

Gather - Scatter

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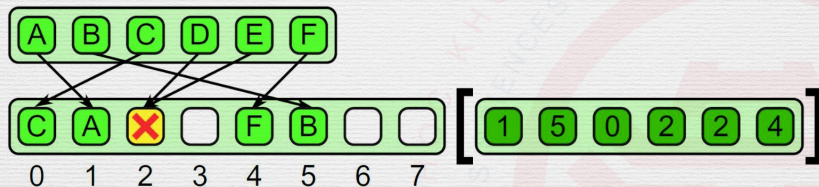
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Scatter

What?

- “Sequential read, scattered random write”
- A relationship *from input* to output
- Smaller set of values is distributed (**written**) into another array
 - [Optional] with an index vector
- There may be gaps in the output array
- Highly memory intensive

What?



Why?

- Efficient memory access
 - Pre-cache contents
- AoS to SoA
- Building block of other algorithms
 - e.g. Radix sort

How?

In serial fashion

```
for (int i = 0; i < N; i++) {  
    out[idx[i]] = in[i];  
}
```

In parallel

```
int tid = ...;  
out[idx[threadIdx.x]] = in[tid]; // lookup  
out[tid * 3] = in[tid];          // strided write  
}
```


Examples

- RGB to Gray

```
out[tid].x = out[tid].y = out[tid].z = gray;
```

- RGB to HSL

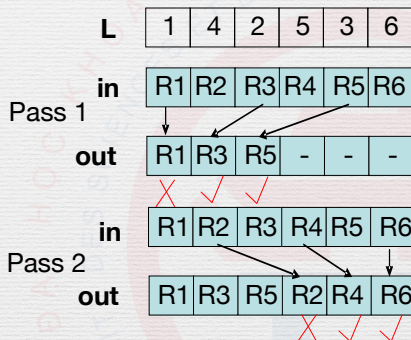
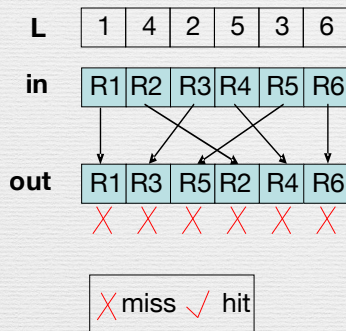
```
outh[tid] = h;  
outs[tid] = s;  
outl[tid] = l;
```

Optimization

- Exploit cache locality
- Multi-pass scatter ¹
 - n passes
 - Divide output to n areas
 - In i^{th} pass
 - Check destination
 - Write only if in i^{th} area

¹Efficient Gather and Scatter Operations on Graphics Processors

Optimization



Labwork 8: Scatter

- To prepare for the next “Gather” labwork, we need to convert the input image:
 - From RGB to HSV, from AoS to SoA: to 3 different arrays ($H[]$, $S[]$, $V[]$)
 - Reversely, from HSV to RGB, from SoA to AoS
- Implement the two scatter 2D kernels `RGB2HSV()` and `HSV2RGB()`
- Test the two kernels for a sample image (convert to HSV and convert back to RGB), compare the output with the input image
- Write a report (in $\text{L}^{\text{A}}\text{T}_{\text{E}}\text{X}$)
 - Name it « `Report.8.scatter.tex` »
 - Explain how you implement the labworks
 - Explain and measure speedup, if you have performance optimizations
- Push the report and your code to your forked repository

Extra: HSV

- Hue, Saturation, Value
 - $H \in [0..360]$: “The color”. Red? Yellow? Cyan? Magenta?
 - $S \in [0..1]$: “The colorfulness”. Really cyan? Light yellow?
 - $V \in [0..1]$: “The brightness”. Dark cyan? Crimson?

Extra: RGB to HSV

- Preparation
 - Scale R, G, B to $[0..255]$ to $[0..1]$
 - Find max and min among $R, G, B \in [0..1]$
 - $\Delta = max - min$
- Conversion

$$H = \begin{cases} 0^\circ & \Delta = 0 \\ 60^\circ \times (\frac{G-B}{\Delta} \bmod 6) & max = R \\ 60^\circ \times (\frac{B-R}{\Delta} + 2) & max = G \\ 60^\circ \times (\frac{R-G}{\Delta} + 4) & max = B \end{cases}$$

$$S = \begin{cases} 0 & max = 0 \\ \frac{\Delta}{max} & max \neq 0 \end{cases}$$

$$V = max$$

Extra: HSV to RGB

- Preparation

- $d = H/60$
- $hi = (int)d \bmod 6$
- $f = d - hi$

- Conversion

- $l = V \times (1 - S)$
- $m = V \times (1 - f \times S)$
- $n = V \times (1 - (1 - f) \times S)$

$$(R, G, B) = \begin{cases} (V, n, l) & 0^\circ \leq H < 60^\circ \\ (m, V, l) & 60^\circ \leq H < 120^\circ \\ (l, V, n) & 120^\circ \leq H < 180^\circ \\ (l, m, V) & 180^\circ \leq H < 240^\circ \\ (n, l, V) & 240^\circ \leq H < 300^\circ \\ (V, l, m) & 300^\circ \leq H < 360^\circ \end{cases}$$

