3D Object Detection of 9-million LiDAR Point Cloud Using Semi-Supervised Machine Learning

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Problem Definition

Objective: Reconstruct the 3D objects in a local neighborhood with minimum dimension

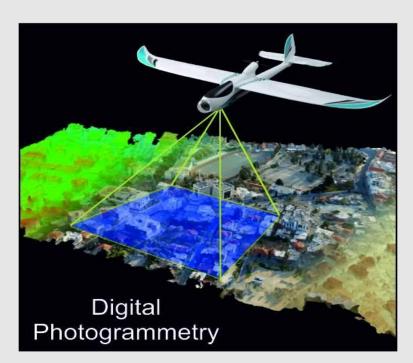
Motivation: Minimize the Misclassification

Applications:

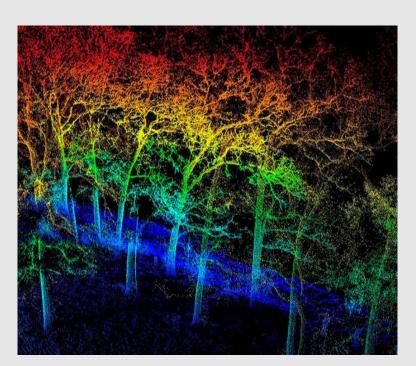
• Autonomous Driving (LYCMU, CVPR '19), (CKZBMFU, NIPS '15), (FDU, NIPS '12)



• Digital Photogrammetry (HH, ISPRS '18)

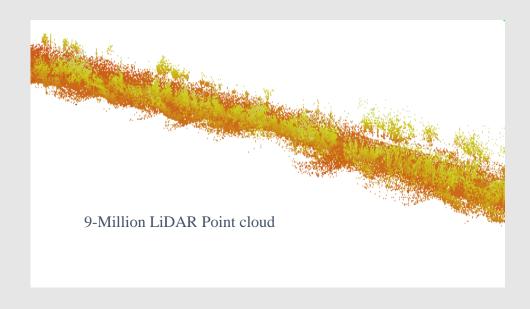


• Forestry & Vegetation (DMS, CVPR '12)



Data Collection & Preparation

- The dataset are acquired by HDL-32E
 - ± 2 cm accuracy
 - 32 Channels
 - 80m-100m Range
 - 700,000 Points per Second
 - 360° Horizontal FOV
 - +10° to -30° Vertical FOV
- The dataset has been labeled
- Metric: Misclassification Rate







Method

Point Cloud



Ground/Non-ground



Kd-Tree





K Nearest Neighbor

Principle Component Analysis

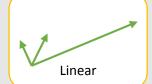
(PCA)

$$Cov_{3x3} = \frac{1}{n+1} \sum_{i=1}^{n+1} (P_i - \overline{P}) (P_{i-} \overline{P})^T$$

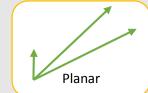
$$\overline{P} = \frac{1}{n+1} \sum_{i=1}^{n+1} P_i$$

$$Cov_{3x3} = [\vec{e}_1 \ \vec{e}_2 \ \vec{e}_3] \begin{bmatrix} \lambda_1 & 0 & 0 \\ 0 & \lambda_2 & 0 \\ 0 & 0 & \lambda_3 \end{bmatrix} \begin{bmatrix} \vec{e}_1 \\ \vec{e}_2 \\ \vec{e}_3 \end{bmatrix}$$







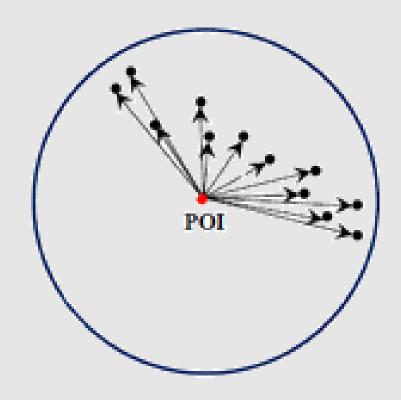


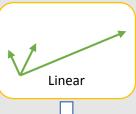




Dynamic PCA

- Local Point Density (LPD)
- Local Point Spacing (LPS)
- Update the radius of Search







$$LPD_{linear}\left(\frac{pts}{m}\right) = \frac{n+1}{2r_n}$$

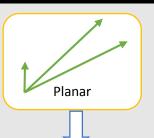
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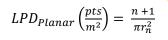
$$LPS_{linear} = \frac{1}{LPD_{linear}}$$

