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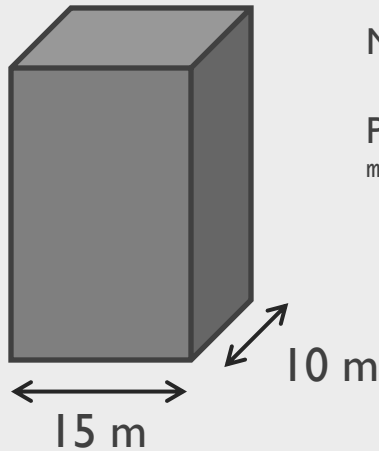
パラメーター  
チューニング  
ヴリヴァシ フェイ  
先端技術開発課



# Max Window Size

The maximum window size has to be greater than the largest objects (X or Y) in the experimental area.

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Largest building

Max window size > 15

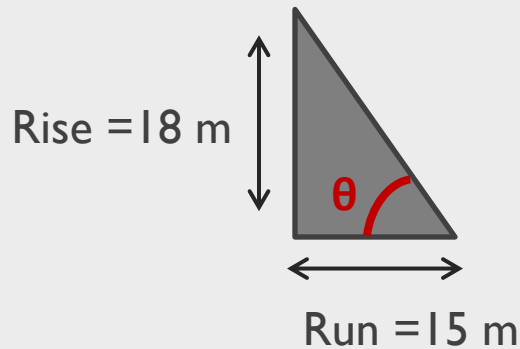
Parameters txt:  
max\_window\_size 16

Type: int  
Range: 3(Linear) or 5(Exponential) - ...  
Default: 33



# Slope

The terrain slope =  $\tan\theta = \frac{\text{elevation between two points}}{\text{distance between two points}} = \frac{\text{rise}}{\text{run}}$



$$\text{Slope} = 18/15 = 1.2$$

Parameters txt:  
slope 1.2

Type: float  
Range: 0.0 – (1.5)  
Default: 0.7

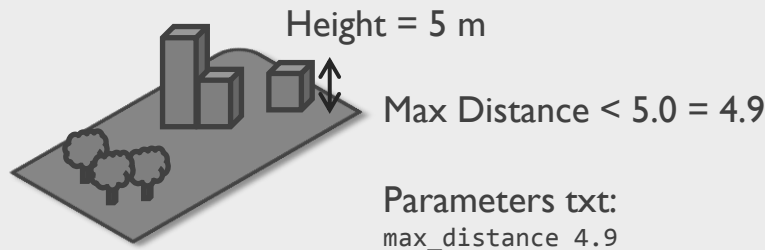
$\theta$	Slope
0.6°	0.01
1°	0.017
1.15°	0.02
1.19°	0.0208
2.86°	0.05
4.76°	0.083
7.13°	0.125
10°	0.176
14.04°	0.25
15°	0.268
26.57°	0.5
30°	0.577
45°	1
56.31°	1.5
60°	1.732
63.43°	2
78.69°	5
89.43°	10
90°	inf.



# Max Distance

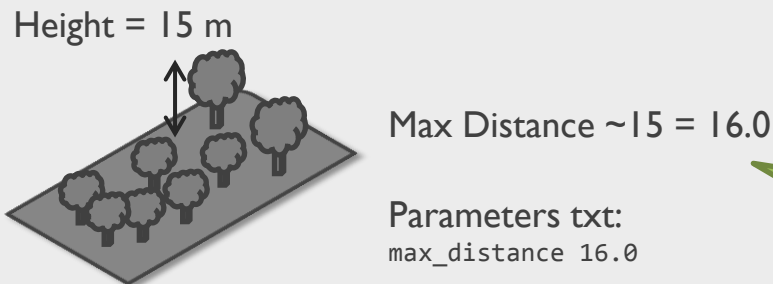
The maximum elevation difference threshold

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Type: float  
Range: (0.0) – (115.7) [m]  
Default: 10.0

**Buildings area: FIXED**  
Max Distance has to be less than the lowest building height



**Forest area: NOT FIXED**  
Max Distance is usually set as the largest elevation difference threshold



# Initial Distance

The initial elevation difference threshold

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Initial Distance ~ 15 cm

Parameters txt:  
`initial_distance 0.15`

Type: float  
Range: (0.00) – (1.00) [m]  
Default: 0.15

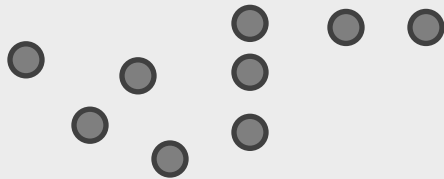
Usually set to a very  
small value.  
Approximately equal  
to the LIDAR  
measurement error.



# Cell Size

## Grid cell size

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Average Spacing between  
points = 0.44

$$\text{Cell Size} < 0.44 / 2 = 0.2$$

Parameters txt:  
cell\_size 0.2

Type: float  
Range: (0.0) – (10.0) [m]  
Default: 1.0

To preserve most of the  
original points, we choose  
the cell size to be about two  
times less than the average  
spacing between points



# Exponential

Way to increase the window size

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$$w_k = 2b^k + 1$$

Exponential = True

Parameters txt:  
exponential true

Type: bool  
Range: true / false  
Default: true

**EXPONENTIAL:**  
Saves  
computational time

$$w_k = 2kb + 1$$

Exponential = False

Parameters txt:  
exponential false

**LINEAR:**  
Gradually changing  
topographic features  
are well preserved



# Base

The radius of the initial window size

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$$w_k = 2b^k + 1$$
$$b = 2; w = 5, 9, 17, 33 \dots$$

Base = 2.0

Parameters txt:  
base 2.0

Type: float  
Range: (0.0) – (10.0)  
Default: 2.0

**EXPONENTIAL:**  
Base usually set to  
2.0

$$w_k = 2kb + 1$$
$$b = 1; w = 3, 5, 7, 9, \dots$$

Base = 1.0

Parameters txt:  
base 1.0

**LINEAR:**  
Base usually set  
to 1.0