## Project Evaluation - Questionnaire

Thank you for taking part in the evaluation! If you could please complete the following questions to the best of your ability.

What phone model did you use during the evaluation? \* Google Pixel 7

Intuitiveness and Ease of Use

This section will ask you questions regarding how easy the controller was to learn and use

0/03/2023, 23.	1 Toject Evaluation - Questionnaire
	fficult did you find changing the settings on the robot?
Very ea	asy
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2	
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7	
8	
9	
10	
Very di	fficult

0/03/2023, 23.1	Troject Evaluation - Questionnaire	
This inc	How difficult did you find connecting to the robot?  This includes looking at the User Manual if needed	
Very ea	sy	
1		
2		
3		
4		
5		
6		
7		
8		
9		
10		
Very dif	ficult	

703/2023, 23:15 Project Evaluation - Questionnaire	
	fficult did you find setting up the Virtual Lead feature?  Iudes looking at the User Manual if needed
Very ea	sy
1	
2	
3	
4	
5	
6	
7	
8	
9	
10	
Very di	fficult

Overall, how intuitive did you find the controller to use (i.e. was it easy to learn <b>without</b> the user manual)?
Not intuitive at all
1
2
3
4
5
6
7
8
9
10
Very intuitive
How often did you have to consult the user manual?
O Not at all
A couple of times
Quite often
O A lot

If you used it, how helpful was the user manual in teaching you what to do?	
Not very helpful	
1 (	
2	
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10	
Very helpful	
Any other feedback regarding intuitiveness of the controller or the user manual?	
Functionality and Responsiveness	

This question will ask you questions regarding the responsiveness and functionality of the controller

Tight	
Loos	se
How diffi	cult did you find it to navigate the robot around an <b>object</b> using either mapping on the
joystick′	
Very easy	у
1 (	
2 (	
3 (	
4 (	
5 (	
6 (	
7 (	
8 (	
9 (	
10 (	
Very diffi	cult

he <b>joy</b> s	ficult did you find it to navigate the robot through the <b>slalom</b> using either mapping on <b>stick</b> ?
Very ea	sy
1	
2	
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7	
8	
9	
10	

0,00,2020, 20.	· i sjoot I talaansi. Qaasaanii aa
How d	ifficult did you find navigating the robot around the <b>object</b> using the <b>Virtual Lead</b>
Very e	asy
1	
2	
3	
4	
5	
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7	
8	
9	
10 Very d	ifficult

How responsive did you find the joystick to use?  Did it start and stop when you wanted it to? Did it respond well to movements of the joystick?		
Not very responsive		
1		
2		
3		
4		
5		
6		
7		
8		
9		
10		
Very responsive		

How responsive did you find the Virtual Lead feature to use?  Did it start and stop when you wanted it to? Did it respond well to movements of the camera?
Not very responsive
1
2
3
4
5
6
7
8
9
10
Very responsive
Competition Website
This section will ask you questions regarding the website for the competition
What is your understanding of what the competition is?
The competition is where people can enter code to control a robot and it will be raced on a track.
Were the rules easy to find and clear to read?  Yes they were easy to find; however, reading a wall of text was a a bit daunting

Would you be interested in entering such a competition?	
Yes	
Final Feedback	
This section is for any final feedback regarding the controller and competition website.	
Did you experience any problems while using the <b>controller</b> ? If so please detail then below	
The virtual lead feature could be quite slow	
Do you have any more feedback to provide about the <b>controller</b> ?	
This can include any features you wished the controller had or any improvements to its design or functionality	
Do you have any more feedback to provide about the <b>competition website</b> ?	
This can include any features you wished the controller had or any improvements to its design or functionality	
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