

plan

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1 work basket

1.1 Some extra reading:

google search: Behaviour-based robotics, subsumption architecture.

1.2 revise thesis under the supervisor's requirements

1.3 different behaviours

1.4 spider movement without changing distance

1.4.1 run

1.4.2 walk

1.4.3 walk right/walk left

1.4.4 turn around

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1.6 revise thesi

2 Tasks

2.1 DONE draw 5 eye ray

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2.6 run towards fly[0%]

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3 leisure

3.1 novels

1. star

2. god