

Education

- **The University of Tokyo** Oct. 2023 – Sept. 2026 (Expected)
Ph. D. Student in Mechanical Engineering Advisor: Lecturer [Moju ZHAO](#)
- **Beihang University** Sept. 2020 – June 2023
M. Sc. in Control Science and Engineering, GPA: 89.8/100 (Top 10%) Advisor: Prof. [Zhang REN](#)
- **Beihang University** Sept. 2016 – June 2020
B. Eng. in Automation, ShenYuan Honors College, GPA: 89.7/100 (Top 10%) Supervisor: Prof. [Lei GUO](#)

Research Interests

My research interest lies in optimization-based control with applications in aerial manipulation, aiming to make aerial robots function as flying hands rather than just eyes.

Publications

Papers

1. **[IROS'25]** [Jinjie Li](#)^{†*}, Jiaxuan Li[†], Kotaro Kaneko, Haokun Liu, Liming Shu, Moju Zhao, “Six-DoF Hand-Based Teleoperation for Omnidirectional Aerial Robots”, *IEEE/RSJ International Conference on Intelligent Robots and Systems (IROS)*, Hangzhou, China, 2025. [\[pdf\]](#) [\[video\]](#)
2. **[RA-L'24]** [Jinjie Li](#), Junichiro Sugihara, Moju Zhao*, “Servo Integrated Nonlinear Model Predictive Control for Overactuated Tilttable-Quadrotors”, *IEEE Robotics and Automation Letters (RA-L)*, vol. 9, no. 10, pp. 8770-8777, Oct. 2024, doi: 10.1109/LRA.2024.3451391. [\[pdf\]](#) [\[video\]](#)
3. **[CDC'23]** [Jinjie Li](#), Liang Han*, Haoyang Yu, Yuheng Lin, Qingdong Li, Zhang Ren, “Nonlinear MPC for Quadrotors in Close-Proximity Flight with Neural Network Downwash Prediction”, *IEEE Conference on Decision and Control (CDC)*, Singapore, Singapore, 2023, pp. 2122-2128, doi: 10.1109/CDC49753.2023.10383632. [\[pdf\]](#) [\[code\]](#)
4. **[ICRA'23 Workshop]** [Jinjie Li](#)^{*}, Liang Han, Haoyang Yu, Yuheng Lin, Qingdong Li, Zhang Ren, “Potato: A Data-Oriented Programming 3D Simulator for Large-Scale Heterogeneous Swarm Robotics”, *ICRA'23 Workshop on The Role of Robotics Simulators for Unmanned Aerial Vehicles*, 2023. [\[pdf\]](#) [\[code\]](#)
5. **[ICRA'22]** [Jinjie Li](#), Liang Han*, Zhang Ren, “Indoor Localization for Quadrotors using Invisible Projected Tags”, *IEEE International Conference on Robotics and Automation (ICRA)*, Philadelphia, PA, USA, 2022, pp. 9404-9410, doi: 10.1109/ICRA46639.2022.9812449. [\[oral\]](#) [\[pdf\]](#) [\[video\]](#)

Co-Authored

6. **[IROS'25]** Yicheng Chen, [Jinjie Li](#), Wen yuan Qin, Yongzhao Hua, Qingdong Li, “Learning to Initialize Trajectory Optimization for Vision-Based Autonomous Flight in Unknown Environments”, *IEEE/RSJ International Conference on Intelligent Robots and Systems (IROS)*, Hangzhou, China, 2025. [\[pdf\]](#) [\[video\]](#) [\[code\]](#)
7. **[ICRA'25]** Hisaaki Iida, Junichiro Sugihara, Kazuki Sugihara, Haruki Kozuka, [Jinjie Li](#), Keisuke Nagato, Moju Zhao*, “Adaptive Perching and Grasping by Aerial Robot with Light-weight and High Grip-force Tendon-driven Three-fingered Hand using Single Actuator”, *IEEE International Conference on Robotics and Automation (ICRA)*, Atlanta, USA, 2025. [\[pdf\]](#) [\[video\]](#)
8. **[ICRA'23]** Ziwei Yan, Liang Han*, Xiaoduo Li, [Jinjie Li](#), Zhang Ren, “Event-Triggered Optimal Formation Tracking Control Using Reinforcement Learning for Large-Scale UAV Systems”, *IEEE International Conference on Robotics and Automation (ICRA)*, London, United Kingdom, 2023, pp. 3233-3239, doi: 10.1109/ICRA48891.2023.10160532. [\[pdf\]](#) [\[video\]](#)

Others

1. Liang Han, [Jinjie Li](#), Zhang Ren, “An Indoor Localization Method based on Invisible Projected Tags”, *Chinese Invention Patent*, 202111154577.4.
2. “A Localization Software based on Invisible Projected Fiducial Tags”, *Chinese Software Copyright*, 2022SR0123403.
3. “A Large-Scale Heterogeneous Multi-Agent Simulation Platform V1.0”, *Chinese Software Copyright*, 2021SR1039534.

Practical Experiences

Beihang Aeromodelling Team, Beihang University

Beijing, China

- **Development of Heavy Load and High Maneuverability Aircrafts**

Nov. 2016 – Oct. 2018

- *Leader of the Composite Material Team & Pilot*

Supervisor: Prof. Zhiqiang Wan

- Developed the composite part of a heavy-load aircraft. Employed carbon and glass fiber reinforced polymer (CGFRP) to make D-box structures, increasing the torsional rigidity to 261.07%. [\[blog\]](#) Trained to be a pilot as well. [\[blog\]](#)
- Won the championship in the 2018 China Aeromodelling Design Challenge (Time-limited Airdrop Project), the best record in history. Reported by *BMFA (British Model Flying Association) News* magazine. [\[pdf\]](#)

Skills Summary

- **Languages:** English (TOEFL iBT 100), Japanese (Beginner), Chinese (Mother Tongue)
- **Coding:** AI Prompt, Git, Python, C/C++, MATLAB, Mathematica, Zsh, \LaTeX , Data-Oriented Programming
- **Software:** ROS 1&2, acados, CasADi, Gazebo, PX4, PyTorch, OpenCV, Pandas, Docker, Eigen
- **Hardware:** NVIDIA Jetson, Raspberry Pi, STM32, Pixhawk, Circuit Design (Altium Designer), CAD (SolidWorks), CNC
- **Hobbies:** Model Airplane (pilot for fixed-wing drones and quadrotors), Photography [\[homepage\]](#), Tennis, Table Tennis, Ski

Leadership

As the first Ph.D. student in our lab, I play a key role in shaping a collaborative and productive research environment. I have successfully collaborated with researchers from China, Japan, Germany, and Italy, demonstrating strong international teamwork skills.

Honors and Awards

- PhD Scholarship from Chinese Scholarship Council (CSC) 2023
- The Champion of “Simulated Search and Rescue Project” in China Aeromodelling Design Challenge (CADC) 2017

Academic Services

Serve as reviewers for RA-L, IROS’25, ICRA’24, IROS’24, and CDC’23. IEEE RAS Graduate Student Member.