
Exploring LLM Reasoning in Just-in-time Adaptive Intervention

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Today's Agenda

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- 03** Motivation & Objectives
- 04** System Architecture
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- 08** Key Takeaways
- 09** Discussion
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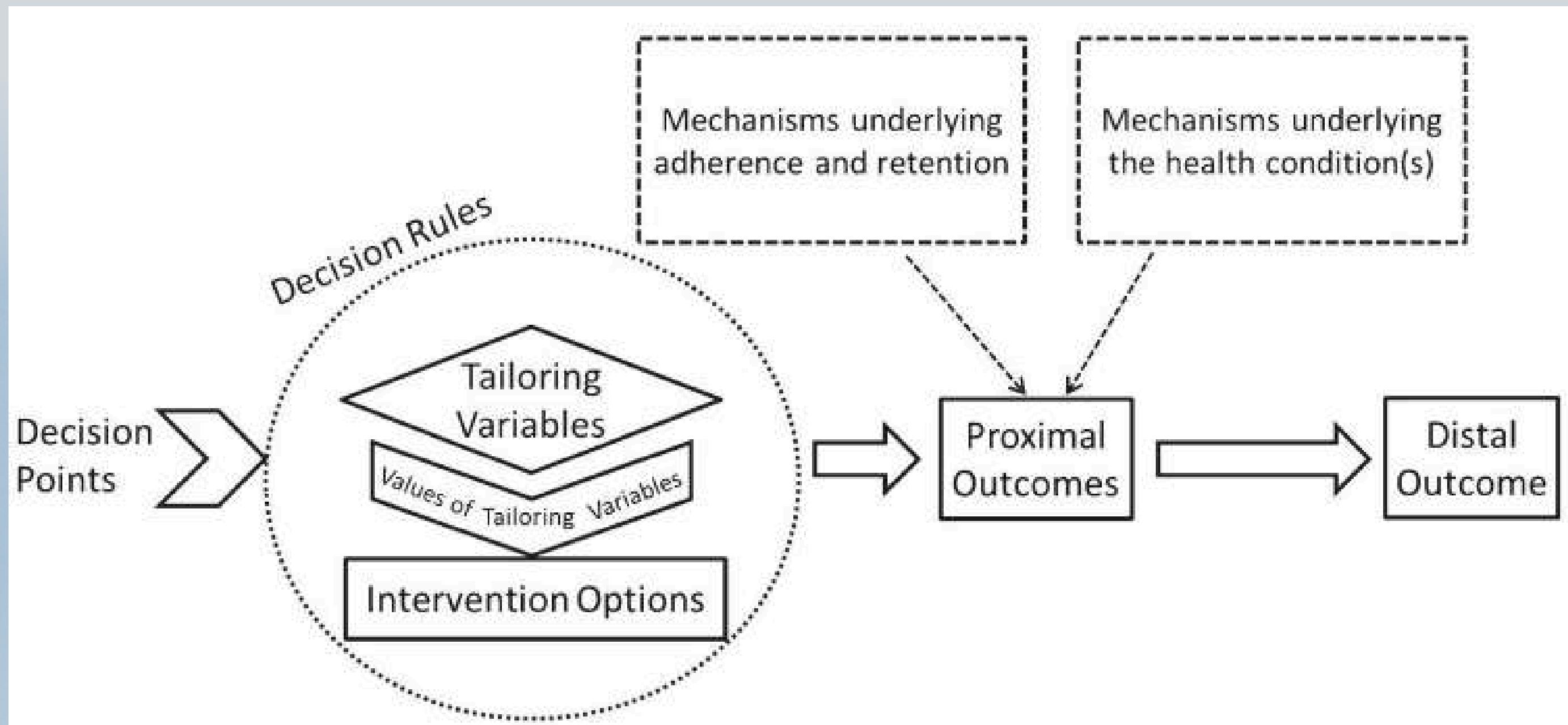
Introduction

Odyssey: LLM-Powered Hydration JITAI:

- End-to-end Just-In-Time Adaptive Intervention
- Edge sensing + calendar + hydration tracking + LLM reasoning
- Nudges with **Smart Timing** and **Smart Content** to help them achieve daily hydration goal.

Related Works: JITAI Framework

According to Nahum-Shani et al.. JITAI “Provide the right type/amount of support, at the right time.”



Related Works: JITAI Desicion Rules

Passive Context Acquisition: everage passive sensing (accelerometers, GPS, device usage)

If distance to high-risk location $\leq S_0$

Then, IO = [Provide an alert]

Else if distance to high-risk location $> S_0$

Then, IO = [Provide nothing]

Related Works: JITAI Desicion Rules

Predictive Modeling for Receptivity & Intervention Timing:
Lightweight ML models (Random Forests, logistic models) effective for low-data personalized predictions.
Deep learning models (RNNs, LSTMs, Transformers) increasingly used for complex, continuous time-series prediction and long-range dependency modeling.

Related Works: JITAI Desicion Rules

Context reasoning over sensor data

AutoLife: semantic interpretation of daily life

Behavioral intervention generation

GPT-4 produces high-quality, empathetic interventions

Shown to outperform laypeople and clinicians

Related Works: Limitation

Components studied in isolation:

