

Jiarui Li

Tel: (+1) 617-256-0033 | Email: jiarui01@mit.edu | Website: <https://jiaruili.com/>

EDUCATION

Massachusetts Institute of Technology (MIT)

Ph.D. in Systems Engineering

Cambridge, MA

Sep 2024 – present

Peking University (PKU)

B.E. in Robotics Engineering with Honors

Beijing, China

Sep 2019 – Jul 2024

RESEARCH APPOINTMENTS

Zardini Lab, LIDS & CEE, Massachusetts Institute of Technology

Graduate Student Research Assistant, Advisor: [Prof. Gioele Zardini](#)

Cambridge, MA

Sep 2024 - present

Computational Robotics Lab, SEAS, Harvard University

Undergraduate Visiting Researcher, Advisor: [Prof. Heng Yang](#)

Boston, MA

Jul 2023 - Feb 2024

Peking University & State Key Laboratory of General Artificial Intelligence

Undergraduate Research Intern in Robotics Lab, Advisor: [Dr. Hangxin Liu](#)

Beijing, China

Jan 2022 - Jun 2023

HONORS & AWARDS SELECTION

The Schoettler Fellowship from *MIT CEE*

2024

Grand Challenges Scholar Award from *Peking University*

2024

Honor Graduates from *Peking University*

2024

Best Paper Award Finalist on Mobile Manipulation from *IEEE IROS*

2023

National Scholarship from *Peking University*

2023

Pacemaker to University Merit Student from *Peking University*

2023

University Merit Student from *Peking University*

2022

Schneider Scholarship from *College of Engineering, Peking University*

2022

PUBLICATIONS (*indicates co-first authors)

- [C3] Yao Su*, **Jiarui Li***, Ziyuan Jiao*, Meng Wang, Chi Chu, Yixin Zhu, Hangxin Liu, “Planning Sequential Aerial Manipulation for Over-actuated UAMs”, in *Proceedings of IEEE/RSJ International Conference on Intelligent Robots and Systems (IROS)*, 2023.
- [J2] - **Extended version submitted to *Transactions on Robotics (T-RO)*, under review**
- [Best Paper Award Finalist on Mobile Manipulation at IROS 2023](#)
- *Poster Presented at Northeast Robotics Colloquium (NERC) 2023*
- [C2] Meng Wang*, Yao Su*, Hang Li, **Jiarui Li**, Jixiang Liang, Hangxin Liu, “Aggregating Single-wheeled Mobile Robots for Omnidirectional Movements”, in *Proceedings of IEEE/RSJ International Conference on Intelligent Robots and Systems (IROS)*, 2023.
- [J1] Wanlin Li*, Meng Wang*, **Jiarui Li**, Yao Su, Devesh K. Jha, Xinyuan Qian, Kaspar Althoefer, Hangxin Liu, “L3F-TOUCH: A Light-weight, Low-cost and WireLess GelSight Sensor with Extended Three-axis Force Sensing”, *IEEE Robotics and Automation Letters (RA-L)*, 2023.
- [C1] Yao Su*, Chi Chu*, Meng Wang, **Jiarui Li**, Yang Liu, Yixin Zhu, Hangxin Liu, “Downwash-aware Control Allocation for Over-actuated UAV Platforms”, in *Proceedings of IEEE/RSJ International Conference on Intelligent Robots and Systems (IROS)*, 2022.

SKILLS

Language: Chinese (Mandarin) Native, **English** Full Professional Proficiency

Programming: Python, C/C++, MATLAB & Simulink, Embedded System (Arduino, STM32)

AI & Robotics: PyTorch, ROS, ARGoS, Gazebo, PyBullet, Webots, SolidWorks, Moveit!, OpenCV, Crazyflie, UR, Kinova and Franka Manipulator Programming

TEACHING

Teaching Assistant, *1.104 Sensing and Intelligent Systems*, MIT, 2025 Spring

PROFESSIONAL ACTIVITIES

Reviewer for Conferences

Conference on Neural Information Processing Systems (NeurIPS)

IEEE/RSJ International Conference on Intelligent Robots and Systems (IROS)

IEEE International Conference on Automation Science and Engineering (CASE)

International Conference on Learning Representations (ICLR)

Last Updated: Dec 2024