July 20 week report

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| 1 | Work done: | |
| 1. | .1 Cameras | |
| pr | ress v to switch cameras | |
| | 1. auto follow camera | |
| | 2. controllable follow camera operation instructions: | |
| | (a) use $>$ or $<$ key to change the dist between the spider and camera | $	h\epsilon$ |
| | (b) use $w/a/s/d$ to rotate | |
| | 3. world camera | |

- 2 Report revision
- 3 Extra reading
- 4 Different behaviours