

ivp1-otchet-checkpoint

May 11, 2024

1

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[9]: import numpy as np
import matplotlib.pyplot as plt

def solve_ode(start, end, h, max_calls, eps, fs, initial_conditions):
    t = start
    v = np.array(initial_conditions)
    kounter = [0]
    print(f"{t_0:13.6f}-{h:13.6f}-{0:13d}-{0:13d}", *[f"{x:12.6f}" for x in v])

    def heun_step(t, v, h):
        k1 = fs(t, v, kounter)
        k2 = fs(t + h, v + h * k1, kounter)
        return v + (h / 2) * (k1 + k2)

    steps = []
    min_steps = []
    num_steps = []
    solutions = []

    while t < end and kounter[0] < max_calls:

        k1 = fs(t, v, kounter)
        k2 = fs(t + h, v + h * k1, kounter)
        v1 = v + (h / 2) * (k1 + k2)

        k2 = fs(t + h/2, v + h/2 * k1, kounter)
        v2 = v + (h / 4) * (k1 + k2)

        v2 = heun_step(t + h/2, v2, h/2)

        r = np.linalg.norm(v2 - v1) / 3

        if r > eps:
            h /= 2
            steps.append(h)
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elif r < eps / 64:
    h *= 2
    steps.append(h)
else:
    if t + h > end:
        h = end - t
    t += h
    v = v1
    steps.append(h)
    solutions.append(v)
    num_steps.append(kounter[0])
    min_steps.append(h)
    print(f"{t:13.6f}{h:13.6f}{r:13.5e}{kounter[0]:13d}", *[f"{x:12.
↪6f}" for x in v])

return steps, min_steps, num_steps, solutions

```

2

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[10]: t_0 = 1.5
      T = 2.5
      h_0 = 0.1
      N_x = 10000
      eps = 0.0001
      n = 3

```

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[11]: def fs(t, v, kounter):
      A = np.array([[-0.4, 0.02, 0], [0, 0.8, -0.1], [0.003, 0, 1]])
      kounter[0] += 1
      return np.dot(A, v)

