



习题课 #2 (Sep. 20)

- 1) 按一行或多行求行列式
- 2) Cramer 法则解方程组
- 3) 选讲 Cauchy 行列式.

Def. 余子式 ((i,j) minor) $M_{ij} = |A_{kl}|_{k \neq i, l \neq j}$.

代数余子式 ((i,j) cofactor) $C_{ij} = (-1)^{i+j} M_{ij}$.

Thm. $\sum_j C_{ij} C_{kj} = \delta_{ik} \det(A)$ i.e., $AC^T = \det(A) I$
 $A = \det(A) C^{-T}$ $C = \det(A)^T A^{-T}$ $A^{-1} = \det(A)^T C^T$.

Thm. 系数矩阵行列式与线性方程组解的联系.

(n 元方程组, n 个方程) $\det(A) \neq 0 \Rightarrow$ 有唯一解. 否则无解或有无穷个解.

特别地, 对于齐次方程组 $\det(A) \neq 0 \Rightarrow$ 有唯一零解. 否则有无穷个解.

Thm. (Cramer 法则) 对于 n 个方程 n 元方程组, $\det(A) \neq 0$ 的情形, 有唯一解: $\det(A)^{-1} (\det(B_1), \dots, \det(B_n))^T$.

$$\det(B_j) = \begin{vmatrix} a_{11} & \dots & a_{1j-1} & b_j & a_{1j+1} & \dots & a_{1n} \\ \vdots & & \vdots & \vdots & \vdots & & \vdots \\ a_{n1} & & a_{nj-1} & b_n & a_{nj+1} & \dots & a_{nn} \end{vmatrix} = \sum_i C_{ij} b_i$$

矩阵理解: $x = A^{-1}b = \det(A)^{-1} C^T b = \det(A)^{-1} \left(\sum_i C^T(j,i) b_i \right) = \det(A)^{-1} \sum_i C_{ij} b_i$.

1) 计算三对角 (Toeplitz) 行列式:
$$\begin{vmatrix} a & b & & 0 \\ c & a & & \\ & & \ddots & \\ 0 & & & a & b \\ & & & c & a \end{vmatrix}$$

记 n 阶行列式值为 D_n .

$$D_n = a D_{n-1} - bc D_{n-2} \quad \text{for } n \geq 2,$$

$$D_2 = a^2 - bc, \quad D_1 = a.$$



令 η_1, η_2 为 $x^2 - ax + bc = 0$ 的两个解.

$$\begin{cases} D_n - \eta_1 D_{n-1} = \eta_2 (D_{n-1} - \eta_1 D_{n-2}) = \eta_2^{n-2} (D_2 - \eta_1 D_1) \\ D_n - \eta_2 D_{n-1} = \eta_1 (D_{n-1} - \eta_2 D_{n-2}) = \eta_1^{n-2} (D_2 - \eta_2 D_1) \end{cases}$$

$$\textcircled{1} \eta_1 = \eta_2 = \eta: \eta^n D_n - \eta^{n-1} D_{n-1} = \eta^2 (D_2 - \eta D_1) \\ \Rightarrow D_n = \eta^n (\eta^{-1} D_1 + (n-1) \eta^{-2} (D_2 - \eta D_1))$$

$$\textcircled{2} \eta_1 \neq \eta_2: D_{n-1} = (\eta_2 - \eta_1)^{-1} (\eta_2^{n-2} (D_2 - \eta_1 D_1) - \eta_1^{n-2} (D_2 - \eta_2 D_1))$$

2) 计算行列式:
$$\begin{vmatrix} a & b & b & \cdots & b \\ c & a & & & \\ & & \ddots & & \\ & & & a & b \\ c & & & c & a \end{vmatrix}$$