- sensing
- prediction
- message generation

✗ No fully automated, end-to-end JITAI system

✗ No real-time closed-loop deployment

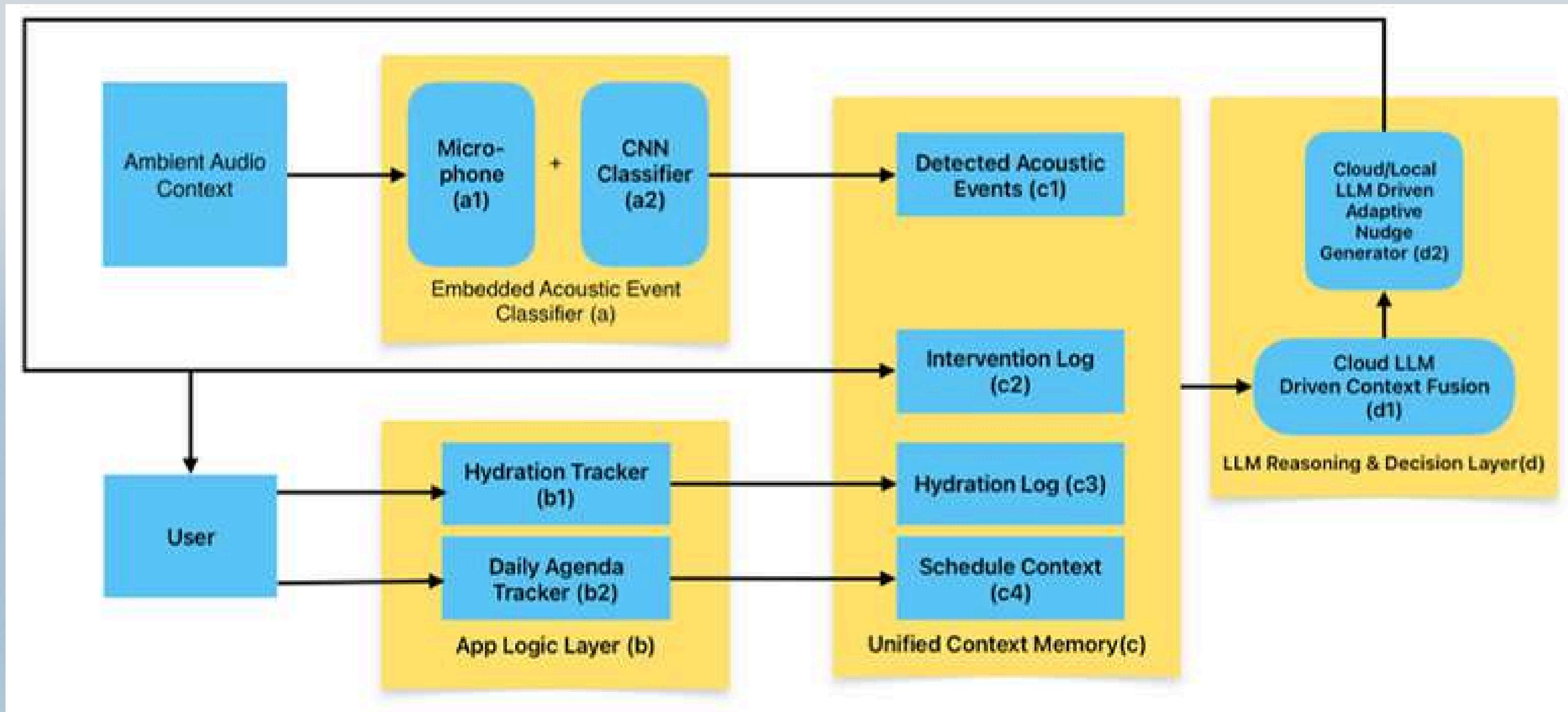
Motivation & Objectives

Goal: Bridge the JITAI operational gap

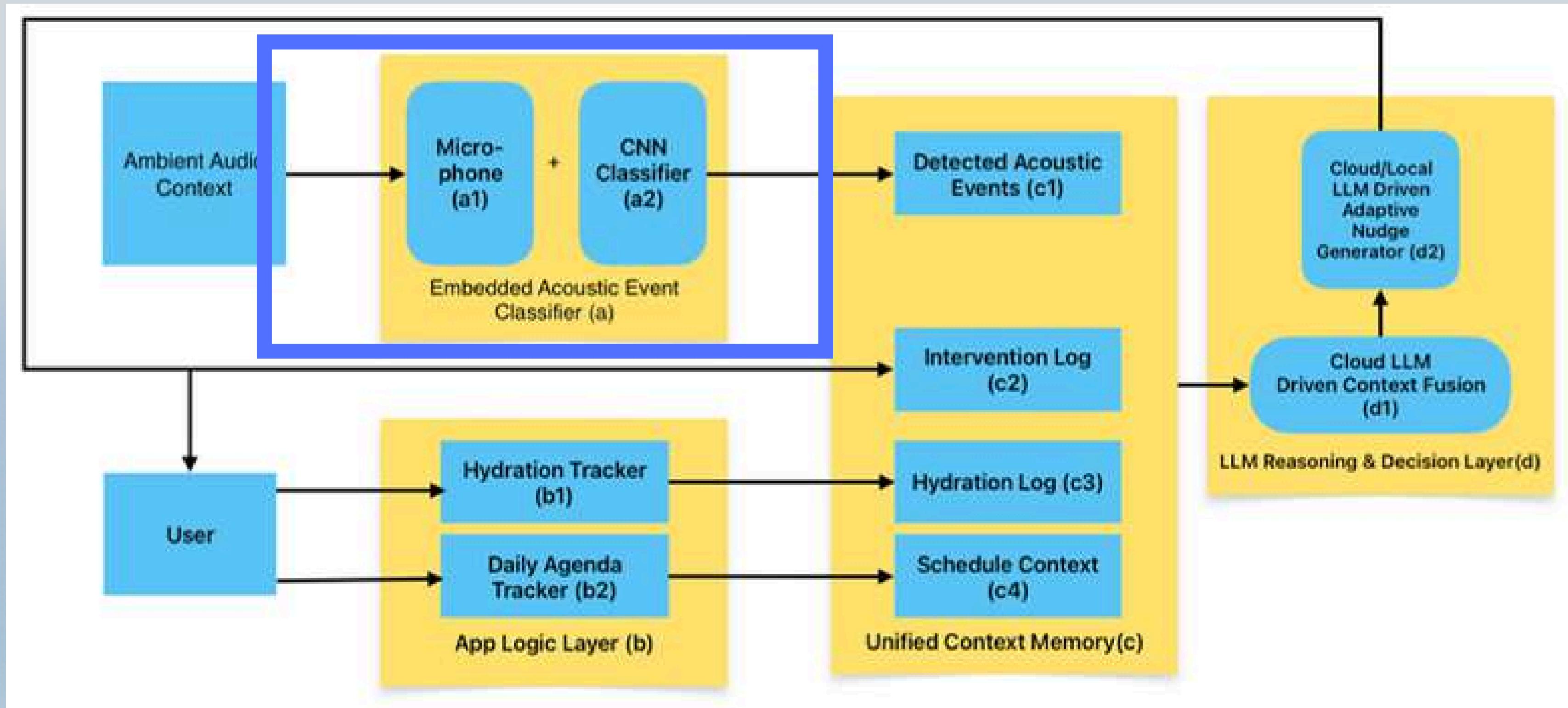
Integrates:

- passive sensing
- automated context fusion
- real-time LLM reasoning
- adaptive intervention delivery
- Fully automated, closed-loop pipeline

