

EE381 HW 7

Lewis Collum

Updated: April 3, 2020

1 - BIOT-SAVART LAW

A - Compared to Coloumb's Law

Similarities:

- Proportional to $1/R^2$
- Work on the principle of superposition

Differences:

- Coulomb's
 - Point charge produces electric field
 - Direction of E is radial to point charge
- Biot-Savart's
 - Current element produces magnetic field
 - Direction of B is perpendicular to \hat{r}

B - Magnetic Field Intensity (H) from a line at a point

$$\vec{H} = \frac{I}{4\pi} \int \frac{d\vec{l} \times \hat{r}}{r^2}$$

$$d\vec{l} \times \hat{r} = dz(\hat{z} \times \hat{r})$$

$$= dz \cdot \hat{\phi} \sin \theta$$

$$= \frac{I \hat{\phi}}{4\pi} \int \frac{\sin \theta dz}{r^2}$$

$$\sin \theta = \frac{z}{r}$$

$$r = \sqrt{x^2 + y^2 + z^2}$$

$$= \frac{I \hat{\phi}}{4\pi} \int \frac{z dz}{(x^2 + y^2 + z^2)^{3/2}}$$

$$\int \frac{z dz}{(x^2 + y^2 + z^2)^{3/2}} = \frac{1}{(\sqrt{x^2 + y^2})^2} \left[\frac{z}{(\sqrt{x^2 + y^2 + z^2})^2} \right]_a^b$$

$$= \frac{I \hat{\phi}}{4\pi \sqrt{x^2 + y^2}} \cdot \left[\frac{b}{\sqrt{x^2 + y^2 + b^2}} - \frac{a}{\sqrt{x^2 + y^2 + a^2}} \right] \checkmark$$

2 - SOLENOID

$$\oint \vec{B} \cdot d\vec{s} = \mu_0 I_{enc}$$

$$\int_{TOP} \vec{B} \cdot d\vec{s} + \int_{BOTTOM} \vec{B} \cdot d\vec{s} + \int_{LEFT} \vec{B} \cdot d\vec{s} + \int_{RIGHT} \vec{B} \cdot d\vec{s} = \mu_0 I_{enc}$$

$$0 + 0 + 0 + \vec{B}l = \mu_0 I_{enc}$$

$$\vec{B} = \frac{\mu_0 I_{enc}}{l}$$

$$\vec{B} = \frac{\mu_0 I N}{l} \hat{z} \checkmark$$

3 - TOKAMAK

A - without E

$$F = F_c + F_m$$

$$= e\vec{E} + e\vec{v}_0 \times \vec{B}$$

$$= e\vec{v}_0 \times \vec{B} \sin 90^\circ$$

$$= e\vec{v}_0 \times \vec{B}$$

$$F_c = \frac{mv_0^2}{R} = e v_0 B \quad \text{CENTRIPETAL FORCE}$$

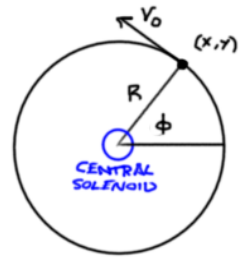
$$\rightarrow R = \frac{mv_0}{eB} \checkmark$$

$$x(t) = R \cos\left(\frac{v_0 t}{R}\right) \hat{x} = \frac{mv_0}{eB} \cos\left(\frac{eBt}{m}\right)$$

$$y(t) = R \sin\left(\frac{v_0 t}{R}\right) \hat{y} = \frac{mv_0}{eB} \sin\left(\frac{eBt}{m}\right)$$

$$v_x(t) = -v_0 \sin\left(\frac{v_0 t}{R}\right) \hat{x} = -v_0 \sin\left(\frac{eBt}{m}\right)$$

$$v_y(t) = v_0 \cos\left(\frac{v_0 t}{R}\right) \hat{y} = v_0 \cos\left(\frac{eBt}{m}\right)$$



$$\phi = \frac{v_0 t}{R}$$

$$= \frac{v_0 t}{\frac{mv_0}{eB}}$$

$$= \frac{eBt}{m}$$

B - with E

$$F = F_e + F_m$$

$$= e\vec{E} + e\vec{v}_0 \times \vec{B}$$

$$= e\vec{E} + e\vec{v}_0 \times \vec{B} = \frac{mv_0^2}{R}$$

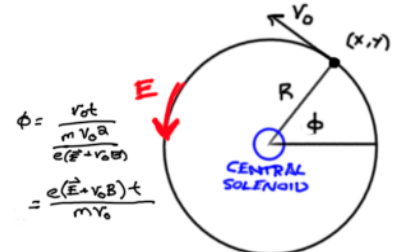
$$\rightarrow R = \frac{mv_0^2}{e(\vec{E} + v_0 B)}$$

$$x(t) = R \cos\left(\frac{v_0 t}{R}\right) \hat{x} = \frac{mv_0^2}{e(\vec{E} + v_0 B)} \cos\left(\frac{e(\vec{E} + v_0 B)t}{mv_0}\right) \hat{x}$$

$$y(t) = R \sin\left(\frac{v_0 t}{R}\right) \hat{y} = \frac{mv_0^2}{e(\vec{E} + v_0 B)} \sin\left(\frac{e(\vec{E} + v_0 B)t}{mv_0}\right) \hat{y}$$

$$v_x(t) = -v_0 \sin\left(\frac{v_0 t}{R}\right) \hat{x} = -v_0 \sin\left(\frac{e(\vec{E} + v_0 B)t}{mv_0}\right) \hat{x}$$

$$v_y(t) = v_0 \cos\left(\frac{v_0 t}{R}\right) \hat{y} = v_0 \cos\left(\frac{e(\vec{E} + v_0 B)t}{mv_0}\right) \hat{y}$$



4 - SLIDING BAR

MOTIONAL

$$V_{emf} = \oint_C (\vec{v} \times \vec{B}) \cdot d\vec{l}$$

$$= \int_{BAR} (\vec{v} \hat{x} \times B_0 \hat{y}) \cdot (-\hat{z} dl)$$

$$= v B_0 \sin 90^\circ \cdot l$$

$$= v B_0 l \text{ across BAR}$$

$$V_{emf} = v B_0 l \text{ across R}$$

$$x_0 = vt$$

$$= 1 \text{ m/s} \cdot t$$

$$x_0 = t$$

$$l = 1 \text{ m}$$

$$= B_0 t$$

$$I_R = \frac{V_{emf}}{R}$$

$$= \frac{B_0 t}{10 \Omega}$$

$$= \frac{1}{10} B_0 t$$

LENZ

$$\Phi = \int_S \vec{B} \cdot d\vec{s}$$

$$= \int_S (\hat{y} B_0 \hat{x}) \cdot \hat{y} dx (-dz)$$

$$= -B_0 l \int_0^{x_0} x dx$$

$$= -\frac{B_0 l x_0^2}{2}$$

$$= -\frac{B_0 l (vt)^2}{2}$$

$$= -\frac{B_0 \cdot 1 \text{ m} \cdot (1 \text{ m/s} \cdot t)^2}{2}$$

$$= -\frac{B_0 t^2}{2}$$

$$V_{emf} = -\frac{d\Phi}{dt}$$

$$= -\frac{d}{dt} \left[-\frac{B_0 t^2}{2} \right]$$

$$= B_0 t$$

$$I_R = \frac{V_{emf}}{R}$$

$$= \frac{1}{10} B_0 t$$

CURRENT FLOWING FROM
BOTTOM OF RESISTOR
TO TOP.