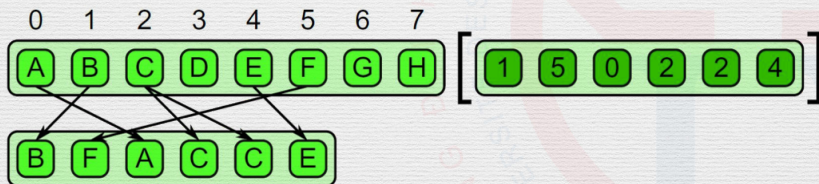
- Scale R, G, B from $[0..1]$ to $[0..255]$



Gather

What?

- “Gathered random read, sequential write”
- A relationship *from output* to input
- Large set of values are **read** from an array
 - [Optional] with an index vector
- No gap in the output array
- Highly memory intensive



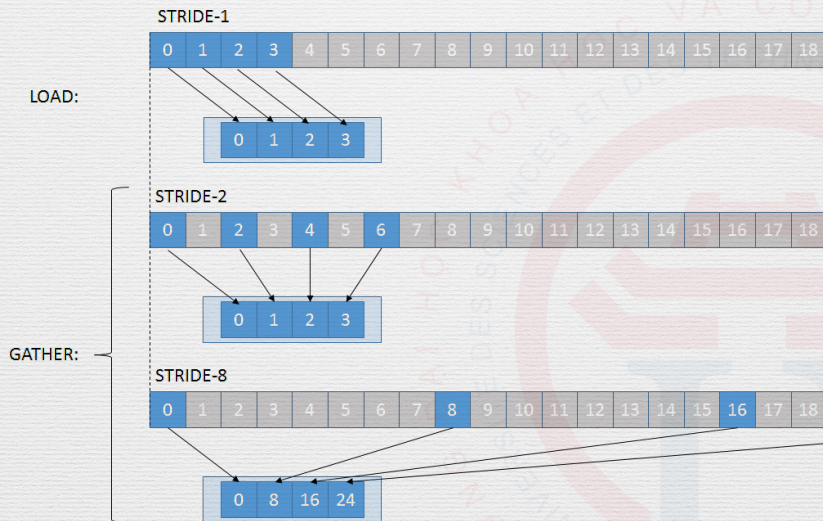
Why?

- SoA to AoS
 - Efficient memory access
- Building block of other algorithms
 - e.g. Radix sort

Why?

- Strided memory access
 - Memory fields accessed are equally distant
 - Called a stride
- Gathered \Rightarrow contiguous access

Why?



How?

In serial fashion

```
for (int i = 0; i < N; i++) {  
    out[i] = in[idx[i]];  
}
```

In parallel

```
int tid = ...;  
out[tid] = in[idx[threadIdx.x]]; // <-- lookup  
out[tid] = in[tid * 3];           // strided read  
}
```

Example

- RGB to gray

```
char gray = (in[tid].x + in[tid].y + in[tid].z) / 3;
```

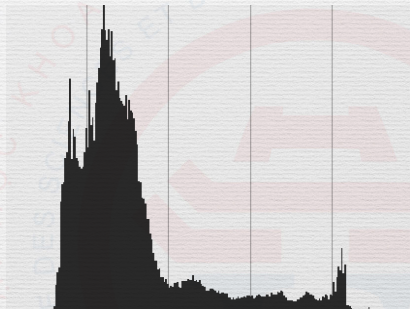

Labwork 9: Histogram Equalization

- Implement labwork 9a: Histogram
 - Calculate histogram of input **grayscale** image
- Implement labwork 9b: Histogram Equalization for **grayscale** image
 - Equalize the histogram for that input image
- Write a report (in L^AT_EX)
 - Name it « Report.9.gather.tex »
 - Explain how you implement the labworks
 - Explain and measure speedup, if you have performance optimizations
- Push the report and your code to your forked repository

Extra 9a: Histogram

- Graphical representation of the value distribution in a digital image
 - Divide range of values to certain ranges (“bins”)
 - Count number of value occurrences for each “bin”
- For image: an array, each element i in the array counts the number of pixels having gray level i