System Architecture



Technical Details

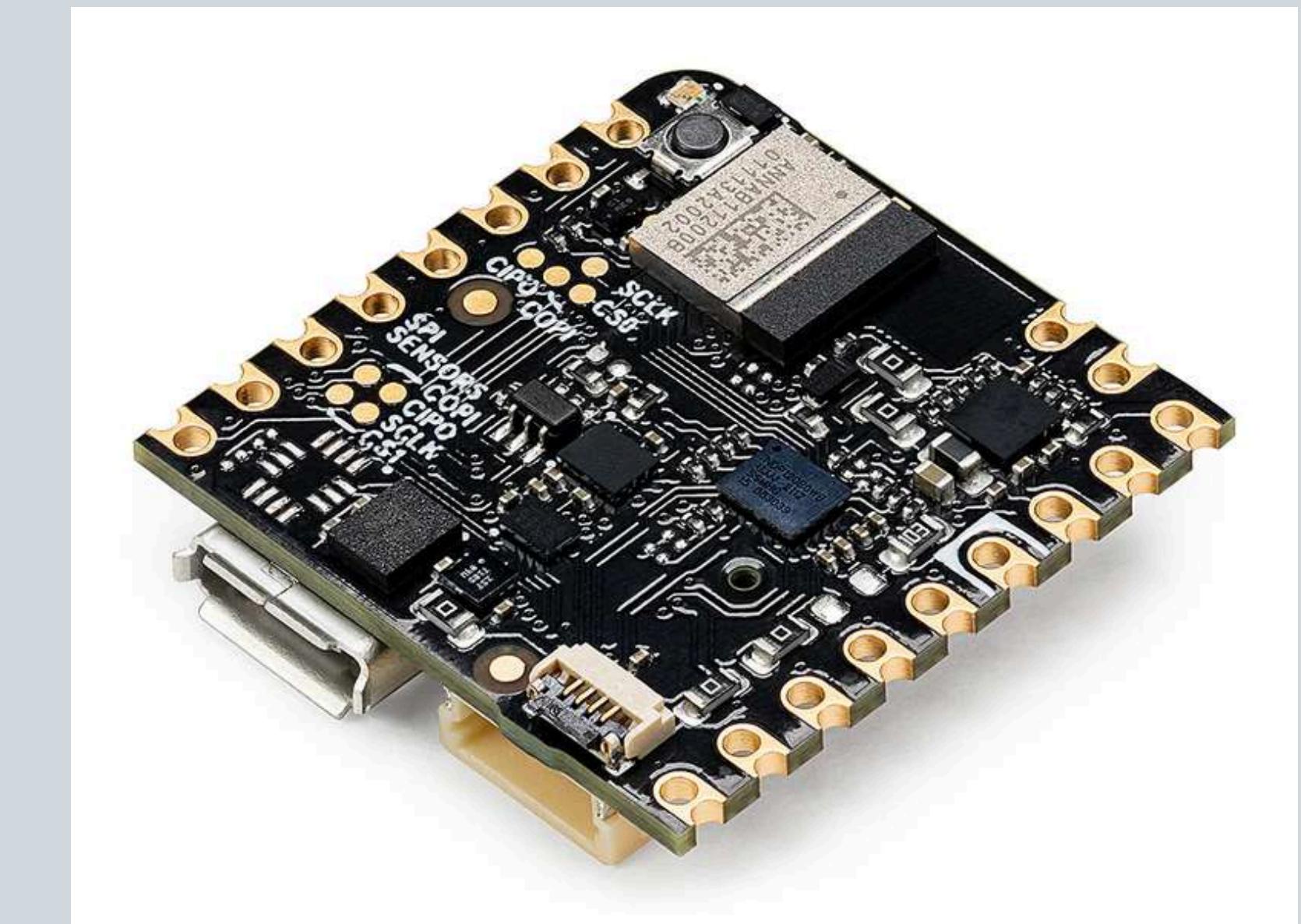


Technical Details (a1)

Using Hardware: Vicla Voice

Incorporating:

- IM69D130, a high-performance digital MEMS microphone from Infineon®
- NDP120 Neural Decision processor
- Coded with ArduinoIDE



Technical Details (a2)

