

Regarding HW1)

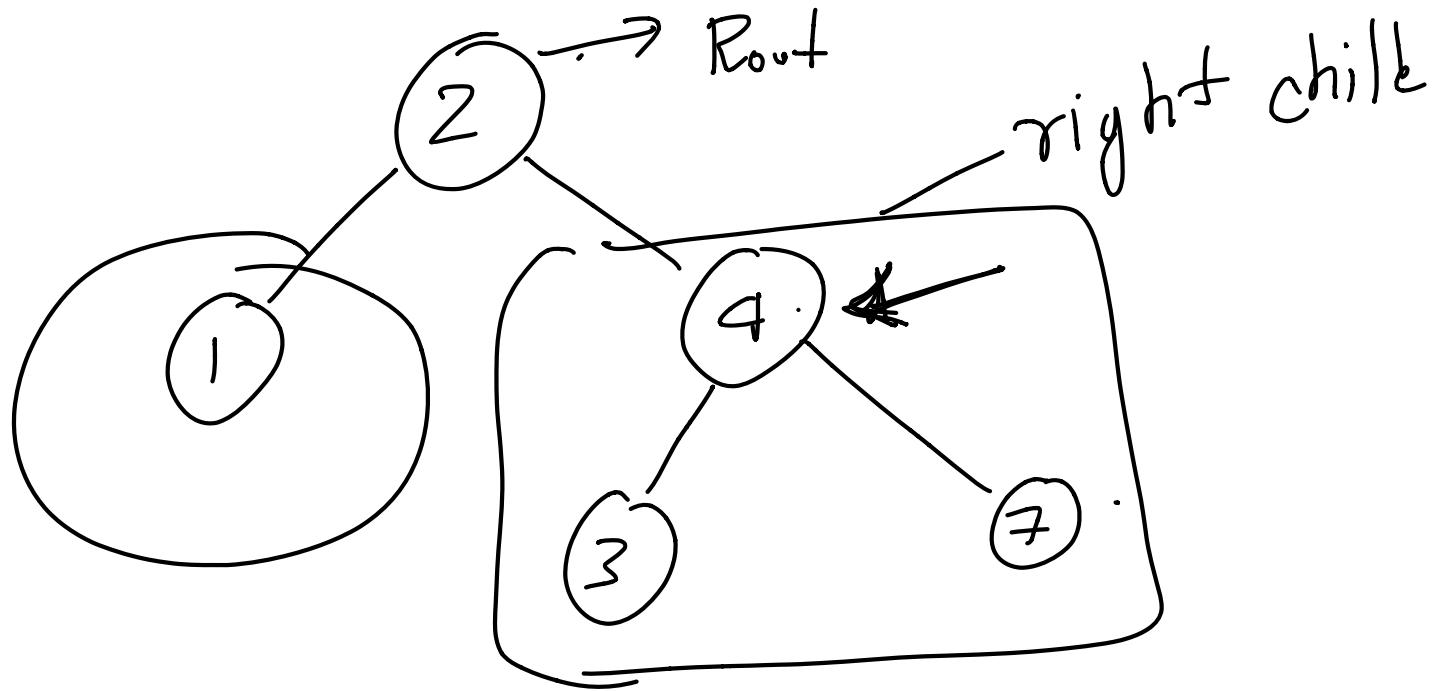
HW11 changed

Type definition of Graph
was changed.

Make sure you use the type
definition.

Binary Search Trees

It's a tree whose nodes/vertices
satisfy "binary search invariance"
property.