记 n 个行列式值为 D_n . $D_1 = a$, $D_2 = a^2 - bc$

$$D_n = (a-b)D_{n-1} + b \begin{vmatrix} 1 & 1 & \cdots & 1 \\ c & a & \cdots & b \\ & & \ddots & \\ & & & a & b \\ c & & & c & a \end{vmatrix} = (a-b)D_{n-1} + b \begin{vmatrix} a-c & b-c & \cdots & b-c \\ c-c & a-c & & \\ & & \ddots & \\ & & & b-c \\ c-c & a-c & & \end{vmatrix}$$

$$= (a-b)D_{n-1} + b(a-c)^{n-1}$$

$$\begin{cases} D_n = (a-b)D_{n-1} + b(a-c)^{n-1} \\ D_n = (a-c)D_{n-1} + c(a-b)^{n-1} \end{cases}$$

$$\textcircled{1} b \neq c: D_{n-1} = (b-c)^{-1} (b(a-c)^{n-1} - c(a-b)^{n-1})$$

$$\textcircled{2} b = c: (a-b)^{-n} D_n = (a-b)^{-(n-1)} D_{n-1} + b(a-b)^{-1}$$

$$\Rightarrow D_n = (a-b)^n ((a-b)^{-1} D_1 + b(a-b)^{-1} (n-1)) \\ = (a-b)^{n-1} (D_1 + (n-1)b)$$

思考: 对于上述两题 $b=c$ 的情形是否可考虑 $c \rightarrow b$ 的极限? 合理性?



3) (Cauchy determinant) 计算 $\left| \frac{1}{x_i + y_j} \right|_{i,j}$.

注意到 $\frac{1}{x_i + y_j} - \frac{1}{x_i + y_1} = \frac{y_1 - y_j}{(x_i + y_1)(x_i + y_j)} = \frac{1}{x_i + y_1} \cdot \frac{y_1 - y_j}{x_i + y_j}$

$$\begin{vmatrix} \frac{1}{x_1 + y_1} & \frac{1}{x_1 + y_2} \cdot \frac{y_1 - y_2}{x_1 + y_2} & \cdots & \frac{1}{x_1 + y_n} \cdot \frac{y_1 - y_n}{x_1 + y_n} \\ \vdots & \vdots & & \vdots \\ \frac{1}{x_n + y_1} & \frac{1}{x_n + y_2} \cdot \frac{y_1 - y_2}{x_n + y_2} & \cdots & \frac{1}{x_n + y_n} \cdot \frac{y_1 - y_n}{x_n + y_n} \end{vmatrix}$$

$$= \frac{\prod_{j>1} (y_1 - y_j)}{\prod_i (x_i + y_1)} \begin{vmatrix} 1 & \frac{1}{x_1 + y_2} & \cdots & \frac{1}{x_1 + y_n} \\ \vdots & \vdots & & \vdots \\ 1 & \frac{1}{x_n + y_2} & \cdots & \frac{1}{x_n + y_n} \end{vmatrix}$$

$$= \frac{\prod_{j>1} (y_1 - y_j)}{\prod_i (x_i + y_1)} \begin{vmatrix} 1 & \frac{1}{x_1 + y_2} & \cdots & \frac{1}{x_1 + y_n} \\ 0 & \frac{x_2 - x_1}{(x_1 + y_2)(x_1 + y_n)} & \cdots & \frac{x_n - x_1}{(x_1 + y_2)(x_1 + y_n)} \\ \vdots & \vdots & & \vdots \\ 0 & \frac{x_n - x_1}{(x_n + y_2)(x_n + y_n)} & \cdots & \frac{x_n - x_1}{(x_n + y_n)(x_n + y_n)} \end{vmatrix}$$

$$= \frac{\prod_{j>1} (y_1 - y_j)}{\prod_i (x_i + y_1)} \prod_{j>1} (x_j - x_1) \cdot \frac{1}{\prod_{j>1} (x_1 + y_j)} \begin{vmatrix} \frac{1}{x_2 + y_2} & \cdots & \frac{1}{x_2 + y_n} \\ \vdots & & \vdots \\ \frac{1}{x_n + y_2} & \cdots & \frac{1}{x_n + y_n} \end{vmatrix}$$