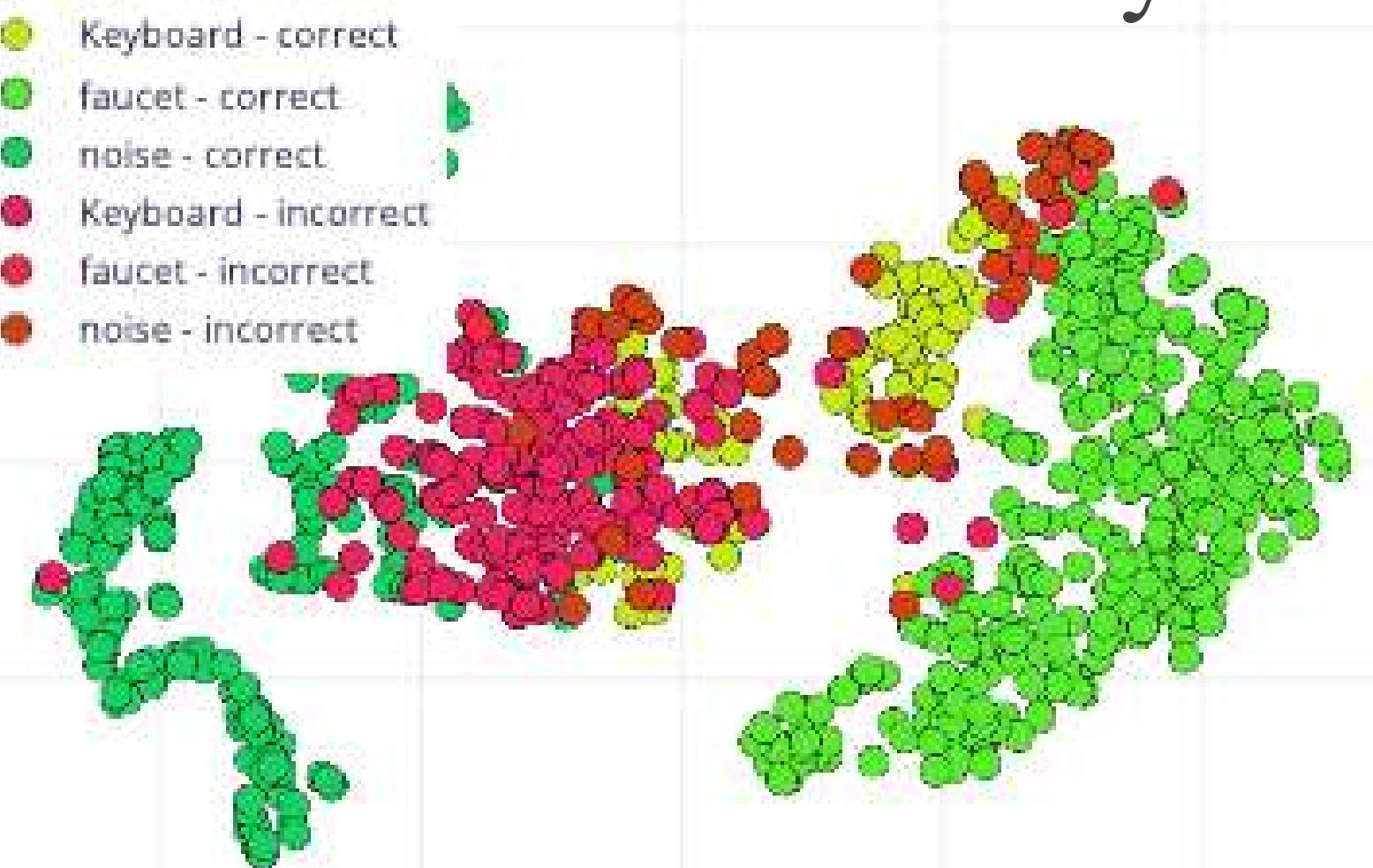


Model Trained on 21 minutes of open source data, trained accuracy 82.8%

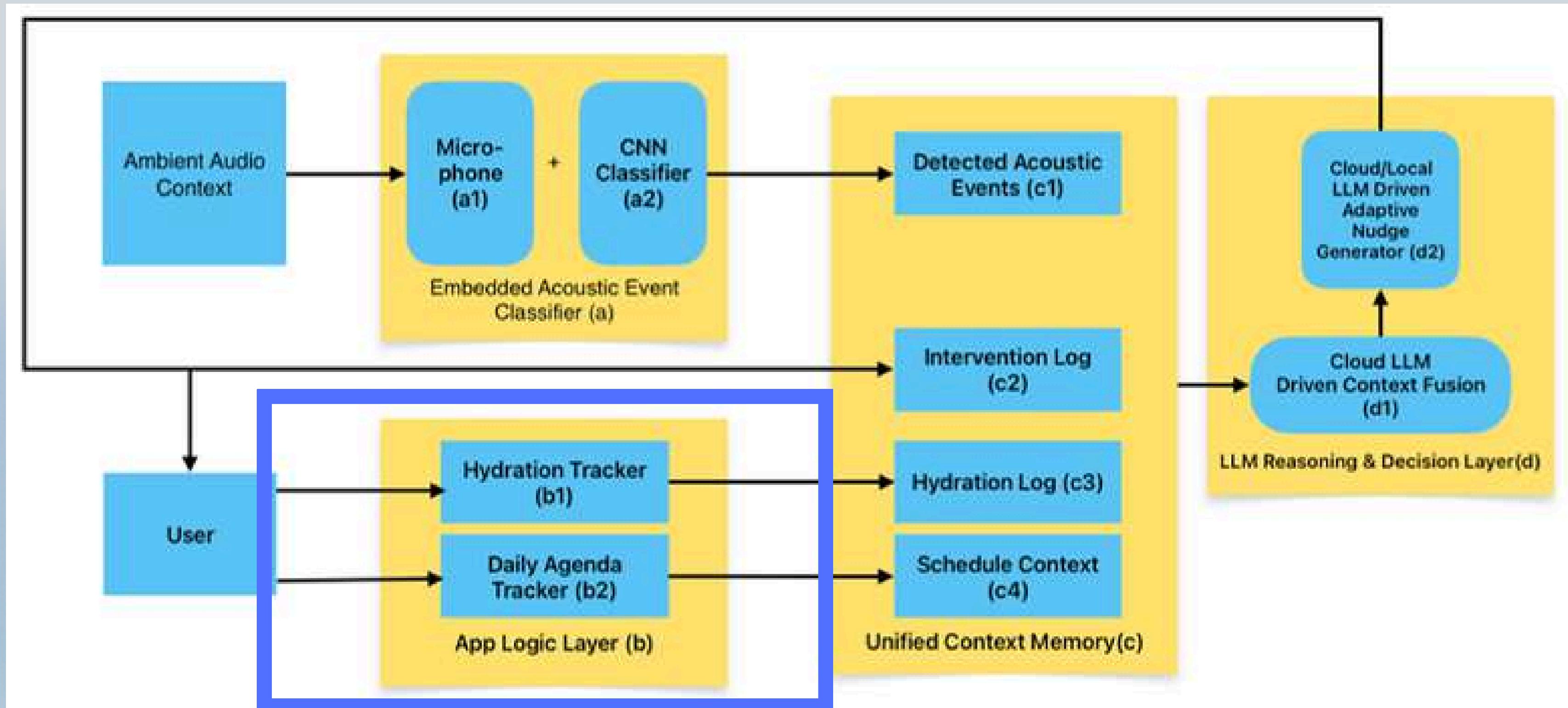
Data explorer (full training set) ⓘ

- Keyboard - correct
- faucet - correct
- noise - correct
- Keyboard - incorrect
- faucet - incorrect
- noise - incorrect

Keyboard/Faucet/Noise



Technical Details



Technical Details (b1)

Model Trained on 21 minutes of open source data, trained accuracy 82.8%

Hydration

Today's Intake

1,250 / 2,000 ml

750 ml to go

Quick Add

+250 ml

+500 ml

+750 ml

Custom Amount (ml)

e.g. 300

Add

Daily Goal (ml)