Extra 9a: Histogram



Extra 9a: Histogram

In serial

```
for (int y = 0; y < height; y++) {  
    for (int x = 0; x < width; x++) {  
        histo[input[y][x]]++;  
    }  
}
```

Extra 9a: Histogram

In parallel: 2 ways

- Atomic operations
 - Race condition due to parallelization
 - Not discussed this week. Next week with Prof. Lillian Aveneau.
- Local histogram
 - Each thread calculates a local histogram `lhisto[]` of a region in image (GATHER)
 - A sum is then combined for all regions (REDUCTION)

Extra 9b: Histogram Equalization

- Previously, grayscale stretch (LW 6)
 - Increases global contrast
 - Linearly calculates intensity of each pixel from $[min..max]$ to $[0..255]$
- Histogram equalization
 - Increases global contrast
 - Recalculates intensity using normalization of cumulative distribution function

Extra 9b: Histogram Equalization

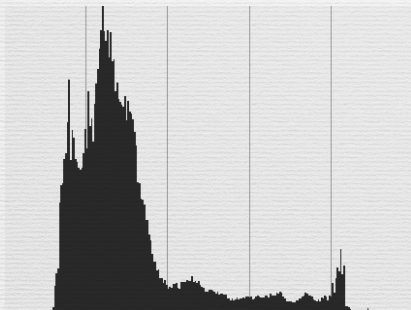


Original

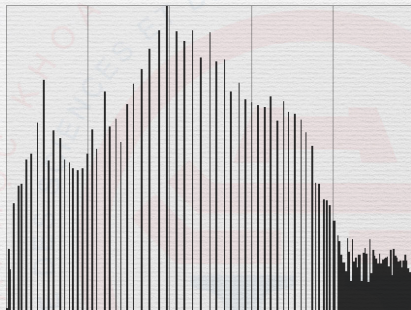


Equalized

Extra 9b: Histogram Equalization



Original



Equalized

Extra 9b: Histogram Equalization

- Calculate histogram `histo[]` (LW8a, GATHER + REDUCE)
- Let n be number of total pixels in the image
- Calculate probability of given intensity j (MAP)

$$p_j = \frac{histo_j}{n}, \forall j \in [0..255]$$

Extra 9b: Histogram Equalization

- Cumulative distribution function (CDF) c is calculated as ²

$$c_i = \sum_{j=0}^i p_j$$

- Linearly scale $c_i \in [0..1]$ to $h_i \in [0..255]$, $\forall i \in [0..255]$ (MAP)
- Original intensity i is transformed to h_i (MAP)
- We should have histogram equalized as now.

² c_i in this case should be calculated using parallel SCAN, but you haven't learnt about it yet. Let's do this step in sequential fashion.

Final Labwork: Fine-art transformation

- Implement Kuwahara filter
- Write a report (in L^AT_EX)
 - Name it « Report.10.kuwahara.tex »
 - Explain how you implement the labworks
 - Explain and measure speedup, if you have performance optimizations
- Push the report and your code to your forked repository

Final Labwork: Fine-art transformation

- Kuwahara filter [[wikipedia](#)]
 - Reduces noise
 - Keeps edge
 - Also produces oil effect
 - Requires a lot of computation!

Final Labwork: Fine-art transformation

- Parameter ω as window size
- Convert RGB to HSV (SCATTER)
- For each pixel $\Phi(i, j)$
 - Define use 4 windows $W^k, k \in [1..4]$ of size $(\omega + 1) \times (\omega + 1)$
 - $W_x^1 \in [i - \omega, i], W_y^1 \in [j - \omega, j]$
 - $W_x^2 \in [i, i + \omega], W_y^2 \in [j - \omega, j]$
 - $W_x^3 \in [i - \omega, i], W_y^3 \in [j, j + \omega]$
 - $W_x^4 \in [i, i + \omega], W_y^4 \in [j, j + \omega]$

Final Labwork: Fine-art transformation

		a	a	a	a/b	b	b	b	b								
		a	a	a	a/b	b	b	b	b								
		a	a	a	a/b	b	b	b	b								
		a/c	a/c	a/c	x	b/d	b/d	b/d									
		c	c	c	c/d	d	d	d									
		c	c	c	c/d	d	d	d									
		c	c	c	c/d	d	d	d									

Example $\omega = 3$

Final Labwork: Fine-art transformation

- Find $W_l, l \in [1..4]$ having lowest standard deviation of brightness.
 - Use V in HSV color space to calculate SD.
- Assign mean (R, G, B) value of this window $|W_l|_{RGB}$ as new color (REDUCE, MAP)

$$\Phi(i, j)_{RGB} = |W_l|_{RGB}$$

Good luck & Have fun