  
 $f(n) \leq c g(n)$ .
- $f = \Omega(g)$ , if there is a constant  $c > 0$  s.t. for all  $n$  from  $n > n'$ ,  
 $f(n) \geq c g(n)$ .
- $f = \Theta(g)$ , if  $f$  is simultaneously  $O(g)$  and  $\Omega(g)$ .