

# Optimal topological SB

- Schrödinger system characterizes the optimality
- **Disintegration of measures:** gives us **static** TSBP (OT formulation)

$$\min D_{KL}(\mathbb{P}_{01} \parallel \mathbb{Q}_{\mathcal{T}01}) \text{ s.t. } \mathbb{P}_0 = \rho_0, \mathbb{P}_1 = \rho_1$$

- An E-OT with transport cost:  $\| y_1 - \Psi_1 y_0 - \xi_1 \|_{K_{11}^{-1}}^2$ 
  - Lagrange multipliers: gives us a topological Schrödinger system — — iterative proportional fitting (cont. Sinkhorn all.) for half-bridge prob
- Stochastic control: tells us how optimal TSB follows a forward-backward SDE system

$$\begin{aligned} dX_t &= [f_t + g_t Z_t] dt + g_t dW_t, & X_0 &\sim \rho_0, & Z_t &\equiv g_t \nabla \log \varphi_t(X_t) \\ dX_t &= [f_t - g_t \hat{Z}_t] dt + g_t dW_t, & X_1 &\sim \rho_1, & \hat{Z}_t &\equiv g_t \nabla \log \hat{\varphi}_t(X_t) \end{aligned}$$

**Enables  
learning!!!**

- Nonlinear Feynman-Kac formula: gives us the dynamics of  $\log \varphi_t$  and  $\log \hat{\varphi}_t$

# Topological SBP

- A topological domain  $\mathcal{T}$ , e.g., a graph or a simplicial complex
- Topological stochastic process:  $X := (X_t)_{t \in [0,1]} : [0,1] \times \mathcal{X} \rightarrow \mathbb{R}^n$ 
  - $\mathcal{X}$ : the node/edge space of  $\mathcal{T}$ , with  $n$  the dimension
  - $X$  follows some unknown dynamics with distr. law:  $X \sim \mathbb{P} \rightarrow X_t \sim \mathbb{P}_t$  (time-marginal)
- Given the initial and final (empirical) signal distr.  $X_0 \sim \rho_0$  and  $X_1 \sim \rho_1$

## Topological Schrödinger Bridge Problem

$$\min D_{KL}(\mathbb{P} \parallel \mathbb{Q}_{\mathcal{T}}) \text{ s.t. } \mathbb{P}_0 = \rho_0, \mathbb{P}_1 = \rho_1$$