# 深度學習模型的比較研究 - 以 MNIST 為例

開放原始碼論文

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摘要

本論文的開放原始碼專案網址為:https://github.com/cccresearch/nnModelCompare

不同的神經網路模型,經訓練之後的正確率可能差異很大。本文針對手寫數字辨識的 MNIST 資料庫進行測試,以便觀察模型的表現,並分析其背後的原因。

關鍵字 神經網路·深度學習·MNIST

## 1 簡介

近幾年深度學習技術讓人工智慧領域有了很大的進展,也吸引到了學術界與產業界共同投入研究,相繼開發出更好,但也相對更複雜的模型。

為何有些模型表現好,有些模型表現差,各個網路層的效用是甚麼,為何需要加入某些層,若拿掉的話會有甚麼不良反應嗎?這就是本研究所想要探討的問題!

## 2 背景

手寫數字辨識的 MNIST 是影像辨識領域中最常被拿來測試的資料集,而 CNN 卷積神經網路架構的 LeNet 則是 Yann Le Cun 1989 年在研究手寫辨識問題時,提出來的辨識模型,實驗發現 LeNet 在手寫辨識上有相當高的正確率。

不過,其他的模型,像是使用多層感知器,也可以達到90%以上的正確率,

[1, 2] and see [3].

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\citet{hasselmo} investigated\dots

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Hasselmo, et al. (1995) investigated...

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<sup>\*</sup>Use footnote for providing further information about author (webpage, alternative address)—not for acknowledging funding agencies.

## 3 方法

簡易的『爬山演算法』如下圖所示1所示。

s = snew

break

else:

return s

fails = 0

fails = fails + 1

**if** (fails  $\geq$  maxFails):

print("solution:", s.str())

```
Algorithm Hill-Climbing(pi)
p = pi // 設定粒子 p 為起始粒子 pi
while not isEnd()
pn = p.neighbor(step) //選擇粒子 p 的鄰居 pn
if pn.fitness()>=p.fitness() //如果更好,就接受
p = pn;
End Algorithm
                                      # 爬山演算法的主體函數
def hillClimbing(s, maxGens, maxFails):
   print("start:", s.str())
                                      # 印出初始解
   fails = 0
                                      # 失敗次數設為 0
   # 當代數 gen < maxGen, 且連續失敗次數 fails < maxFails 時,就持續嘗試尋找更好的解。
   for gens in range (maxGens):
       snew = s.neighbor()
                                         取得鄰近的解
       sheight = s.height()
                                      #
                                         sheight=目前解的高度
       nheight = snew.height()
                                      #
                                         nheight=鄰近解的高度
       if (nheight >= sheight):
                                      #
                                         如果鄰近解比目前解更好
           print(gens, ':', snew.str())
                                      #
                                          印出新的解
```

#

#

#

否則

就移動過去

然後傳回。

將連續失敗次數加一

印出最後找到的那個解

移動成功,將連續失敗次數歸零

```
import torch.nn as nn
1
     import torch.nn.functional as F
2
3
4
     class Net(nn.Module):
         def init (self):
5
             super(Net, self). init ()
6
             self.fc1 = nn.Linear(28*28, 10)
7
8
         def forward(self, x):
9
             x = x.view(-1, 28*28)
10
             x = self.fc1(x)
11
             return x
12
```

### 3.1 高度函數如何設計

Measure Measur

$$\xi_{ij}(t) = P(x_t = i, x_{t+1} = j | y, v, w; \theta) = \frac{\alpha_i(t) a_{ij}^{w_t} \beta_j(t+1) b_j^{v_{t+1}}(y_{t+1})}{\sum_{i=1}^{N} \sum_{j=1}^{N} \alpha_i(t) a_{ij}^{w_t} \beta_j(t+1) b_j^{v_{t+1}}(y_{t+1})}$$
(1)

Table 1: 不同模型的 MNIST 正確率

模型	正確率	說明
fc1s fc2 fc2s fc2net fc2signet	74% 92% 10% 92% 95% 91% 97%	損失負無限大

#### 3.1.1 如何選取好的鄰居?

任何的參數變動,都可以創造出新的鄰居模型,因此、鄰居的選擇性是無限多的,我們面臨的問題是,該如何從無限多的鄰居當中,選擇一個有可能更好的適當鄰居呢?

在此、我們用了一些啟發式法則如下

- 1. 加一個新層
- 2. 將一層換成另一層
- 3. 調整某層的參數

**Paragraph** Paragraph Para

## 4 實驗

[1,2] and see [3].

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#### 4.1 Figures

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<sup>&</sup>lt;sup>2</sup>Sample of the first footnote.

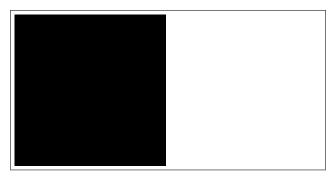


Figure 1: Sample figure caption.

Table 2: Sample table title

	Part	
Name	Description	Size $(\mu m)$
Dendrite Axon Soma	Input terminal Output terminal Cell body	$       \sim 100 \\       \sim 10 \\       up to 10^6$

#### 4.2 Tables

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#### 4.3 Lists

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- consectetur adipiscing elit.
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