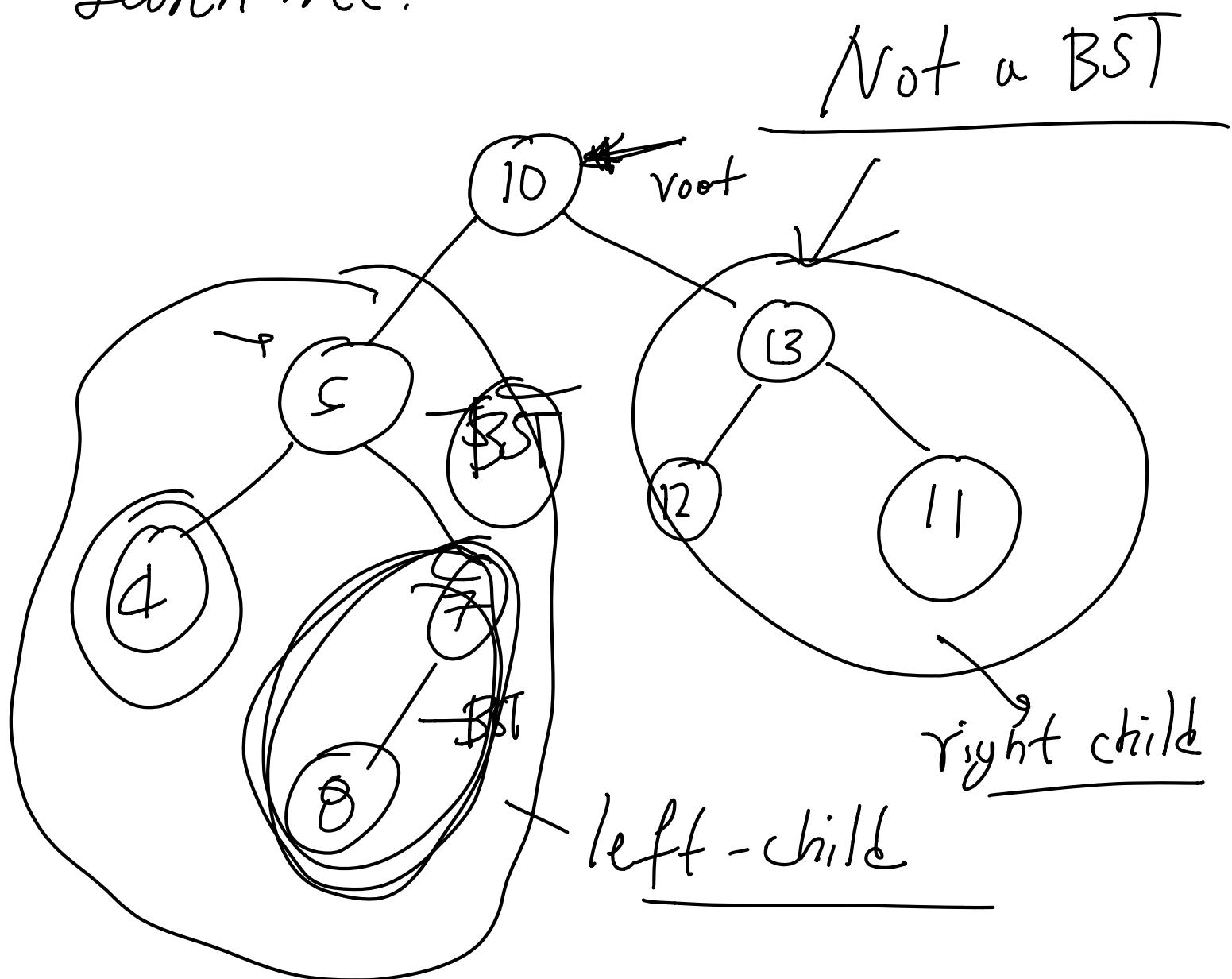


All nodes of the left child of the ^{root}
are less than value of that
node.

All nodes of the right child of the ^{root}
are greater than or equal to
value of that node.

Left child of the root
left child is again a binary search tree.

Right child of the root
right child is again a binary search tree.