initial_conditions = [1, 1, 2]

```

3

```

[12]: steps, min_steps, num_steps, solutions = solve_ode(t_0, T, h_0, N_x, eps, fs,
↪initial_conditions)

```

1.500000	0.100000	0	0	1.000000	1.000000
2.000000					
1.600000	0.100000	8.45154e-05	5	0.962820	1.061398
2.210309					
1.700000	0.100000	9.33737e-05	10	0.927221	1.125613
2.442690					
1.750000	0.050000	1.28171e-05	20	0.909992	1.158775

2.568019						
1.800000	0.050000	1.34742e-05	25	0.893138	1.192634	
2.699768						
1.850000	0.050000	1.41654e-05	30	0.876652	1.227187	
2.838267						
1.900000	0.050000	1.48925e-05	35	0.860527	1.262426	
2.983862						
1.950000	0.050000	1.56573e-05	40	0.844756	1.298342	
3.136916						
2.000000	0.050000	1.64617e-05	45	0.829333	1.334924	
3.297812						
2.050000	0.050000	1.73079e-05	50	0.814253	1.372157	
3.466951						
2.100000	0.050000	1.81979e-05	55	0.799508	1.410026	
3.644757						
2.150000	0.050000	1.91341e-05	60	0.785092	1.448511	
3.831672						
2.200000	0.050000	2.01189e-05	65	0.771001	1.487590	
4.028165						
2.250000	0.050000	2.11548e-05	70	0.757227	1.527236	
4.234726						
2.300000	0.050000	2.22444e-05	75	0.743766	1.567420	
4.451871						
2.350000	0.050000	2.33906e-05	80	0.730612	1.608110	
4.680143						
2.400000	0.050000	2.45962e-05	85	0.717758	1.649267	
4.920111						
2.450000	0.050000	2.58644e-05	90	0.705200	1.690849	
5.172377						
2.500000	0.050000	2.71984e-05	95	0.692932	1.732810	
5.437568						
2.500000	0.000000	2.86017e-05	100	0.680948	1.775097	
5.716349						

4

4.0.1

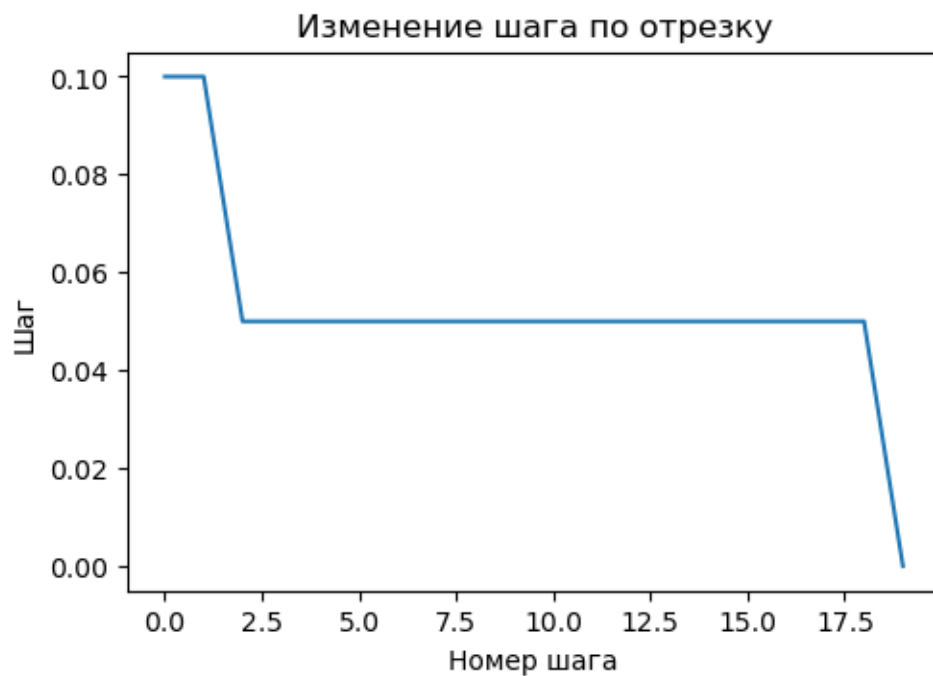
```
[13]: plt.figure(figsize=(12, 8))

plt.subplot(2, 2, 1)
plt.plot(range(len(steps)), steps)
plt.xlabel(' ')
plt.ylabel(' ')
plt.title(' ')

```

```
[13]: Text(0.5, 1.0, ' ')

```

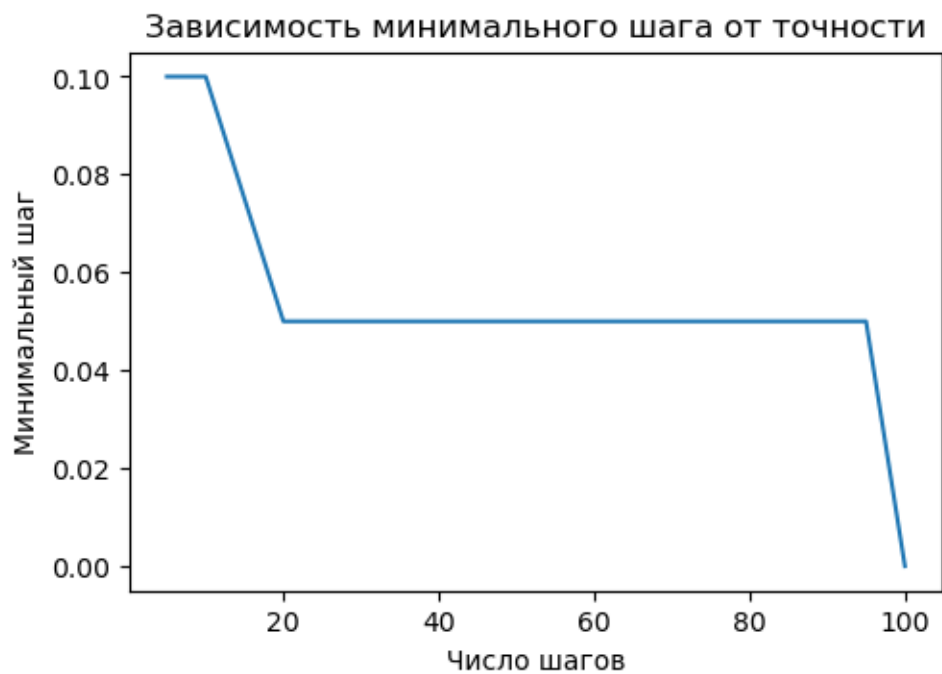


4.0.2