Linear









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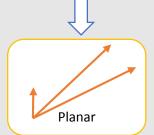
$$LPS_{Planar} = \frac{1}{\sqrt{LPD_{Planar}}}$$

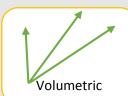


 $r = 4 \times LPS$



PCA (again)







$$LPD_{vol}\left(\frac{pts}{m^3}\right) = \frac{n+1}{\frac{4}{3}\pi r_n^3}$$

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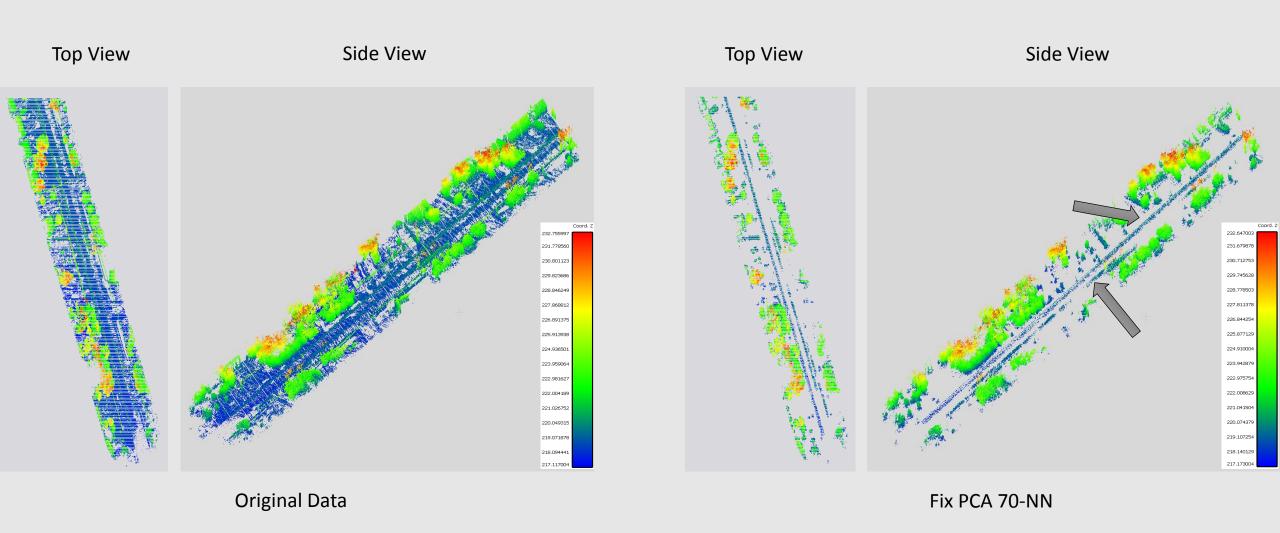
$$LPS_{vol} = \frac{1}{\sqrt[3]{LPD_{vol}}}$$



