

## [PS 2]

#1.

- (a) Training of data-B doesn't converge, whereas that of data-A does.
- (b) Because data-B is linearly separable, so scale of  $\theta^T x$  gets larger to decrease loss until  $|\theta|$  reaches  $\infty$
- (c) iii)  $\rightarrow \theta$  won't go  $\infty$ .
- (d)  $\rightarrow$  this prevents data-B from being linearly separable.
- (2) No, because it maximises geometric margin, with  $|\theta|$  fixed.

#2.

- (a) Learned  $\theta$  of logistic regression model meets:

$$\frac{\partial J(\theta)}{\partial \theta} = \sum (y^i - h_\theta(x^i)) x^i = 0$$

$\Rightarrow$  matrix form:

$$\underbrace{\begin{bmatrix} 1 & & 1 \\ \vdots & \ddots & \vdots \\ x_n^{(1)} & & x_n^{(m)} \end{bmatrix}}_{X \text{ (n+1 x m)}} \underbrace{(Y - h(X))}_{(m \times 1)} = 0$$

consider 1<sup>st</sup> row of eq.

$$\sum (y^i - h_\theta(x^i)) = 0$$

$(y^i \in \{0, 1\})$

$$\Rightarrow \sum P(y^i = 1 | x^i; \theta) = \sum h_\theta(x^i) = \sum y^i = \sum 1_{\{y^i = 1\}}$$

this is equivalent to question's condition  $(a, b) = (0, 1)$

- (b) Perfect calibration doesn't necessarily imply perfect accuracy because calibration is about probability. Converse is necessarily true.

(c)  $X(Y - h(X)) + 2\lambda\theta = 0$

consider 1<sup>st</sup> row of eq.

$$\sum (y^i - h_\theta(x^i)) + 2\lambda\theta = 0 \Rightarrow \sum P(y^i = 1 | x^i; \theta) = \sum 1_{\{y^i = 1\}} + 2\lambda\theta$$

$\therefore$  prediction will be biased, proportional to  $\theta_0$

#3. Prove by contradiction.

assume  $\|\theta_{MAP}\|_2 > \|\theta_{ML}\|_2$

then  $P(\theta_{MAP}) < P(\theta_{ML}) \quad \because \theta \sim \mathcal{N}(0, \tau^2 I)$

$$\Rightarrow P(\theta_{MAP}) \prod P(y^i | x^i; \theta) < P(\theta_{ML}) \prod P(y^i | x^i; \theta_{MAP})$$

$$(\because \theta_{ML} \text{ maximises } \prod P(y^i | x^i; \theta)) < P(\theta_{ML}) \prod P(y^i | x^i; \theta_{ML})$$

$\Rightarrow$  contradicts to the fact that  $\theta_{MAP}$  maximises  $\prod P(y^i | x^i; \theta)$ ,

#4.

$$(a) \quad u^T K u = \sum_{i,j} z_i z_j (K_1(x^i, x^j) + K_2(x^i, x^j)) \\ = u^T K_1 u + u^T K_2 u \geq 0 \Rightarrow \text{kernel},$$

(b) not kernel

$$(c) \quad u^T K u = \alpha u^T K_1 u \quad \therefore \text{kernel}$$

(d) not kernel

(e) Since  $K_1(x, z), K_2(x, z)$  is kernel,  $\exists \phi_1 \in \mathbb{R}^{d_1}, \exists \phi_2 \in \mathbb{R}^{d_2}$   
s.t.  $K_1(x, z) = \phi_1(x)^T \phi_1(z), K_2(x, z) = \phi_2(x)^T \phi_2(z)$

Then  $K(x, z)$

$$= \sum_i \phi_1(x)_i \phi_1(z)_i + \sum_j \phi_2(x)_j \phi_2(z)_j$$

$$= \sum_i \sum_j (\phi_1(x)_i \phi_2(x)_j) (\phi_1(z)_i \phi_2(z)_j) = \underbrace{f(x)}_{\phi_3(x)}^T \underbrace{f(z)}_{\phi_3(z)} \\ \text{, } \phi_3 \in \mathbb{R}^{d_1+d_2} \Rightarrow K \text{ is kernel},$$

$$(f) \quad u^T K u = \sum_{i,j} u_i u_j f(x^i) f(x^j) = \left( \sum_i u_i f(x^i) \right)^2 \geq 0 \Rightarrow \text{kernel}$$

$$(g) \quad u^T K u = \sum_{i,j} u_i u_j K_\phi(\phi(x^i), \phi(x^j)) \geq 0 \Rightarrow \text{kernel}$$

$$(h) \quad u^T K u = \sum_{i,j} u_i u_j \left( \sum_k \alpha_k (K_1(x^i, x^j))^k \right) \geq 0 \quad (\because (a), (c), (e))$$

#5. Since  $\theta$  is too high dim,  $\theta^T \phi(x)$  is represented as kernel  $K(\theta, \phi(x))$  always. (a) To predict,  $h_\theta(x^{(n)}) = g(K(\theta^i, \phi(x^{(n)})))$  (b) And param update rule is modified to

$$K(\theta^{(n)}, \phi(x^{(n)})) := K(\theta^i, \phi(x^{(n)})) + \alpha 1\{K(\theta^i, \phi(x^{(n)})) y^{(n)} < 0\} K(\theta^i, \phi(x^{(n)}))$$

(c). Only dot product in kernel form need:  $O(n^2) \rightarrow O(n)$

#6. look at  
PS2-6.ipynb