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## EE368 Lab Assignment: Dynamics

Spring 2025

Group Assignment: Dynamics

Due Date: 6.1 23:59

### Reference Material:

- Chapter 6 of Introduction to Robotics

### Task:

1. Add comments to function *get\_torque* in *Dynamics.py*
2. Move the manipulator and draw the curves of the real torques and the calculated torques for each joint. Describe the curve. (hint: use *rqt\_plot*)

### Submission:

Submit code with comments and report.