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EDUCATION

University of California, Los Angeles (UCLA)

Sep.2024-Now

♦ Major: Electrical and Computer Engineering (MS)

University of Science and Technology Beijing (USTB)

Sep.2020-Jun.2024

♦ Major: Computer Science (BS)♦ GPA: 3.92/4 (Top 3/278)

PUBLICATION

Junyi Zhang, Chang Liu, Chun Yang*, SAN: Structure-Aware Network for Complex and Long-tailed Chinese Text Recognition, 17th International Conference on Document Analysis and Recognition (ICDAR 2023), published.

RESEARCH EXPERIENCE

► National Laboratory of Pattern Recognition (NLPR), Institute of Automation, Chinese Academy of Sciences

Feb.2023-Sep.2023

Research Topic:

Docking Based on Protein Binding Pockets Similarity

Academic Supervisor: Prof. Shu Wu, Prof. Qiang Liu

- ♦ Related fields: AI4Science, Data Mining, Geometric Deep Learning, Diffusion Model
- ❖ Incorporated similarity information of protein binding pockets into the molecular docking model, enabling transfer learning on diverse docking datasets, thereby enhancing model robustness and improving docking performance.
- ♦ Developed a modeling framework to extract similarity information from protein binding pockets. Proposed a heterogeneous graph representation comprising three types of nodes: molecule, motif, and subpocket, and employed graph neural networks to extract and process information from the graph.

► Pattern Recognition and AI Technology Innovation Lab

May 2022-Jan.2023

University of Science and Technology Beijing

Research Topic:

SAN: Structure-Aware Network for Complex and Long-tailed Chinese Text Recognition

Academic Supervisor: Prof. Xucheng Yin, Prof. Chun Yang

- ♦ Related fields: Optical Character Recognition (OCR), CV, NLP
- ♦ Proposed a Structure-Aware Network (SAN) for complex and long-tailed character recognition by utilizing the hierarchical components information of the character.
- ♦ Auxilary Radical Branch (ARB) based on the tree modeling of the label is introduced, which enhances the structure awareness of visual features.
- ❖ Proposed a novel TreeSim method to measure the similarity of two characters, and propose a TreeSim-based weighting mechanism for ARB to further utilize the depth information in the hierarchical representation.
- ♦ Our code has been open-sourced on GitHub. GitHub URL: https://github.com/Levi-ZJY/SAN

SCHOLARSHIP

- ♦ National Scholarship of China (Awarded to 0.2% of students nationwide)
- ♦ Champion's Scholarship (Top 1 in CS department)
- ♦ University-Level First-Class Scholarship

SKILLS

- ♦ Proficient: Python, PyTorch, C, C++
- ♦ Familiar: Java, JavaScript, Verilog, Assembly, HTML

COMPETITIONS

► National AI Board Game Tournament

National 2nd Prize

Jul.2022-Aug.2022

- ♦ Developed a PyTorch-based program for the board game EinStein würfelt nicht, utilizing reinforcement learning principles and the Monte Carlo Tree Search (MCTS) algorithm
- ♦ Built and optimized a deep learning model to predict action probability distributions and value functions, addressing challenges such as slow computation speed and floating-point overflow.

► MCM/ICM

Honorable Mention

Feb.2022-Mar.2022

- Developed a forest management model to enhance carbon sequestration, leveraging logistic growth theory, differential equations, and advanced fitting techniques.
- ♦ Applied the model to the Greater Khingan Mountains, optimizing forest harvesting schedules using data-driven analysis and the Particle Swarm Optimization algorithm.

▶ Mathematics Competition of Chinese College Students

1st Prize in Beijing

Dec.2021

❖ Included advanced problems in higher mathematics, linear algebra, and probability theory, designed to test contestants' mathematical thinking abilities and depth of understanding.

▶ Physics Competition of Chinese College Students

1st Prize in Beijing

Nov.2021

♦ Included advanced problems in mechanics, thermodynamics, electromagnetism, optics, and relativity, designed to evaluate contestants' ability to analyze physical problems and apply mathematical modeling and computational skills.

▶RoboCup

1st Prize

May 2021-Jul.2021

♦ Implemented automatic control for the NAO robot using C++, integrating image data from robot vision and motion information from multiple sensors.

► Microcontroller Application Competition

3rd Prize

Apr.2021-May 2021

♦ Developed an electric fan control system using C language and STM32 microcontroller. Integrated temperature and humidity sensors, human infrared sensors, and implemented advanced features leveraging external interrupts, PWM, and SPI communication.