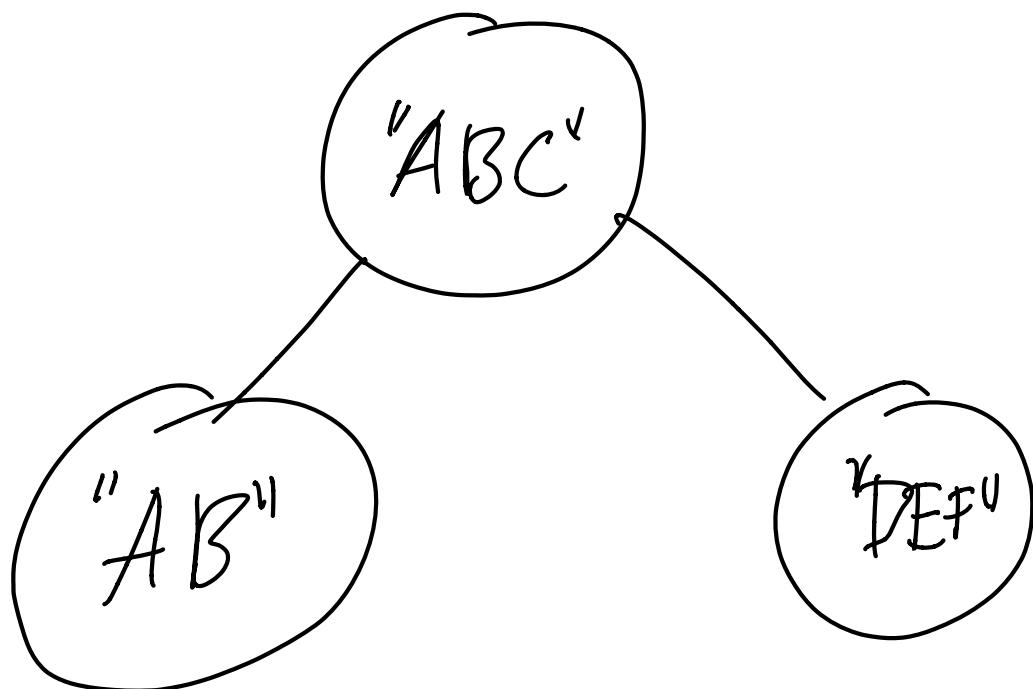


Satisfies condition 1

Satisfies condition 2

Check Left child is a BST

False



"AB" < "ABC" < "DEF"

Racket Definition

(define-struct (BST A))

([He? : (A A → Boolean)])

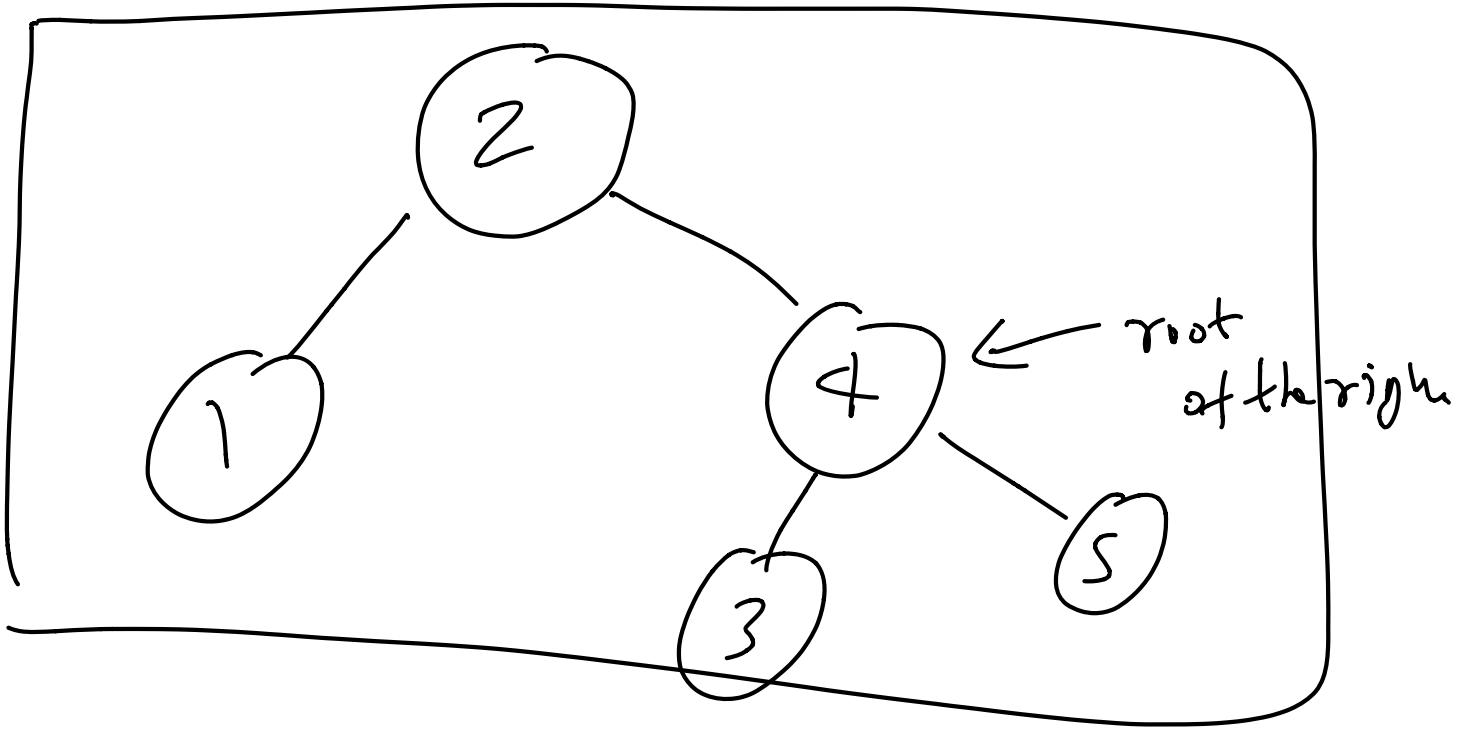
[bst : (U 'none (Node A))])