$$= \frac{\prod_{j>1} (x_j - x_1) \prod_{j>1} (y_1 - y_j)}{\prod_{i=1 \text{ 或 } j=1} (x_i + y_j)} \begin{vmatrix} \frac{1}{x_2 + y_2} & \cdots & \frac{1}{x_2 + y_n} \\ \vdots & & \vdots \\ \frac{1}{x_n + y_2} & \cdots & \frac{1}{x_n + y_n} \end{vmatrix}$$

$$= \prod_{i<j} (x_j - x_i) (y_i - y_j) \prod_{i,j} (x_i + y_j)^{-1}$$



求行列式 $\begin{vmatrix} a_0 & a_1 & \dots & a_{n-1} \\ & a_1 & \dots & a_n \\ & & \ddots & \\ & & & a_1 \\ a_1 & \dots & & a_0 \end{vmatrix}$ (循环方阵) [需要矩阵乘法]

$$A(1, \zeta, \dots, \zeta^{n-1})^T = f(\zeta)(1, \zeta, \dots, \zeta^{n-1})^T \Rightarrow \det(A) = \prod_{\zeta \neq 1} f(\zeta)$$

5) 计算 $D = \begin{vmatrix} \sin \theta_1 & \sin 2\theta_1 & \dots & \sin n\theta_1 \\ \vdots & \vdots & & \vdots \\ \sin \theta_n & \sin 2\theta_n & \dots & \sin n\theta_n \end{vmatrix}$

$$\begin{aligned} D &= \begin{vmatrix} \frac{1}{2i}(e^{i\theta_1} - e^{-i\theta_1}) & \frac{1}{2i}(e^{2i\theta_1} - e^{-2i\theta_1}) & \dots & \frac{1}{2i}(e^{ni\theta_1} - e^{-ni\theta_1}) \\ \vdots & \vdots & & \vdots \\ \frac{1}{2i}(e^{i\theta_n} - e^{-i\theta_n}) & \frac{1}{2i}(e^{2i\theta_n} - e^{-2i\theta_n}) & \dots & \frac{1}{2i}(e^{ni\theta_n} - e^{-ni\theta_n}) \end{vmatrix} \\ &= \prod_k \frac{1}{2i} (e^{i\theta_k} - e^{-i\theta_k}) \begin{vmatrix} 1 & e^{i\theta_1} + e^{-i\theta_1} & \dots & e^{(n-1)i\theta_1} + e^{-(n-1)i\theta_1} \\ \vdots & \vdots & & \vdots \\ 1 & e^{i\theta_n} + e^{-i\theta_n} & \dots & e^{(n-1)i\theta_n} + e^{-(n-1)i\theta_n} \end{vmatrix} \\ &= \prod_k \sin \theta_k \begin{vmatrix} 1 & e^{i\theta_1} + e^{-i\theta_1} & \dots & e^{(n-1)i\theta_1} + e^{-(n-1)i\theta_1} \\ \vdots & \vdots & & \vdots \\ 1 & e^{i\theta_n} + e^{-i\theta_n} & \dots & e^{(n-1)i\theta_n} + e^{-(n-1)i\theta_n} \end{vmatrix} \\ &= \prod_k \sin \theta_k \begin{vmatrix} 1 & e^{i\theta_1} + e^{-i\theta_1} & \dots & e^{(n-1)i\theta_1} + e^{-(n-1)i\theta_1} \\ \vdots & \vdots & & \vdots \\ 1 & e^{i\theta_n} + e^{-i\theta_n} & \dots & e^{(n-1)i\theta_n} + e^{-(n-1)i\theta_n} \end{vmatrix} \\ &= \prod_k \sin \theta_k \begin{vmatrix} 1 & e^{i\theta_1} + e^{-i\theta_1} & \dots & e^{(n-1)i\theta_1} + e^{-(n-1)i\theta_1} \\ \vdots & \vdots & & \vdots \\ 1 & e^{i\theta_n} + e^{-i\theta_n} & \dots & e^{(n-1)i\theta_n} + e^{-(n-1)i\theta_n} \end{vmatrix} \\ &= \prod_k \sin \theta_k \begin{vmatrix} 1 & e^{i\theta_1} + e^{-i\theta_1} & \dots & e^{(n-1)i\theta_1} + e^{-(n-1)i\theta_1} \\ \vdots & \vdots & & \vdots \\ 1 & e^{i\theta_n} + e^{-i\theta_n} & \dots & e^{(n-1)i\theta_n} + e^{-(n-1)i\theta_n} \end{vmatrix} \\ &= \prod_k \sin \theta_k \prod_{i < j} 2(\cos \theta_i - \cos \theta_j) \end{aligned}$$



