

Project Evaluation - Questionnaire

Thank you for taking part in the evaluation! If you could please complete the following questions to the best of your ability.

***Required**

1. What phone model did you use during the evaluation? *

Intuitiveness and Ease of Use

This section will ask you questions regarding how easy the controller was to learn and use

2. How difficult did you find changing the settings on the robot?
This includes looking at the User Manual if needed

Mark only one oval.

Very easy

1

☐

2

☐

3

☐

4

☐

5

☐

6

☐

7

☐

8

☐

9

☐

10

☐

Very difficult

3. How difficult did you find connecting to the robot?
This includes looking at the User Manual if needed

Mark only one oval.

Very easy

1

☐

2

☐

3

☐

4

☐

5

☐

6

☐

7

☐

8

☐

9

☐

10

☐

Very difficult

4. How difficult did you find setting up the Virtual Lead feature?
This includes looking at the User Manual if needed

Mark only one oval.

Very easy

1

☐

2

☐

3

☐

4

☐

5

☐

6

☐

7

☐

8

☐

9

☐

10

☐

Very difficult

5. Overall, how intuitive did you find the controller to use (i.e. was it easy to learn **without** the user manual)?

Mark only one oval.

Not intuitive at all

1

☐

2

☐

3

☐

4

☐

5

☐

6

☐

7

☐

8

☐

9

☐

10

☐

Very intuitive

6. How often did you have to consult the user manual?

Mark only one oval.

- ☐ Not at all
- ☐ A couple of times
- ☐ Quite often
- ☐ A lot

7. If you used it, how helpful was the user manual in teaching you what to do?

Mark only one oval.

Not very helpful

1

☐

2

☐

3

☐

4

☐

5

☐

6

☐

7

☐

8

☐

9

☐

10

☐

Very helpful

8. Any other feedback regarding intuitiveness of the controller or the user manual?

Functionality and Responsiveness

This question will ask you questions regarding the responsiveness and functionality of the controller

9. Which angle-motor mapping did you prefer the best

Mark only one oval.

☐ Tight

☐ Loose

10. How difficult did you find it to navigate the robot around an **object** using either mapping on the **joystick**?

Mark only one oval.

Very easy

1

☐

2

☐

3

☐

4

☐

5

☐

6

☐

7

☐

8

☐

9

☐

10

☐

Very difficult

11. How difficult did you find it to navigate the robot through the **slalom** using either mapping on the **joystick**?

Mark only one oval.

Very easy

1

☐

2

☐

3

☐

4

☐

5

☐

6

☐

7

☐

8

☐

9

☐

10

☐

Very difficult

12. How difficult did you find navigating the robot around the **object** using the **Virtual Lead** feature?

Mark only one oval.

Very easy

1

☐

2

☐

3

☐

4

☐

5

☐

6

☐

7

☐

8

☐

9

☐

10

☐

Very difficult

13. How responsive did you find the joystick to use?
Did it start and stop when you wanted it to? Did it respond well to movements of the joystick?

Mark only one oval.

Not very responsive

1

2

3

4

5

6

7

8

9

10

Very responsive

14. How responsive did you find the Virtual Lead feature to use?
Did it start and stop when you wanted it to? Did it respond well to movements of the camera?

Mark only one oval.

Not very responsive

1 ☐

2 ☐

3 ☐

4 ☐

5 ☐

6 ☐

7 ☐

8 ☐

9 ☐

10 ☐

Very responsive

Competition Website

This section will ask you questions regarding the website for the competition

15. What is your understanding of what the competition is?

16. Were the rules easy to find and clear to read?

17. Would you be interested in entering such a competition?

Final Feedback

This section is for any final feedback regarding the controller and competition website.

18. Did you experience any problems while using the **controller**? If so please detail then below

19. Do you have any more feedback to provide about the **controller**?

This can include any features you wished the controller had or any improvements to its design or functionality

20. Do you have any more feedback to provide about the **competition website**?

This can include any features you wished the controller had or any improvements to its design or functionality

This content is neither created nor endorsed by Google.

Google Forms