(define-struct (Node A) ← Binary
Tree)

([value : A])

[left-child : (U 'none (Node A))])

[right-child : (U 'none (Node A))])



Preorder tree.

```

(: root : (Node Integer) ) ← left child
(define root (Node 2 (Node 1
                           'none
                           'none)
                         (Node 4 (Node 3
                           'none
                           'none)
                         (Node 5
                           'none
                           'none))))
```

(λ : my-bst : (BST Integer))
(define my-bst (BST <= root))
 ↑
 key BST

Using lambda

(define my-bst (BST (lambda ([a: Integer]
[b: Integer] (<= a b)))
 root))

1. BST search

Search for target

1. Check if root == target $\xrightarrow{\text{output}} \underline{\text{root}}$
2. if target > root

target if its exists can only exist in the right subtree.

Recursively check for target in the right subtree

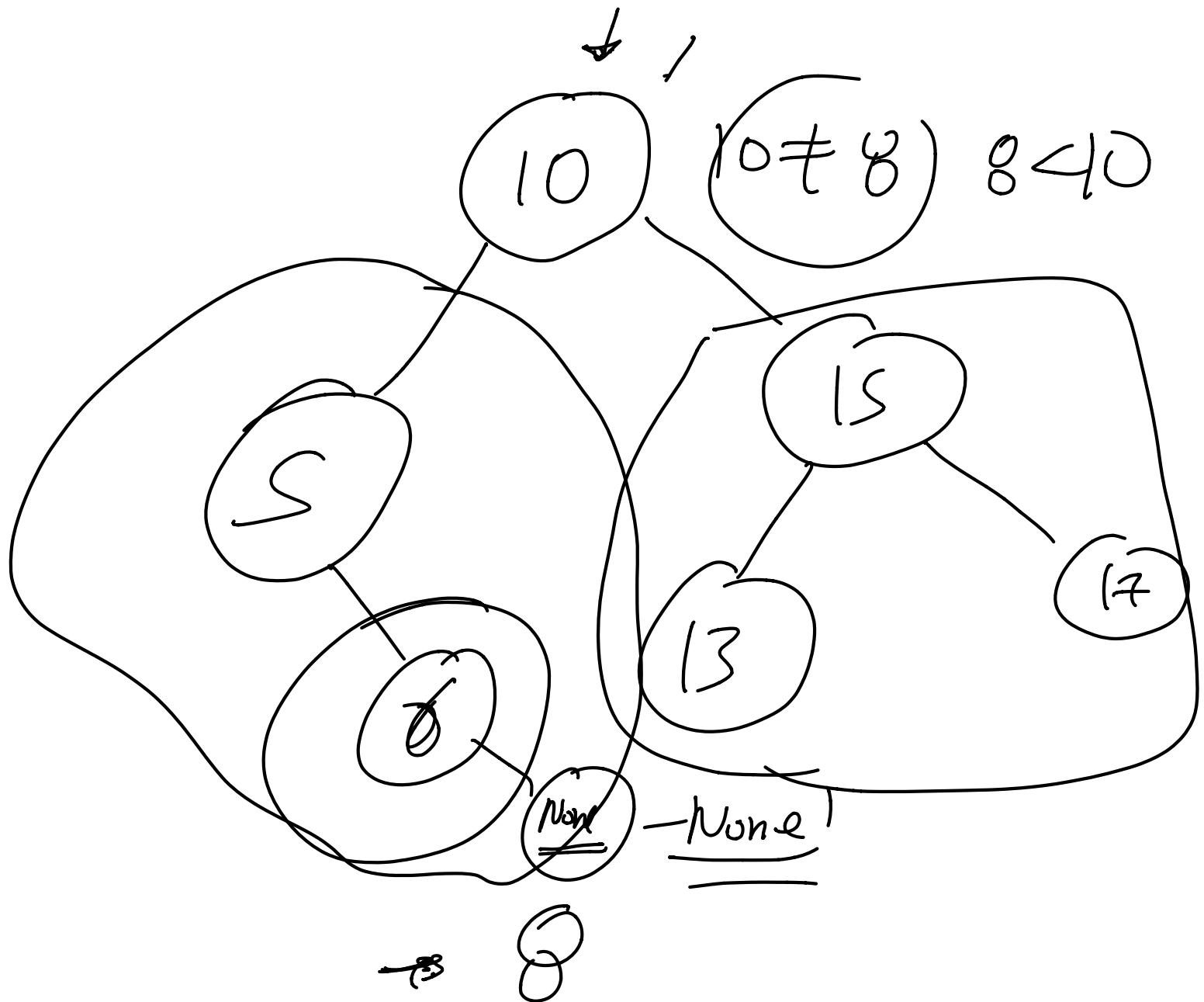
3. if target < root

if target is less than root
that means if target exists
it can only exist in left
subtree.

Recursively check for target
in left subtree.

Base .

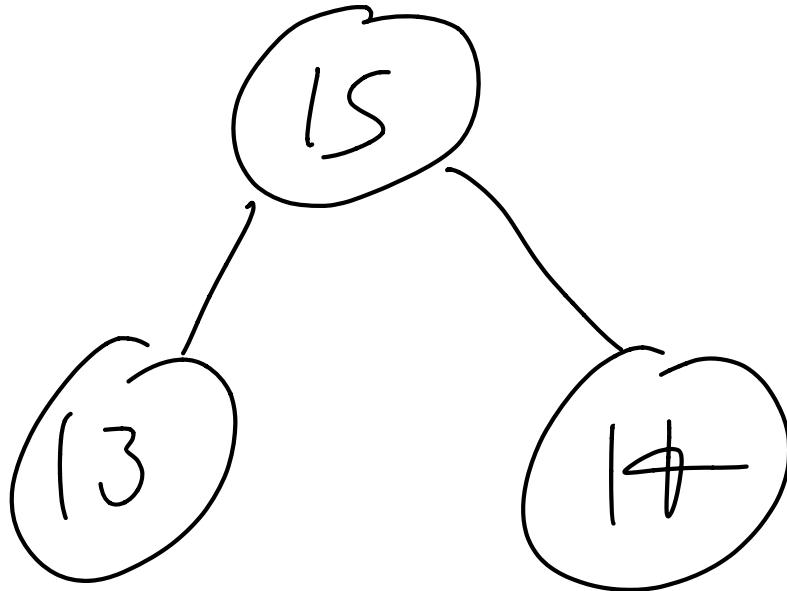
If my tree is empty.
output None.



LS check with the root

10