6) 证明: $\frac{d}{dt} \det(A_{ij}(t))_{ij} = \sum_j \det B_j(t) = \sum_{ij} \frac{d}{dt} a_{ij}(t) C_{ij}(t)$ B_j 为 A 仅对第 j 列求导所得矩阵.

$$\begin{aligned} \text{Proof. } \frac{d}{dt} \det(A_{ij}(t))_{ij} &= \frac{d}{dt} \sum_{i=1}^n (a_{i1}(t) C_{i1}(t)) \\ &= \sum_{i=1}^n a_{i1}(t)' C_{i1}(t) + \sum_{i=1}^n a_{i1}(t) C_{i1}(t)' \\ &= \det B_1(t) + \sum_{i=1}^n a_{i1}(t) \sum_{j=1}^{n-1} \det D_j^{(i)}(t) \quad (\text{归纳假设}) \end{aligned}$$

其中 $D_j^{(i)}(t)$ 为 A 划去 i 行、 1 列后仅对第 j 列求导所得矩阵,

这也等同于 $B_{j+1}(t)$ 划去 i 行、 1 列对应的矩阵, 故有 $\sum_i a_{i1}(t) \det D_j^{(i)}(t)$

为 $\det B_{j+1}(t)$. 于是原式为 $\sum_j \det B_j(t)$.

进一步地: $\sum_j \det B_j(t) = \sum_{ij} a_{ij}(t)' C_{ij}(t)$ (按第 j 列展开).

7) (加边法) 计算

$$D_1 = \begin{vmatrix} 1 & \dots & 1 \\ x_1 & \dots & x_n \\ \vdots & & \vdots \\ x_1^{k-1} & \dots & x_n^{k-1} \\ \vdots & & \vdots \\ x_1^{k-1} & \dots & x_n^{k-1} \\ \vdots & & \vdots \\ x_1^n & \dots & x_n^n \end{vmatrix}$$

$$D_2 = \begin{vmatrix} 1+x_1 & 1+x_1^2 & \dots & 1+x_1^n \\ \vdots & \vdots & & \vdots \\ 1+x_n & 1+x_n^2 & \dots & 1+x_n^n \end{vmatrix}$$

$$D_3 = \det(t + a_{ij})_{ij}$$

D_1 为行列式 $\begin{vmatrix} y & x_1 & \dots & x_n \\ \vdots & \vdots & & \vdots \\ y^n & x_1^n & \dots & x_n^n \end{vmatrix}$ 中 y^k 前系数的 $(-1)^k$ 倍.

而上述行列式可写为 $\prod_{j=1}^n (x_j - y) \prod_{l \neq j} (x_l - x_j)$

y^k 前系数为 $(-1)^k \sum_{i_1 < \dots < i_{n-k}} \prod_{p=1}^{n-k} x_{i_p} \prod_{j \notin \{i_1, \dots, i_{n-k}\}} (x_l - x_j)$