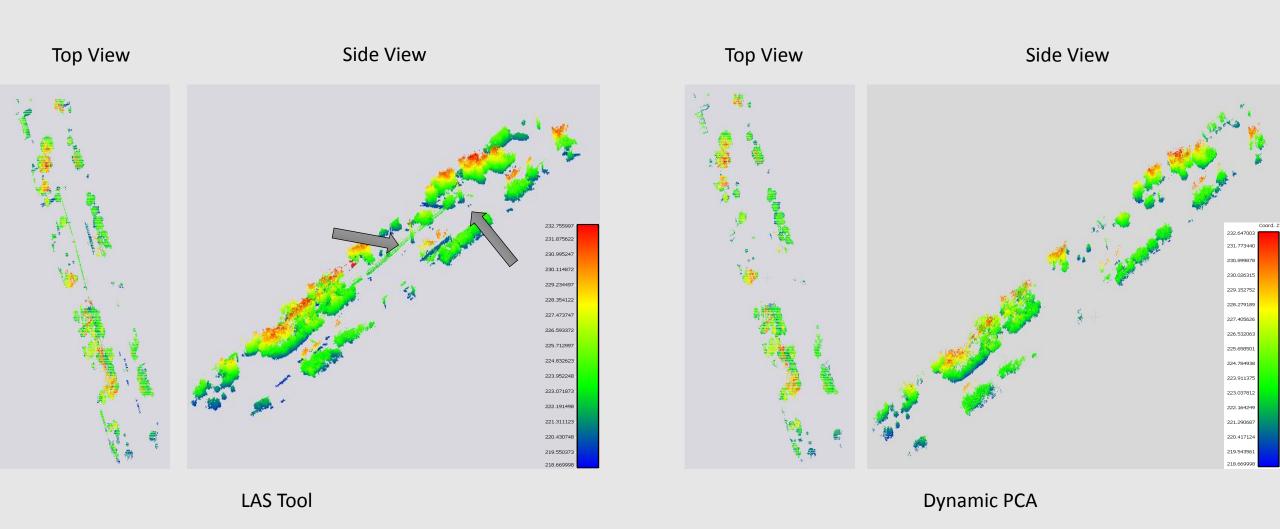




Result

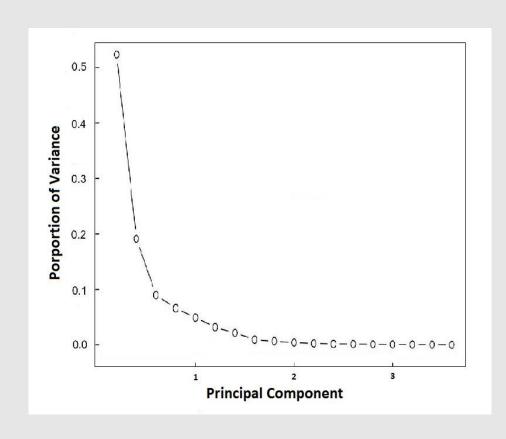


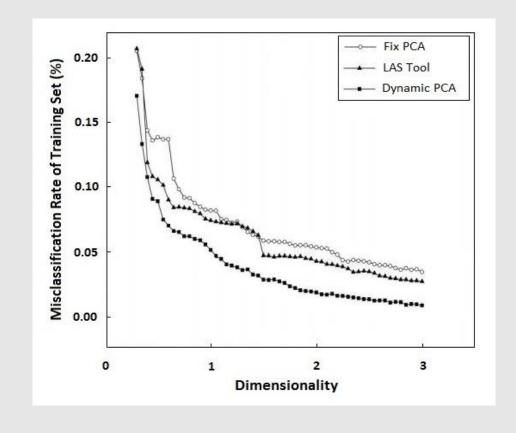
Result



Misclassification

Misclassification Rate:
$$\frac{1}{n}\sum_{i=1}^{n}I(y_i\neq \hat{y}_i)$$





Genome Sequence Classification Using Long Short-Term Memory Recurrent Neural Network

Siamak Rabienia



Spring 2020

Problem Definition

Objective: Given sequence of genes, train a deep neural network for pattern recognition.

"....TAAATGCTACCGTCACAATATTCGTG ACCAGACTGAAGTTATTGAATGCGGCTT GGAAGTTAAGCACTTATGCCC...."



"....TAAATGCTACCGTCACAATATTCGTG ACCAGACTGAAGTTATTGAATGCGGCTT GGAAGTTAAGCACTTATGCCC...."

Dataset.npy

- Consists of genes and their resistances status against a drug.
- A gene is a string of DNA letters that gets translated into a protein, or amino acid.
- Size of genome sequences are variable, therefore we perform padding to fix size.

Application: Find treatment for diseases

Criteria:

- Use 5-fold cross-validation to select an optimal hyper parameter set.
- Explain your choice of model architecture and any challenges that you encountered.
- Compare CV performance to test performance.

