

plan

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1 work today

1.1 spider movement without changing distance

1.1.1 run

1.1.2 walk

1.1.3 walk right/walk left

1.1.4 turn around

1.2 read one paper and write notes

1.3 revise thesi

2 work basket

2.1 Some extra reading:

google search: Behaviour-based robotics, subsumption architecture.

2.2 revise thesis under the supervisor's requirements

2.3 different behaviours