于是 $D_1 = \sum_{i_1 < \dots < i_{n-k}} \prod_{p=1}^{n-k} x_{i_p} \prod_{j \notin \{i_1, \dots, i_{n-k}\}} (x_l - x_j) = \sigma_{n-k} \prod_{j \neq l} (x_l - x_j)$



$$D_2 = \begin{vmatrix} 1 & 1 & 1 & \cdots & 1 \\ -1 & x_1 & x_1^2 & \cdots & x_1^n \\ \vdots & \vdots & \vdots & \ddots & \vdots \\ -1 & x_n & x_n^2 & \cdots & x_n^n \end{vmatrix} = - \begin{vmatrix} -1 & 1 & 1 & \cdots & 1 \\ 1 & x_1 & x_1^2 & \cdots & x_1^n \\ \vdots & \vdots & \vdots & \ddots & \vdots \\ 1 & x_n & x_n^2 & \cdots & x_n^n \end{vmatrix}$$

$$= - \begin{vmatrix} -2 & 0 & \cdots & 0 \\ +1 & x_1 & \cdots & x_1^n \\ \vdots & \vdots & \ddots & \vdots \\ +1 & x_n & \cdots & x_n^n \end{vmatrix} = - \begin{vmatrix} 1 & 1 & \cdots & 1 \\ 1 & x_1 & \cdots & x_1^n \\ \vdots & \vdots & \ddots & \vdots \\ 1 & x_n & \cdots & x_n^n \end{vmatrix}$$

$$= +2 \begin{vmatrix} x_1 & \cdots & x_1^n \\ \vdots & \ddots & \vdots \\ x_n & \cdots & x_n^n \end{vmatrix} = \prod_k (x_k - 1) \prod_{i < j} (x_j - x_i)$$

$$= \left(2 \prod_k x_k - \prod_k (x_k - 1) \right) \prod_{i < j} (x_j - x_i).$$

$$D_3 = \det A + t \sum_{i,j} C_{ij} \leftarrow \text{代数系数}.$$

8)
$$\begin{cases} (\lambda-2)x_1 - 3x_2 - 2x_3 = 0, \\ -x_1 + (\lambda-8)x_2 - 2x_3 = 0, \\ 2x_1 + 14x_2 + (\lambda+3)x_3 = 0. \end{cases} \quad \text{何时有非零解.}$$

$$\begin{vmatrix} \lambda-2 & -3 & -2 \\ -1 & \lambda-8 & -2 \\ 2 & 14 & \lambda+3 \end{vmatrix} = (\lambda-2)(\lambda^2-5\lambda+4) - 3\lambda-9+28+2(6+2\lambda-16)$$

$$= (\lambda-2)(\lambda-1)(\lambda-4) + \lambda-1 = (\lambda-1)(\lambda-3)^2.$$

$\lambda=1$ 或 3 时有非零解.

思考: 对于 n 元齐次方程组 (n 个方程), 使得

$$\begin{cases} a_{11}x_1 + \cdots + a_{1n}x_n = \lambda x_1 \\ \vdots \\ a_{n1}x_1 + \cdots + a_{nn}x_n = \lambda x_n \end{cases}$$

有非零解的 λ 是否可能无穷多个? 若有限, 至多几个?



补充：分片线性函数拟合、样条函数插值

上一节已证存在唯一至多 n 次多项式恰好经过事先固定的点 $\{(x_k, y_k)\}_{k=0}^n$ ($n+1$) 个 $\{x_k\}_{k=0}^n$ 互不相同. [多项式拟合] (利用 Vandermonde 矩阵非奇异).

在实际应用中, 多项式拟合有潜在问题 ① 计算代价高 ② Runge 现象.

故时常考虑局部逼近方案: 令 $x_0 < x_1 < \dots < x_n$.

在每一区间 $[x_{k-1}, x_k]$ 使用 s 次多项式 $g_k(x)$ 逼近, 使得

$g_k(x_{k-1}) = y_{k-1}$, $g_k(x_k) = y_k$, $k=1, 2, \dots, n$. 且在分段处有 r 阶连续性:

$$g_k^{(l)}(x_k) = g_{k+1}^{(l)}(x_k), \quad l=0, 1, \dots, r.$$

问题: ① 若 $s=1$, $r=0$ (分片线性函数) 证明存在唯一 $\{g_k\}_{k=1}^n$ 满足上述条件.