Metric: Accuracy

Structure LSTM-RNN

Input Layer



Embedding Layer



LSTM Layer 1



LSTM Layer 2



Lambda Layer



Output Layer

Input Layer: Genome Sequence of size 190 (X)

Embedding Layer: Projects the input space to the lower dimension spaces

LSTM Layers: A long short-term memory (LSTM) network that avoids the vanishing gradient problem by adding 'forget' gates

Lambda Layers: Wraps an arbitrary expression.

Output Layer:

$$Z_{i}^{[i]} = W_{i}^{[i]^{T}} X + B_{i}^{[i]}$$

W: weight, B: bi

B: bias, Z: output

Analysis

Activation Function: Sigmoid function is used to activate the neurons

$$g(z) = \frac{1}{1 + e^{-z}}$$

It converts estimated probabilities to 0 and 1.

Cross-Entropy Loss:

$$L(z,y) = -[y \log(z) + (1 - y)\log(1 - z)]$$

Updating Weights:

- Take a batch of training data.
- Perform forward propagation to obtain the loss.
- Backpropagate the loss to get the gradients.
- Use the gradients to update the network's weights.

Learning Rate: It will be adapted using Adam's optimizer.

Dropout: 18% Portion - Acts like a regularizer preventing overfitting the training data by dropping out units in a neural network.

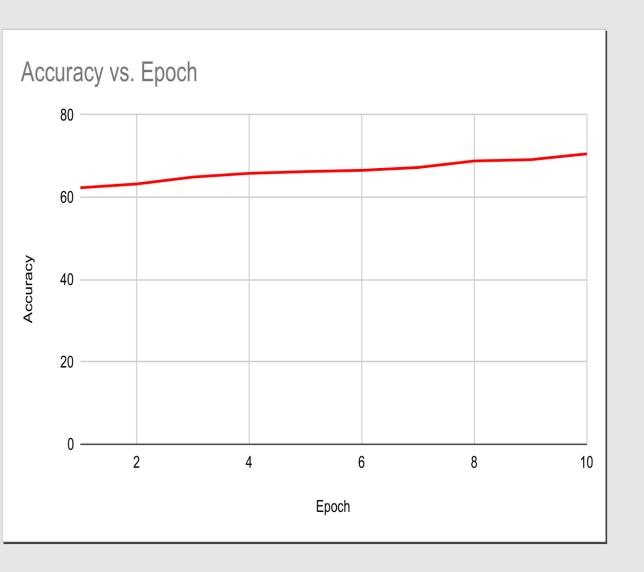
Train-Test: 80%-20% with 5-fold cross-validation to avoid over-fitting issues and discover the hyper-parameters (epoch size, neuron size)