2,000 ml

- +

Hydration Window

Set the time range for daily hydration tracking

Start

End

6 AM ↴

10 PM ↴

Today's Log

Reset Day

+500 ml

12:17

+250 ml

10:31

+250 ml

10:31



AI Chat



Events



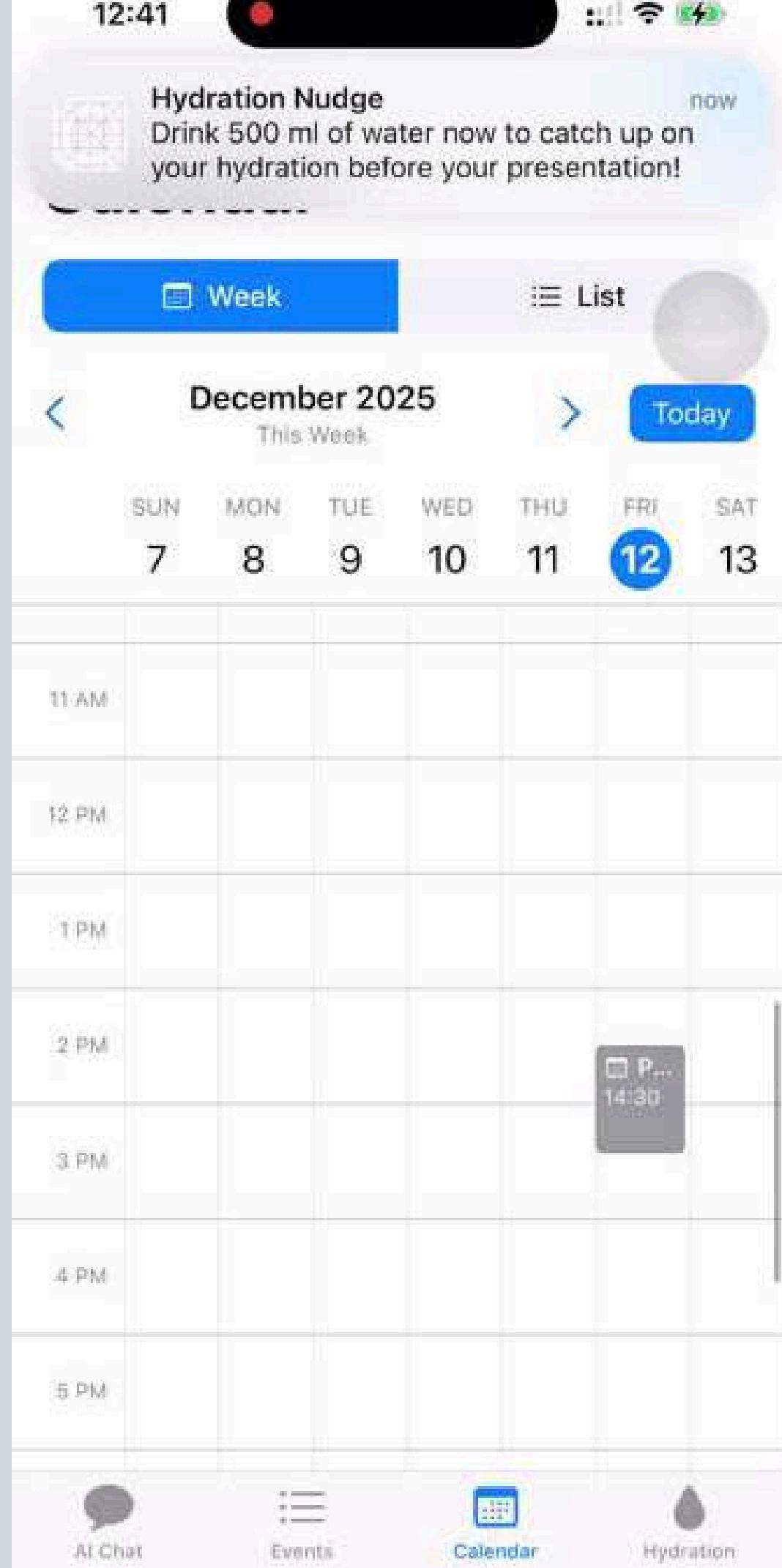
Calendar



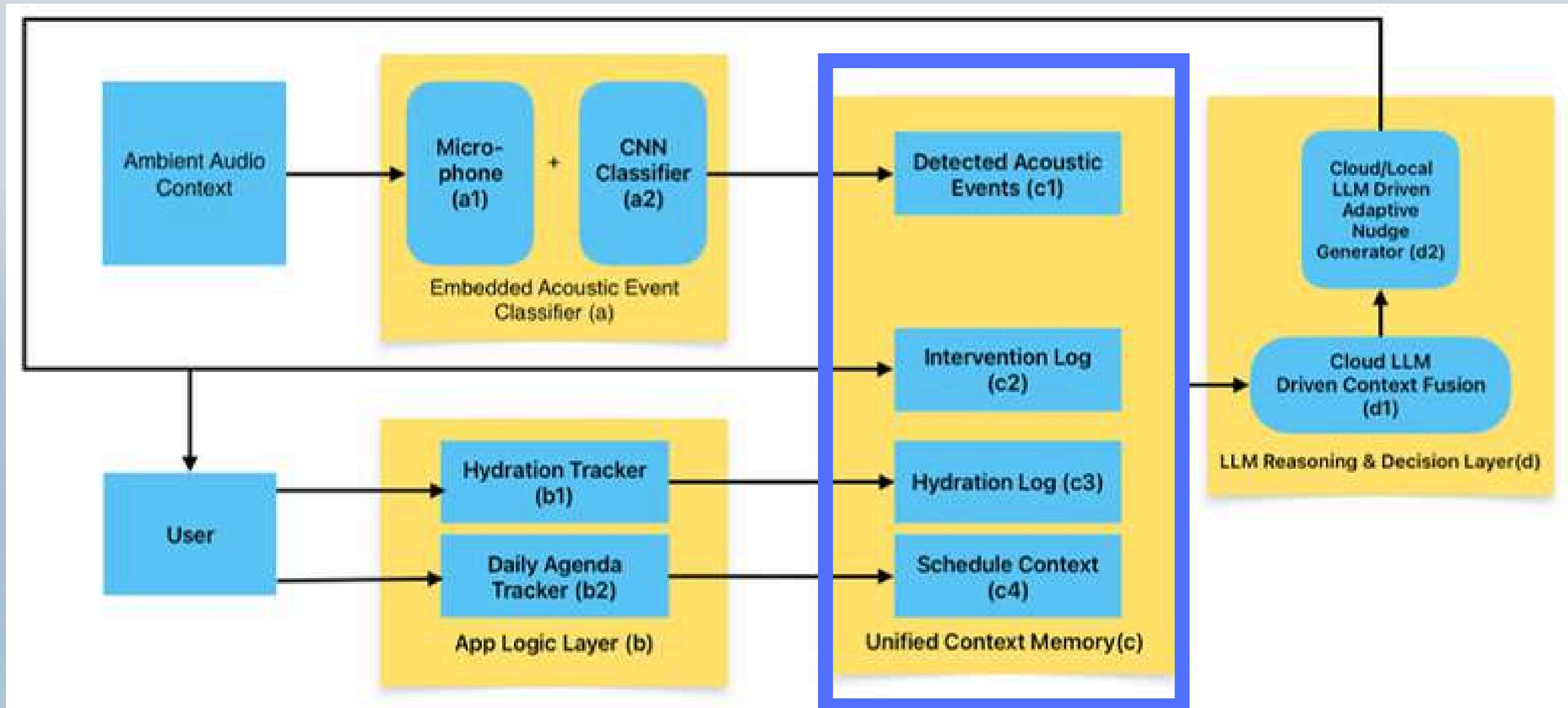
Hydration

Technical Details (b2)

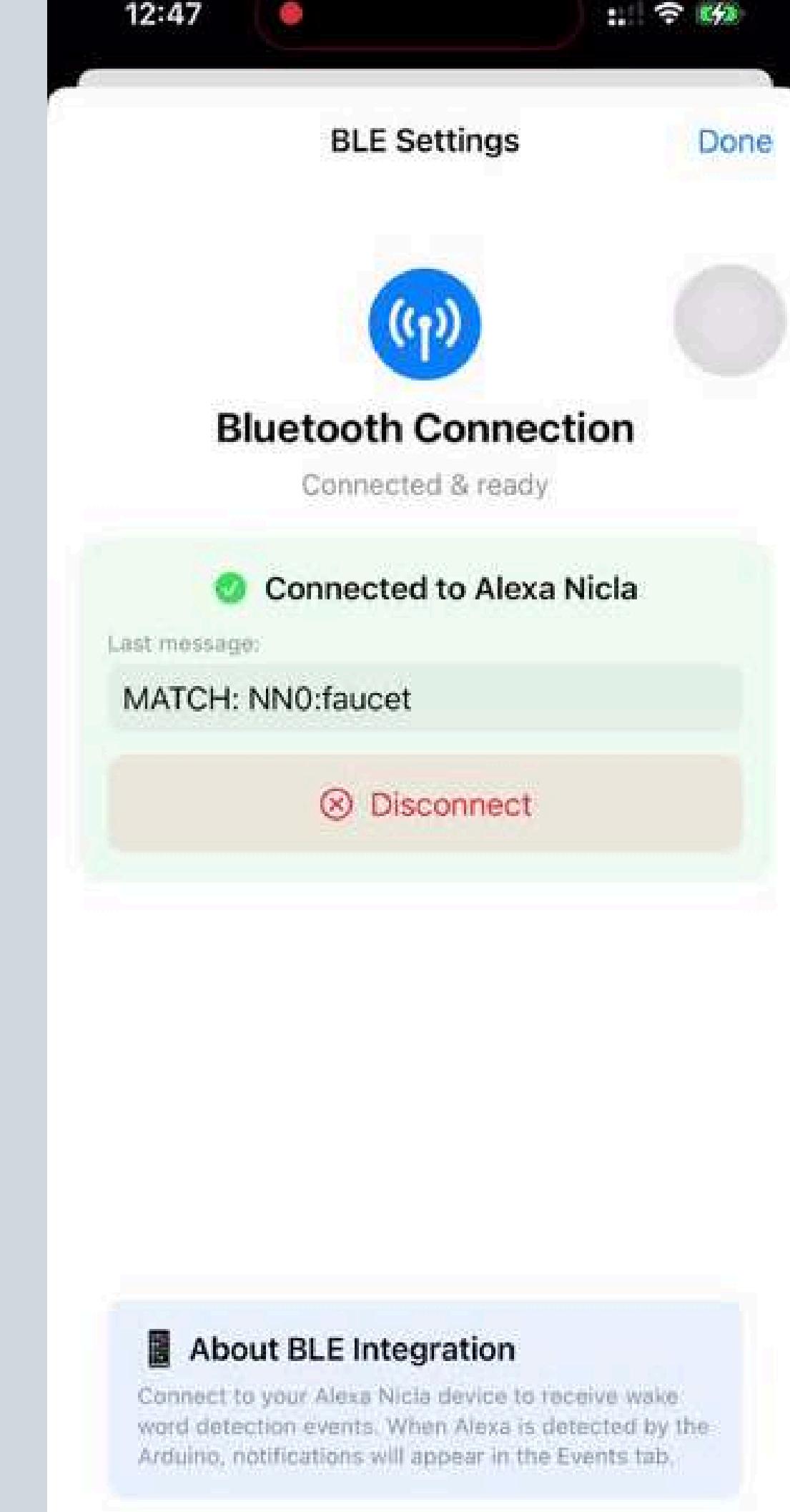
daily agenda tracker



Technical Details



Technical Details (c1) detected acoustic event



Technical Details (c2) intervention log

12:47

BLE Settings Done



Bluetooth Connection

Connected & ready

Connected to Alexa Nicla

Last message:

MATCH: NNO:faucet

Disconnect

About BLE Integration

Connect to your Alexa Nicla device to receive wake word detection events. When Alexa is detected by the Arduino, notifications will appear in the Events tab.

Technical Details (c3) hydration log

Today's Intake
1,250 / 2,000 ml 
750 ml to go

Quick Add
+250 ml +500 ml +750 ml

Custom Amount (ml)
e.g. 300 Add

Daily Goal (ml)
2,000 ml - +

Hydration Window
Set the time range for daily hydration tracking
Start 6 AM End 10 PM