② 若 $s=3$, $r=2$ (cubic spline) 存在唯一性是否仍能保证?

* 将条件转化为线性方程组:

n 个至多 s 次多项式 $\rightarrow n(s+1)$ 个未知元

插值条件 $\rightarrow 2n$ 个方程. 光滑性条件 $\rightarrow (n-1)r$ 个方程.

仅当 $2n + (n-1)r \geq n(s+1)$, 即 $(1+r-s)n \geq r$.

当 $s=r+1$ 时, 需要额外至少 r 个方程才能保证唯一性.

记 $g_k'(x_k) = m_k$. 则由 $g_k(x_k) = y_k$, $g_k'(x_k) = m_k$, $g_k(x_{k-1}) = y_{k-1}$, $g_k'(x_{k-1}) = m_{k-1}$

可唯一确定 $g_k(x) = y_{k-1} h_k(x) + y_k \tilde{h}_k(x) + m_{k-1} g_k(x) + m_k \tilde{g}_k(x)$.

$$\begin{aligned} g_k''(x_k) = g_{k+1}''(x_k) &\Rightarrow y_{k-1} h_k''(x_k) + y_k \tilde{h}_k''(x_k) + m_{k-1} g_k''(x_k) + m_k \tilde{g}_k''(x_k) \\ &= y_k h_{k+1}''(x_k) + y_{k+1} \tilde{h}_{k+1}''(x_k) + m_k g_{k+1}''(x_k) + m_{k+1} \tilde{g}_{k+1}''(x_k) \end{aligned}$$

组成关于 m_1, \dots, m_n 的三对角矩阵.

对于自然样条 ($g_1''(x_0) = g_n''(x_n) = 0$), 系数矩阵为

$$\begin{pmatrix} 2 & 1 & & \\ 1-\lambda_1 & 2 & \lambda_1 & \\ & \ddots & \ddots & \ddots \\ & & 1-\lambda_{n-1} & 2 & \lambda_{n-1} \\ & & & 1 & 2 \end{pmatrix} \quad \text{行列式不为 0.}$$



9) $A_{ij} \begin{cases} > 0, i=j, \\ < 0, i \neq j. \end{cases} \sum_j A_{ij} > 0$. 证明 $\det(A_{ij})_{ij} > 0$.

$$\begin{vmatrix} A_{11} & A_{12} & \cdots & A_{1n} \\ A_{21} & A_{22} & \cdots & A_{2n} \\ \vdots & \vdots & \ddots & \vdots \\ A_{n1} & A_{n2} & \cdots & A_{nn} \end{vmatrix} = A_{11} \begin{vmatrix} A_{22} - A_{21}A_{11}^{-1}A_{12} & A_{23} - A_{21}A_{11}^{-1}A_{13} & \cdots & A_{2n} - A_{21}A_{11}^{-1}A_{1n} \\ \vdots & \vdots & \ddots & \vdots \\ A_{n2} - A_{n1}A_{11}^{-1}A_{12} & A_{n3} - A_{n1}A_{11}^{-1}A_{13} & \cdots & A_{nn} - A_{n1}A_{11}^{-1}A_{1n} \end{vmatrix}$$

第 $(i-1)$ 行对角元为 $A_{ii} - A_{i1}A_{11}^{-1}A_{1i} > A_{ii} - A_{i1}A_{11}^{-1}A_{1i}$

$$= -A_{11}^{-1}A_{i1}(A_{11} + A_{1i}) > 0.$$

第 $(i-1)$ 行所有元素之和为 $\sum_{j=2}^n A_{ij} - A_{i1}A_{11}^{-1}A_{1j} > -A_{i1} - \sum_{j=2}^n A_{i1}A_{11}^{-1}A_{1j}$

$$= -A_{11}^{-1}A_{i1}(A_{11} + \sum_{j=2}^n A_{1j}) > 0.$$

第 $(i-1)$ 行非对角元为 $A_{ij} - A_{i1}A_{11}^{-1}A_{1j} < 0 - 0 = 0$.

依照归纳法立即得证.