```
[14]: plt.figure(figsize=(12, 8))

plt.subplot(2, 2, 2)
plt.plot(num_steps, min_steps)
plt.xlabel('')
plt.ylabel('')
plt.title('')
```

```
[14]: Text(0.5, 1.0, '')
```

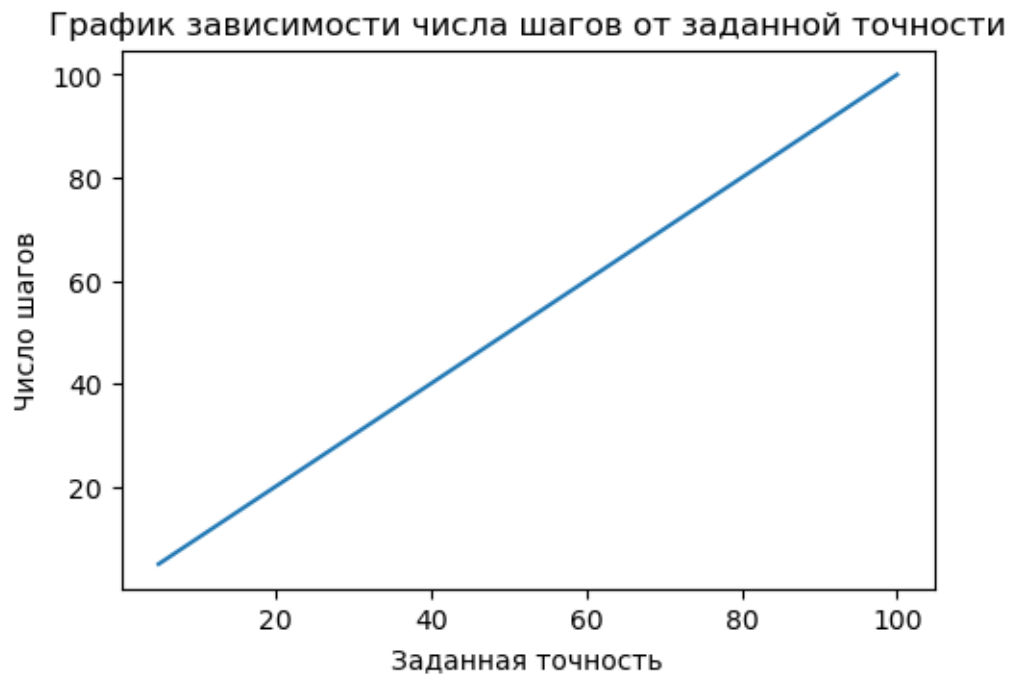


4.0.3

```
[15]: plt.figure(figsize=(12, 8))

plt.subplot(2, 2, 3)
plt.plot(num_steps, num_steps)
plt.xlabel(' ')
plt.ylabel(' ')
plt.title(' ')
```

```
[15]: Text(0.5, 1.0, ' ')
```



4.0.4

```
[16]: plt.figure(figsize=(12, 8))

plt.subplot(2, 2, 4)
t = np.linspace(t_0, T, len(solutions[0]))
for i, sol in enumerate(solutions):
    plt.plot(t, sol, label=f"eps={eps*(2**i):.4f}")
    plt.xlabel('t')
    plt.ylabel(' ')
    plt.title(' ')
    plt.legend()
```