Today's Log Reset Day

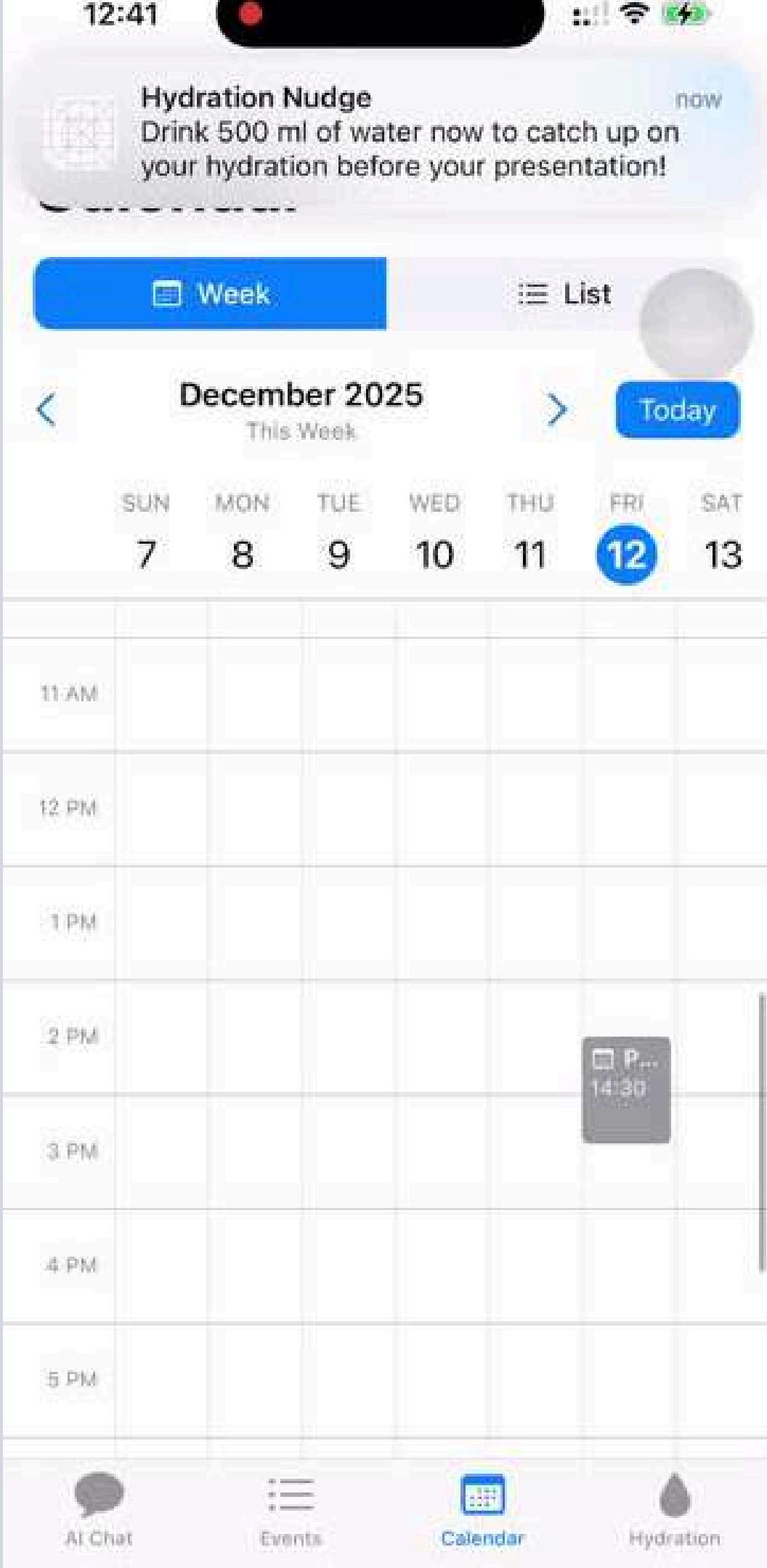
Action	Time
+500 ml	12:17
+250 ml	10:31
+250 ml	10:31

