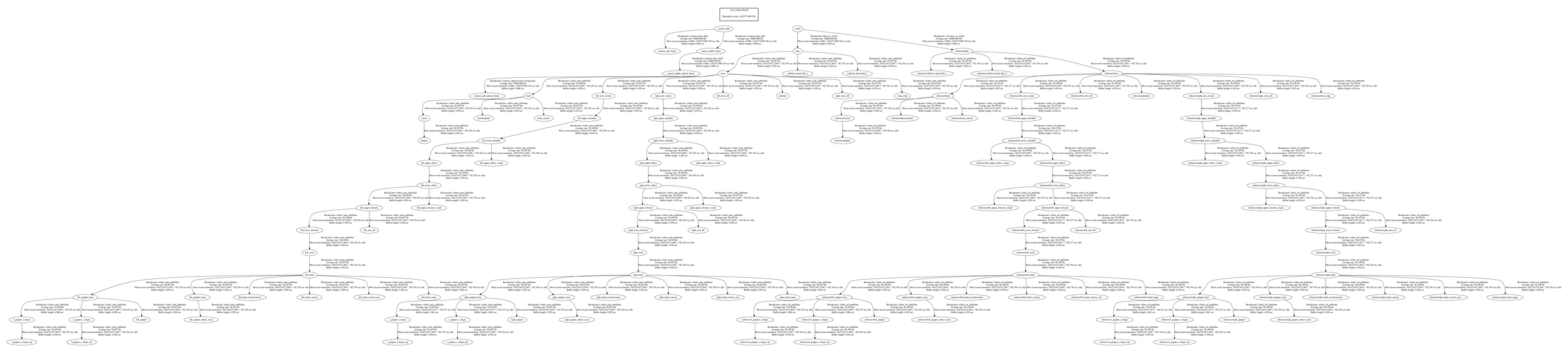
view_frames Result
Recorded at time: 1652719496.740
camera_link
Broadcaster: camera_base_link2
Average rate: 10000.000 Hz
Most recent transform: 0.000 (1652719496.740 sec old)
Buffer length: 0.000 sec
camera_base_link
Broadcaster: camera_base_link
Average rate: 10000.000 Hz
Most recent transform: 0.000 (1652719496.740 sec old)
Buffer length: 0.000 sec
world
Broadcaster: /base_to_world
Average rate: 10.000 Hz
Most recent transform: 0.000 (1652719496.740 sec old)
Buffer length: 0.000 sec
Broadcaster: /tf_base_to_world
Average rate: 10.000 Hz
Most recent transform: 0.000 (1652719496.740 sec old)
Buffer length: 0.000 sec
camera_rgb_frame
camera_depth_frame
Broadcaster: /camera_base_link2
Average rate: 10000.000 Hz
Most recent transform: 0.000 (1652719496.740 sec old)
Buffer length: 0.000 sec
base
Broadcaster: robot_state_publisher
Average rate: 50.207 Hz
Most recent transform: 1652719271.965 (762.765 sec old)
Buffer length: 4.930 sec
Broadcaster: robot_state_publisher
Average rate: 50.207 Hz
Most recent transform: 1652719271.965 (762.765 sec old)
Buffer length: 4.930 sec
Broadcaster: robot_state_publisher
Average rate: 50.207 Hz
Most recent transform: 1652719271.965 (762.765 sec old)
Buffer length: 4.930 sec
elbow_link
Broadcaster: /robot_tf_publisher
Average rate: 50.199 Hz
Most recent transform: 1652719271.965 (762.765 sec old)
Buffer length: 4.930 sec
Broadcaster: /robot_tf_publisher
Average rate: 50.199 Hz
Most recent transform: 1652719271.965 (762.765 sec old)
Buffer length: 4.930 sec
camera_depth_optical_frame
Broadcaster: /camera_optical_frame_broadcaster
Average rate: 10000.000 Hz
Most recent transform: 0.000 (1652719496.740 sec old)
Buffer length: 0.000 sec
wrist
Broadcaster: robot_state_publisher
Average rate: 50.207 Hz
Most recent transform: 1652719271.965 (762.765 sec old)
Buffer length: 4.930 sec
Broadcaster: robot_state_publisher
Average rate: 50.207 Hz
Most recent transform: 1652719271.965 (762.765 sec old)
Buffer length: 4.930 sec
Broadcaster: robot_state_publisher
Average rate: 50.207 Hz
Most recent transform: 1652719271.965 (762.765 sec old)
Buffer length: 4.930 sec
Broadcaster: robot_state_publisher
Average rate: 50.207 Hz
Most recent transform: 1652719271.965 (762.765 sec old)
Buffer length: 4.930 sec
elbow_head_link_1
Broadcaster: /robot_tf_publisher
Average rate: 50.199 Hz
Most recent transform: 1652719271.965 (762.765 sec old)
Buffer length: 4.930 sec
elbow_head_link_2
Broadcaster: /robot_tf_publisher
Average rate: 50.199 Hz
Most recent transform: 1652719271.965 (762.765 sec old)
Buffer length: 4.930 sec
elbow_head_link_3
Broadcaster: /robot_tf_publisher
Average rate: 50.199 Hz
Most recent transform: 1652719271.965 (762.765 sec old)
Buffer length: 4.930 sec
elbow/elbow_head_link_1
Broadcaster: /robot_tf_publisher
Average rate: 50.199 Hz
Most recent transform: 1652719271.965 (762.765 sec old)
Buffer length: 4.930 sec
elbow/elbow_head_link_2
Broadcaster: /robot_tf_publisher
Average rate: 50.199 Hz
Most recent transform: 1652719271.965 (762.765 sec old)
Buffer length: 4.930 sec
elbow/elbow_head_link_3
Broadcaster: /robot_tf_publisher
Average rate: 50.199 Hz
Most recent transform: 1652719271.965 (762.765 sec old)
Buffer length: 4.930 sec
camera_rgb_optical_frame
head
Broadcaster: robot_state_publisher
Average rate: 50.207 Hz
Most recent transform: 1652719271.965 (762.765 sec old)
Buffer length: 4.930 sec