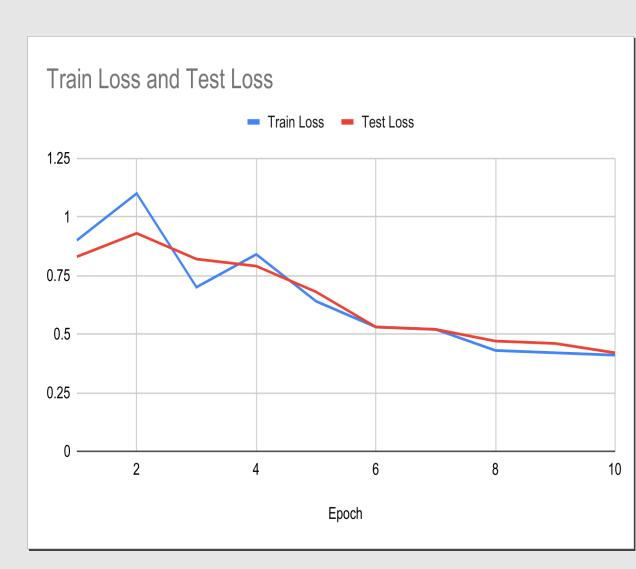
Epoch: 10

Neuron size: 60

Batch Size: 400

Result





Python_Code

```
import tensorflow as tf
 import theano
 import pandas as pd
 import numpy as np
 import matplotlib
 import os
 import math
 import pydot
 import graphviz
 matplotlib.use('pdf')
 import matplotlib.pyplot as plt
 from keras.layers import Dense, Dropout, LSTM, Embedding, Activation, Lambda, Bidirectional
 from keras.engine import Input, Model, InputSpec
 from keras.preprocessing.sequence import pad sequences
 from keras.utils import plot model
 from keras.utils.data utils import get file
 from keras.models import Sequential
 from keras.optimizers import Adam
 from keras.callbacks import ModelCheckpoint
 from sklearn.utils import class weight
 from keras import backend as K
 from keras.preprocessing import sequence
 from keras.models import model from json
 EPCOHS = 10
 BATCH SIZE = 400
 input layer = 4
 output layer = 50
 middle layer = 62
 dropout perentage = 0.18
 seglen = 900
 checkpoint dir = checkpoints
 os.path.exists(checkpoint dir)
def letter to index(letter):
      alphabet = 'ATGC
     return next((i for i, letter in enumerate( alphabet) if letter == letter), None)
def parseInput(test split = 0.1, maxlen = seqlen):
     data = np.load("dataset.npy", allow pickle=True).item()
     df = pd.DataFrame(data, columns=["genes", "resistant"])
     df['genes'] = df['genes'].apply(lambda x: [int(letter to index(e)) for e in x])
     df = df.reindex(np.random.permutation(df.index))
     train size = int(len(df) * (1 - test split))
     X train = df['genes'].values[:train size]
     y train = np.array(df['resistant'].values[:train size])
     X test = np.array(df['genes'].values[train size:])
     y test = np.array(df['resistant'].values[train size:])
     return pad_sequences(X_train, maxlen=maxlen), y_train, pad_sequences(X_test, maxlen=maxlen), y_test
```

```
def build net (input length, rnn hidden dim = middle layer, output dim = output layer, input dim = input layer, dropout = dropout
     model = Sequential()
     model.add(Embedding(input_dim = input_layer, output_dim = output_dim, input_length = input_length, name='embedding_layer'))
     model.add(Bidirectional(LSTM(rnn_hidden_dim, return_sequences=True)))
     model.add(Dropout(dropout))
     model.add(Bidirectional(LSTM(rnn hidden dim)))
     model.add(Dropout(dropout))
     model.add(Dense(1, activation='sigmoid'))
     model.compile('adam', 'binary crossentropy', metrics=['accuracy'])
     return model
def create plots(history):
     plt.plot(history.history['acc'])
     plt.plot(history.history['val acc'])
     plt.title('model accuracy')
     plt.ylabel('accuracy')
     plt.xlabel('epoch')
     plt.legend(['train', 'test'], loc='upper left')
     plt.savefig('accuracy.png')
     plt.clf()
     plt.plot(history.history['loss'])
     plt.plot(history.history['val loss'])
     plt.title('model loss')
     plt.ylabel('loss')
     plt.xlabel('epoch')
     plt.legend(['train', 'test'], loc='upper left')
     plt.savefig('loss.png')
     plt.clf()
☐if name == ' main ':
     X train, y train, X test, y test = parseInput()
     model = build net(len(X train[0]))
     filepath= checkpoint dir + "/weights-improvement-{epoch:02d}-{val loss:.2f}.hdf5"
     checkpoint = ModelCheckpoint(filepath, monitor='val loss', verbose=0, save best only=True, mode='max')
     callbacks list = [checkpoint]
      class_weight = class_weight.compute_class_weight('balanced', np.unique(y_train), y_train)
     print(class weight)
     history = model.fit(X_train, y_train, batch_size=BATCH_SIZE, class_weight=class_weight,
         epochs=EPCOHS, callbacks=callbacks list, validation split = 0.1, verbose = 1)
     model json = model.to json()
     with open ("neuralnet.json", "w") as json file:
         json file.write(model json)
     model.save weights("weights")
     create plots (history)
     plot model(model, to file='model.png')
     score, acc = model.evaluate(X_test, y_test, batch_size=BATCH_SIZE)
     print('score:', score)
     print(' accuracy:', acc)
```