 AI Chat  Events  Calendar  Hydration

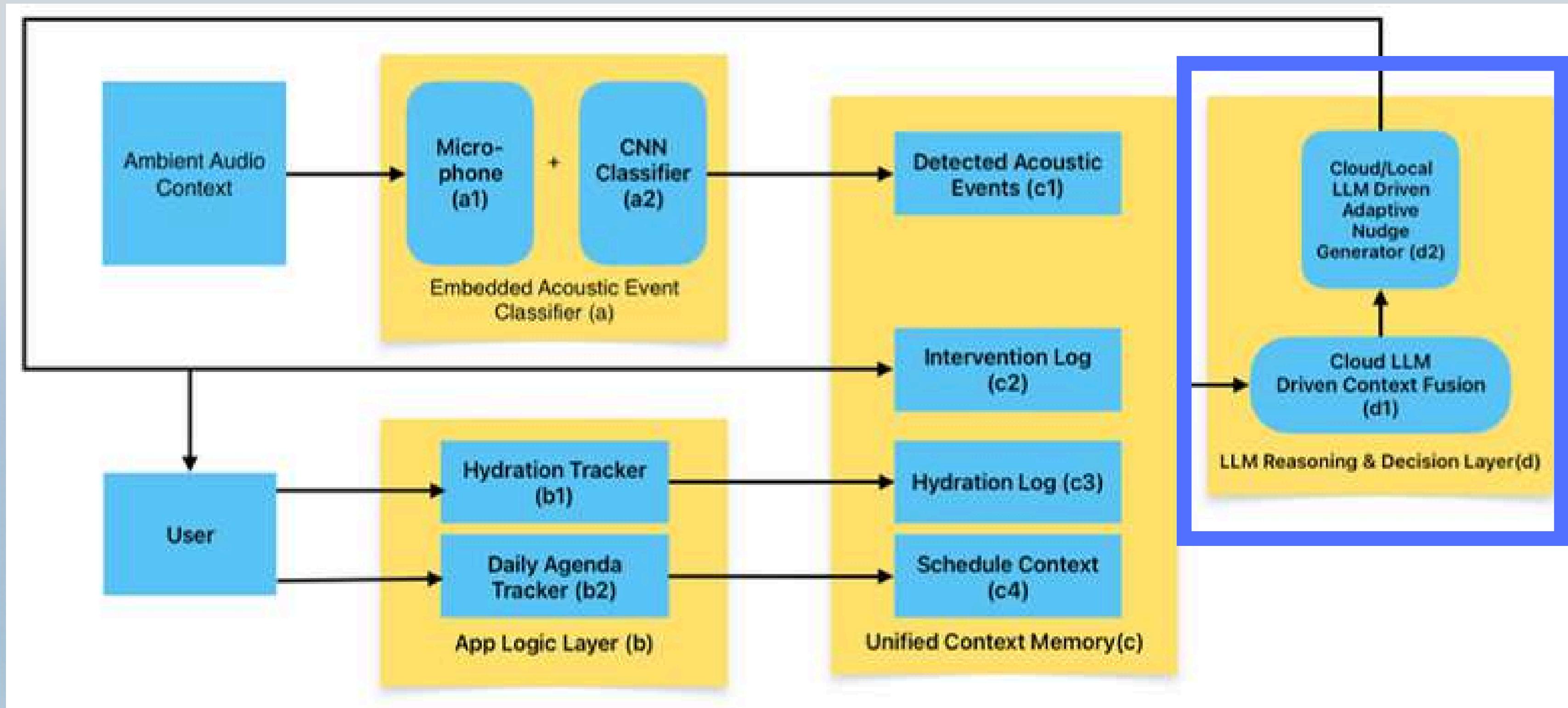
Technical Details (c4) schedule content



Technical Details (c4) schedule content

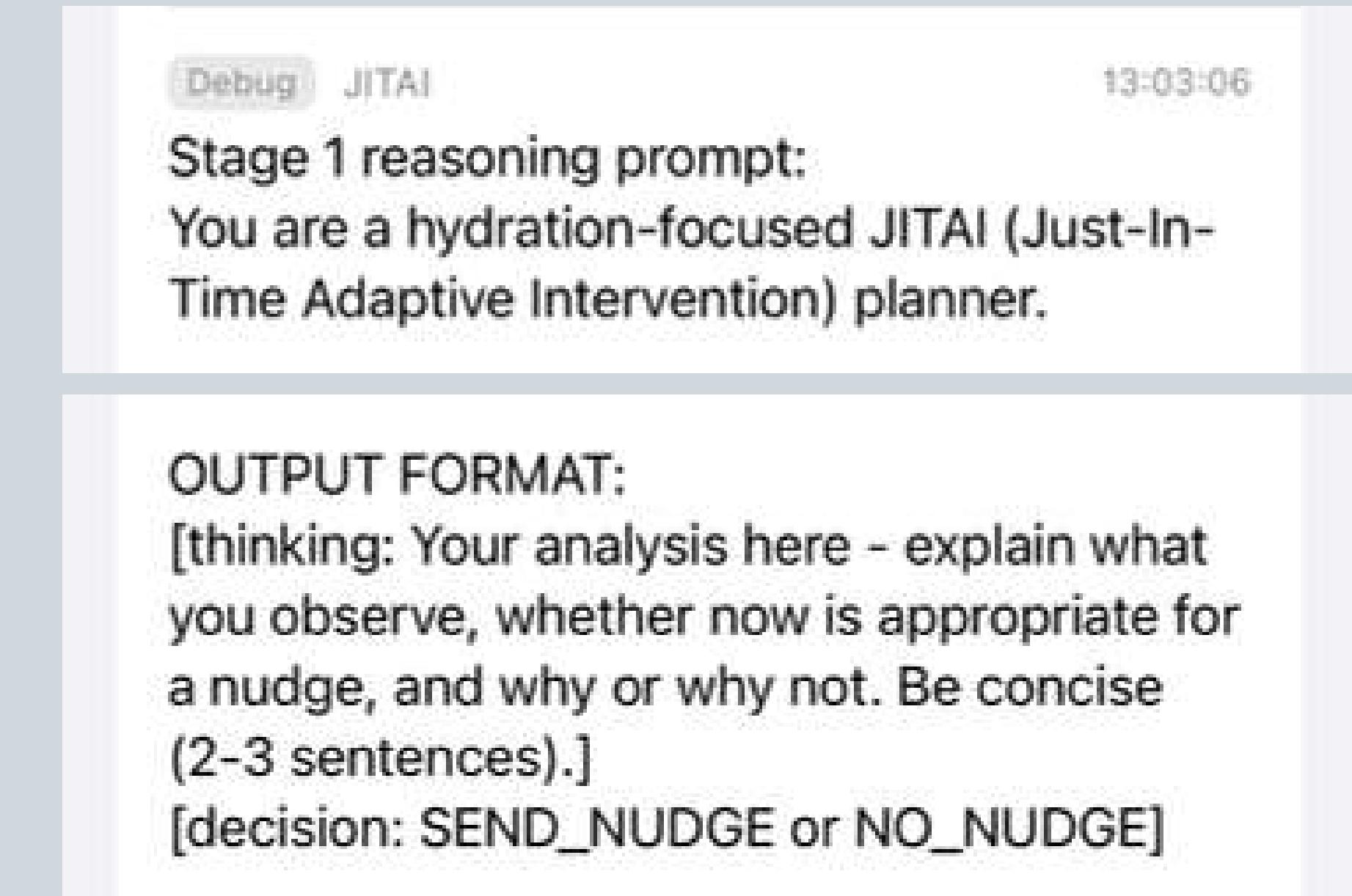


Technical Details



Technical Details (d1)

Cloud LLM Driven Context Fusion



WebSocket connection to <wss://api.openai.com/v1/realtim>
Model: gpt-4o-realtime-preview-2024-10-01

Technical Details (d1)

Cloud LLM Driven Context Fusion

4. Environmental & Activity Context:

- Recent faucet events = good opportunity; keyboard events = deep work (low interruptibility).

5. Nudge History & Personalization:

- Avoid repeating similar messages too often; respect recent nudges to prevent fatigue.

DECISION MATRIX (consider ALL of these):

1. Temporal Context & Progress Alignment:

- Is intake progress aligned with time progress through the 6 AM–10 PM window?
 - Are there long gaps since last drink? Extended work sessions without breaks?

2. Schedule Awareness:

- Avoid ongoing meetings (check if event timestamps overlap with NOW).
 - Prefer upcoming transitions and breaks.
 - If large non-interruptible blocks are coming, suggest pre-hydration.

3. Hydration State:

- Check "Progress gap": negative = behind schedule (more urgent), positive = ahead (less urgent).
 - Significant deficit (e.g., >30% behind) increases nudge priority.

Technical Details (d1) Cloud LLM Driven Context Fusion

Info JITAI

13:03:09

Decision: NO_NUDGE - skipping stage 2

Info JITAI

13:03:09

Stage 1 reasoning:

[thinking: The user has made good progress towards their hydration goal, being ahead of schedule with a positive progress gap of +119 ml. There are no upcoming meetings in the immediate future until 14:30, and the user has just had a recent faucet event, indicating they are engaged in hydration activities. Given that they are already ahead, and have had several nudges today, it may not be appropriate to send another nudge right now as it could lead to fatigue or annoyance. The user appears to be managing their hydration well at the moment.]

[decision: NO_NUDGE]

Technical Details (d2)

Cloud/Local LLM Driven Adaptive Nudge Generator

TinyLlama-1.1B is a compact decoder-only transformer designed for efficient on-device inference.

Model type: 1.1-billion-parameter autoregressive transformer.

Quantization: Commonly deployed as Q4_K_M, reducing memory to ~600–700MB.

cpp bridge: <https://github.com/ggml-org/llama.cpp>

Info Nudge

13:18:08

Logged nudge: Drink 500 ml of water now to stay energized and hydrated for your presentation at 14:30!

Info JITAI

13:18:08

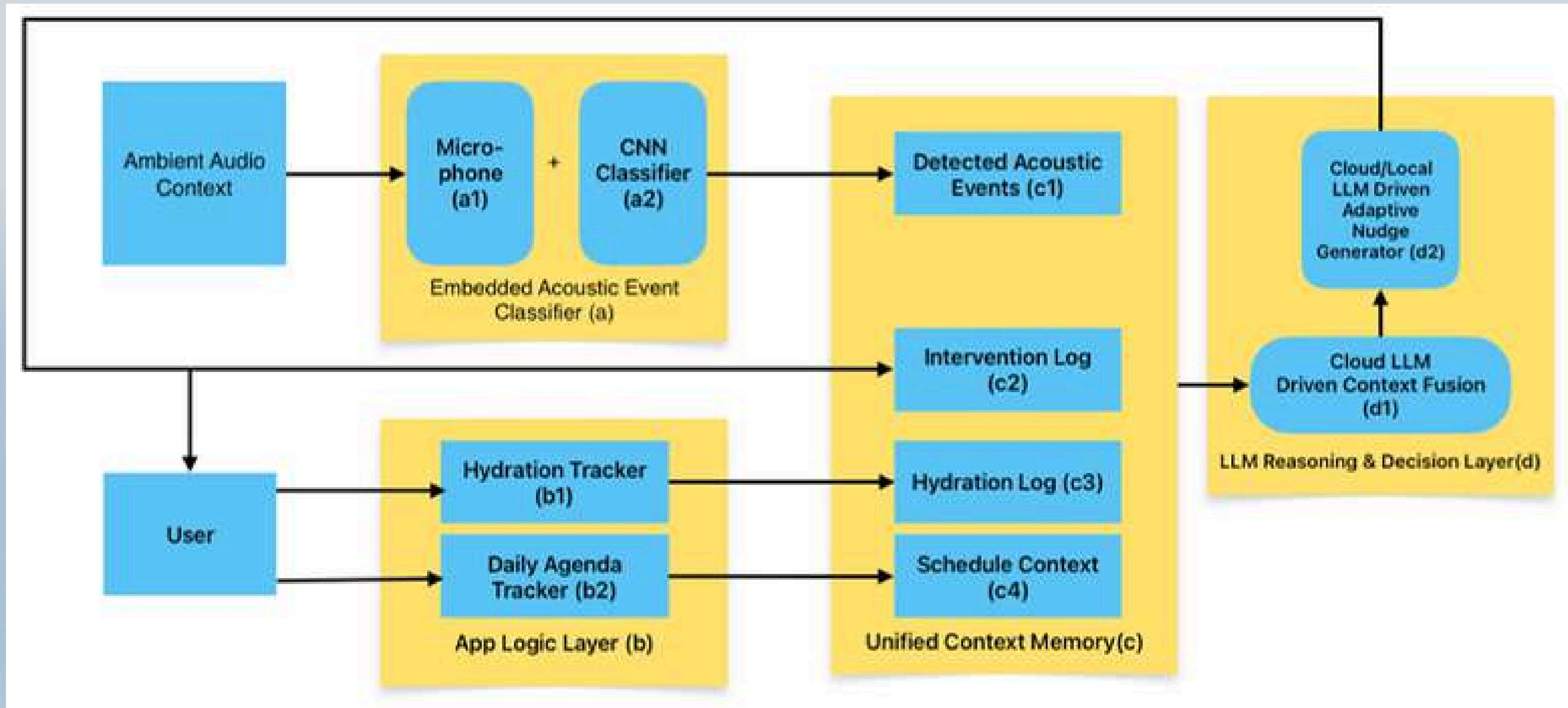
Stage 2 generated nudge: Drink 500 ml of water now to stay energized and hydrated for your presentation at 14:30!

