view_frames Result

Recorded at time: 1652373490.740

camera_link
camera_rgb_frame
camera_depth_frame
camera_depth_optical_frame
world
base
torso
collision_head_link_1
collision_head_link_2
reference/base
reference/collision_head_link_1
reference/collision_head_link_2
reference/torso
camera_rgb_optical_frame
head
left_arm_mount
right_arm_mount
left_torso_itb
pedestal
right_torso_itb
sonar_ring
screen
display
dummyhead1
head_camera
left_upper_shoulder
left_lower_shoulder
left_upper_elbow
left_upper_elbow_visual
left_lower_elbow
left_upper_forearm
left_upper_forearm_visual
left_lower_forearm
left_arm_itb
left_wrist
left_hand
left_gripper_base
left_gripper_mass
left_hand_accelerometer
left_hand_camera
left_hand_camera_axis
left_hand_range
l_gripper_l_finger
l_gripper_r_finger
left_gripper
left_gripper_object_mass
l_gripper_l_finger_tip
l_gripper_r_finger_tip
right_upper_shoulder
right_lower_shoulder
right_upper_elbow
right_upper_elbow_visual
right_lower_elbow
right_upper_forearm
right_upper_forearm_visual
right_lower_forearm
right_arm_itb
right_wrist
right_hand
right_gripper_base
right_gripper_mass
right_hand_accelerometer
right_hand_camera
right_hand_camera_axis
right_hand_range
r_gripper_l_finger
r_gripper_r_finger
right_gripper
right_gripper_object_mass
r_gripper_l_finger_tip
r_gripper_r_finger_tip
reference/head
reference/screen
reference/display
reference/dummyhead1
reference/head_camera
reference/left_arm_mount
reference/left_torso_itb
reference/pedestal
reference/right_arm_mount
reference/right_torso_itb
reference/sonar_ring
reference/left_upper_shoulder
reference/left_lower_shoulder
reference/left_upper_elbow_visual
reference/left_upper_elbow
reference/left_lower_elbow
reference/left_upper_forearm_visual
reference/left_upper_forearm
reference/left_lower_forearm
reference/left_arm_itb
reference/left_wrist
reference/left_hand
reference/left_gripper_base
reference/left_gripper_mass
reference/left_hand_accelerometer
reference/left_hand_camera
reference/left_hand_camera_axis
reference/left_hand_range
reference/l_gripper_l_finger
reference/l_gripper_r_finger
reference/left_gripper
reference/left_gripper_object_mass
reference/l_gripper_l_finger_tip
reference/l_gripper_r_finger_tip
reference/right_upper_shoulder
reference/right_lower_shoulder
reference/right_upper_elbow_visual
reference/right_upper_elbow
reference/right_lower_elbow
reference/right_upper_forearm_visual
reference/right_upper_forearm
reference/right_lower_forearm
reference/right_arm_itb
reference/right_wrist
reference/right_hand
reference/right_gripper_base
reference/right_gripper_mass
reference/right_hand_accelerometer
reference/right_hand_camera
reference/right_hand_camera_axis
reference/right_hand_range
reference/r_gripper_l_finger
reference/r_gripper_r_finger
reference/right_gripper
reference/right_gripper_object_mass
reference/r_gripper_l_finger_tip
reference/r_gripper_r_finger_tip
Broadcaster: /camera_base_link1
Broadcaster: /camera_base_link
Broadcaster: /camera_base_link2
Broadcaster: /base_to_world
Broadcaster: /ref_base_to_world
Broadcaster: /camera_optical_frame_broadcaster
Broadcaster: /robot_state_publisher
Broadcaster: /robot_ref_publisher
Average rate: 10000.000 Hz
Most recent transform: 0.000 (1652373490.740 sec old)
Buffer length: 0.000 sec
Average rate: 50.207 Hz
Most recent transform: 1652374273.505 (-782.765 sec old)
Buffer length: 4.920 sec
Average rate: 38.540 Hz
Most recent transform: 1652374273.005 (-782.265 sec old)
Buffer length: 4.930 sec
Average rate: 19.976 Hz
Most recent transform: 1652374272.995 (-782.255 sec old)
Buffer length: 4.906 sec
Average rate: 19.955 Hz
Most recent transform: 1652374272.977 (-782.237 sec old)
Buffer length: 4.861 sec
Average rate: 50.199 Hz
Average rate: 38.415 Hz
Most recent transform: 1652374273.017 (-782.277 sec old)