# Jinjie LI

Email: jinjie-li@dragon.t.u-tokyo.ac.jp
Homepage: jinjie.li

## Education

- **The University of Tokyo** — Oct. 2023 – Sept. 2026 (expected)
  *Doctoral Student in Mechanical Engineering* — *Advisor: Lecturer Moju ZHAO*
- **Beihang University** — Sept. 2020 – June 2023
  *M. Sc. in Control Science and Engineering, GPA: 89.8/100 (↑10%)* — *Advisor: Prof. Zhang REN*
- **Beihang University** — Sept. 2016 – June 2020
  *B. Eng. in Automation, ShenYuan Honors College, GPA: 89.7/100 (↑10%)* — *Supervisor: Prof. Lei GUO*

## Research Interests

My research interest lies in optimization-based control with applications in aerial manipulation, aiming to make aerial robots function as flying hands rather than just eyes.

## Publications

### Papers

1. **[RA-L'24]** Jinjie Li, Junichiro Sugihara, Moju Zhao, "Servo Integrated Nonlinear Model Predictive Control for Over-actuated Tiltable-Quadrotors", *IEEE Robotics and Automation Letters (RA-L)*, vol. 9, no. 10, pp. 8770-8777, Oct. 2024, doi: 10.1109/LRA.2024.3451391.. [pdf] [video]

2. **[CDC'23]** Jinjie Li, Liang Han, Haoyang Yu, Yuheng Lin, Qingdong Li, Zhang Ren, "Nonlinear MPC for Quadrotors in Close-Proximity Flight with Neural Network Downwash Prediction", *IEEE Conference on Decision and Control (CDC)*, Singapore, Singapore, 2023, pp. 2122-2128, doi: 10.1109/CDC49753.2023.10383632. [pdf]

3. **[ICRA'22]** Jinjie Li, Liang Han, Zhang Ren, "Indoor Localization for Quadrotors using Invisible Projected Tags", *IEEE International Conference on Robotics and Automation (ICRA)*, Philadelphia, PA, USA, 2022, pp. 9404-9410, doi: 10.1109/ICRA46639.2022.9812449. [oral] [pdf] [video]

4. **[ICRA'23 Workshop]** Jinjie Li, Liang Han, Haoyang Yu, Yuheng Lin, Qingdong Li, Zhang Ren, "Potato: A Data-Oriented Programming 3D Simulator for Large-Scale Heterogeneous Swarm Robotics", *ICRA'23 Workshop on The Role of Robotics Simulators for Unmanned Aerial Vehicles*, 2023. [pdf]

**Co-Authored**

5. **[ICRA'25]** Hisaaki Iida, Junichiro Sugihara, Kazuki Sugihara, Haruki Kozuka, Jinjie Li, Keisuke Nagato, Moju Zhao, "Adaptive Perching and Grasping by Aerial Robot with Light-weight and High Grip-force Tendon-driven Three-fingered Hand using Single Actuator", *IEEE International Conference on Robotics and Automation (ICRA)*, Atlanta, USA. [pdf] [video]

6. **[ICRA'23]** Ziwei Yan, Liang Han, Xiaoduo Li, Jinjie Li, Zhang Ren, "Event-Triggered Optimal Formation Tracking Control Using Reinforcement Learning for Large-Scale UAV Systems", *IEEE International Conference on Robotics and Automation (ICRA)*, London, United Kingdom, 2023, pp. 3233-3239, doi: 10.1109/ICRA48891.2023.10160532. [pdf] [video]

### Others

1. Liang Han, Jinjie Li, Zhang Ren, "An Indoor Localization Method based on Invisible Projected Tags", *Chinese Invention Patent*, 202111154577.4.
2. "A Localization Software based on Invisible Projected Fiducial Tags", *Chinese Software Copyright*, 2022SR0123403.
3. "A Large-Scale Heterogeneous Multi-Agent Simulation Platform V1.0", *Chinese Software Copyright*, 2021SR1039534.

## Practical Experiences

*Beihang Aeromodelling Team, Beihang University* — *Beijing, China*

- **Development of Heavy Load and High Maneuverability Aircrafts** — Nov. 2016 – Oct. 2018
  *Leader of the Composite Material Team & Pilot* — *Supervisor: Prof. Zhiqiang Wan*
  - Developed the composite part of a heavy-load aircraft. Employed carbon and glass fiber reinforced polymer (CGFRP) to make D-box structures, increasing the torsional rigidity to 261.07%. [blog] Trained to be a pilot as well. [blog]
  - Won the championship in the 2018 China Aeromodelling Design Challenge (Time-limited Airdrop Project), the best record in history. Reported by *BMFA (British Model Flying Association) News* magazine. [pdf]

## Skills Summary

- **Languages:** English (TOEFL iBT 100), Japanese (Beginner), Chinese (Mother Tongue)
- **Coding:** AI Prompt, Python, C/C++, MATLAB, Mathematica, Bash, Git, Data-Oriented Programming, LaTeX
- **Software:** ROS 1&2, ACADOS, CasADi, Gazebo, PX4, PyTorch, TensorFlow, OpenCV, Pandas, Eigen, Docker
- **Hardware:** NVIDIA Jetson, Raspberry Pi, STM32, Pixhawk, Circuit Design (Altium Designer), CAD (SolidWorks), CNC
- **Hobbies:** Model Airplane (pilot for fixed-wing drones and quadrotors), Photography [homepage], Tennis, Table Tennis, Ski

## Academic Services

Serve as reviewers for CDC'23, ICRA'24, IROS'24, IROS'25, and RA-L.