Debug JITAI

13:18:07

Stage 2 nudge generation prompt

Technical Details



User Demo Time

Evaluation: Edge&Cloud

Local LLM Performance:

Very poor performance on
1st-Level: context fusion.
Poor performance on 2nd-
Level: Nudg Generation
Instability: Tokenization failure

The image shows a messaging application interface with three tabs at the top: Cloud (selected), Local, and Hybrid. The Cloud tab displays a conversation between a user and an AI assistant. The user asks for a hydration nudg, and the AI responds. A 'REQUIREMENTS' section follows. The Local tab shows a series of errors where the AI fails tokenization, indicated by a warning icon and the message 'llama_decode failed for prompt'. The Hybrid tab is partially visible on the right.

Cloud Local Hybrid

Local AI

[user: "Hey, can you generate a hydration nudg for me? I'm behind on my goal and need to catch up quickly."]

[assistant: "Sure, here's a hydration nudg for you:"

REQUIREMENTS

12:28

Local AI

REASONING:
[thinking: The user is currently 560 ml behind schedule, which is significant (more than 30% deficit). Despite having just consumed 250 ml a minute ago, the user has a strong request for a hydrat

12:29

Message

Cloud Local

llama_decode failed for prompt

12:30

Local AI

- 12:31 — NUDGE:
[user: "Hey, can you remind me to drink 250 ml of water now to catch up on my hydration goal? I'm behind by 570 ml."]

12:34

Local AI

⚠ Local LLM error:
Tokenization failed

12:34

Local AI

⚠ Local LLM error:
Tokenization failed

12:35

Local AI

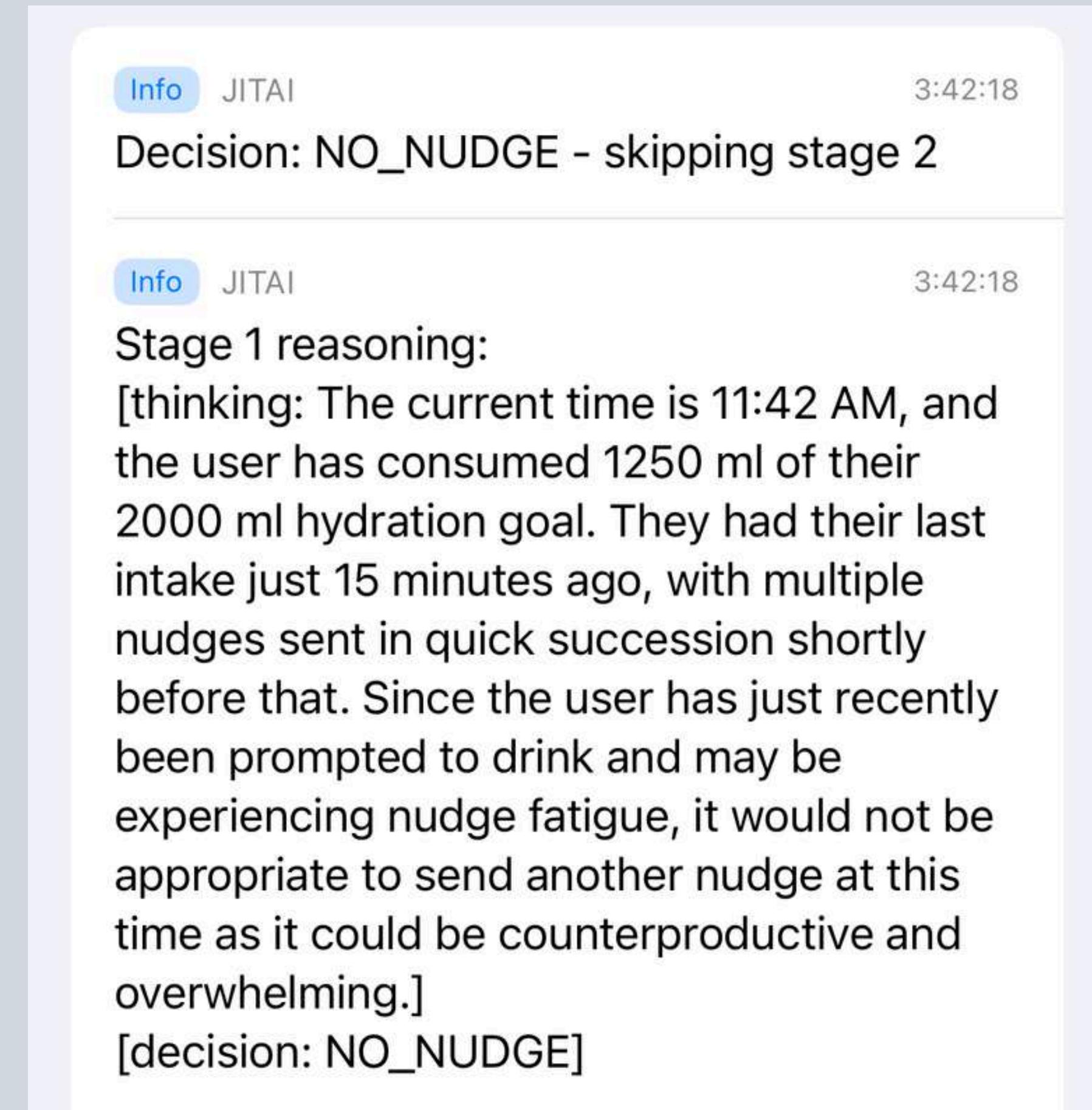
⚠ Local LLM error:
Tokenization failed

12:36

Message

Evaluation: Cloud Alone

Case1: Nudge Fatigue



Evaluation: Cloud Alone

Case2: Meeting ahead but detected BLE event {faucet}

Info JITAI

6:22:59

Stage 1 reasoning:

[thinking: The user has made significant progress towards their hydration goal, having already consumed 250 ml, which is ahead of schedule with a positive progress gap of 205 ml. However, they have an upcoming meeting starting at 6:38, which suggests that now would be a good time to encourage further hydration before the meeting begins, especially since there has been an active period with multiple faucet events indicating recent drinking. A nudge would be timely to help maintain their hydration state before the work session begins, but care must be taken not to interrupt their deep work focus too much now.]

[decision: SEND_NUDGE]

Discussion & Limitation

Edge acoustic model accuracy is constrained by on-device compute and memory

High-capacity models (e.g., YOLO-scale architectures) are infeasible on embedded hardware

Evaluation was limited to bench testing

No long-term, real-world deployment or user study due to time constraints

**Thank
you**

for your time
and attention