$LS > R$
go to right subtree



(\because BST search : (All (A) (BST A))
 $A \rightarrow (\vee \text{'none} (\text{BST} A))$

(define (BST-search ? target)
 (match ?
 [((BST _ 'none) 'none)]
 [(BST !te? (Node my-val lc rc))
 (cond
 [and ($a \leq b$)
 and ($b \leq a \Rightarrow \underline{a = b}$)
 [and (!te? target my-val) (

$(\text{Ite? } \text{my-val} \text{ target}) \text{ if }$
[$(\text{Ite? } \text{target} \text{ my-val})$
 $\quad (\text{BST-search } (\text{BST } \text{Ite? } \text{lc})$
 $\quad \text{target}) \text{ if }$
[$(\text{Ite? } \text{my-val} \text{ target}) (\text{BST-search}$
 $\quad (\text{BST } \text{Ite? } \text{rc})$
 $\quad \text{target}) \text{ if }$
[$\text{else } (\text{error "Error"}) \text{ if } \text{if } \text{if } \text{if }$

$$\begin{aligned} & (aRb, bRa \\ \Rightarrow & a = b \end{aligned}$$

Insert something in to BST

Suppose you want insert target in to BST.

Base case : BST is none,
Create a new BST

Check if root < target

recursively insert target
into the right child.

if target < root
recursively insert target
into the left child.

(: BST-insert : (A || (A) A (BST A)
→ (BST A)))

(define (BST-insert value z)

(local

{

(lte?: A A → Boolean)

(define lte? (BST-lte? z))

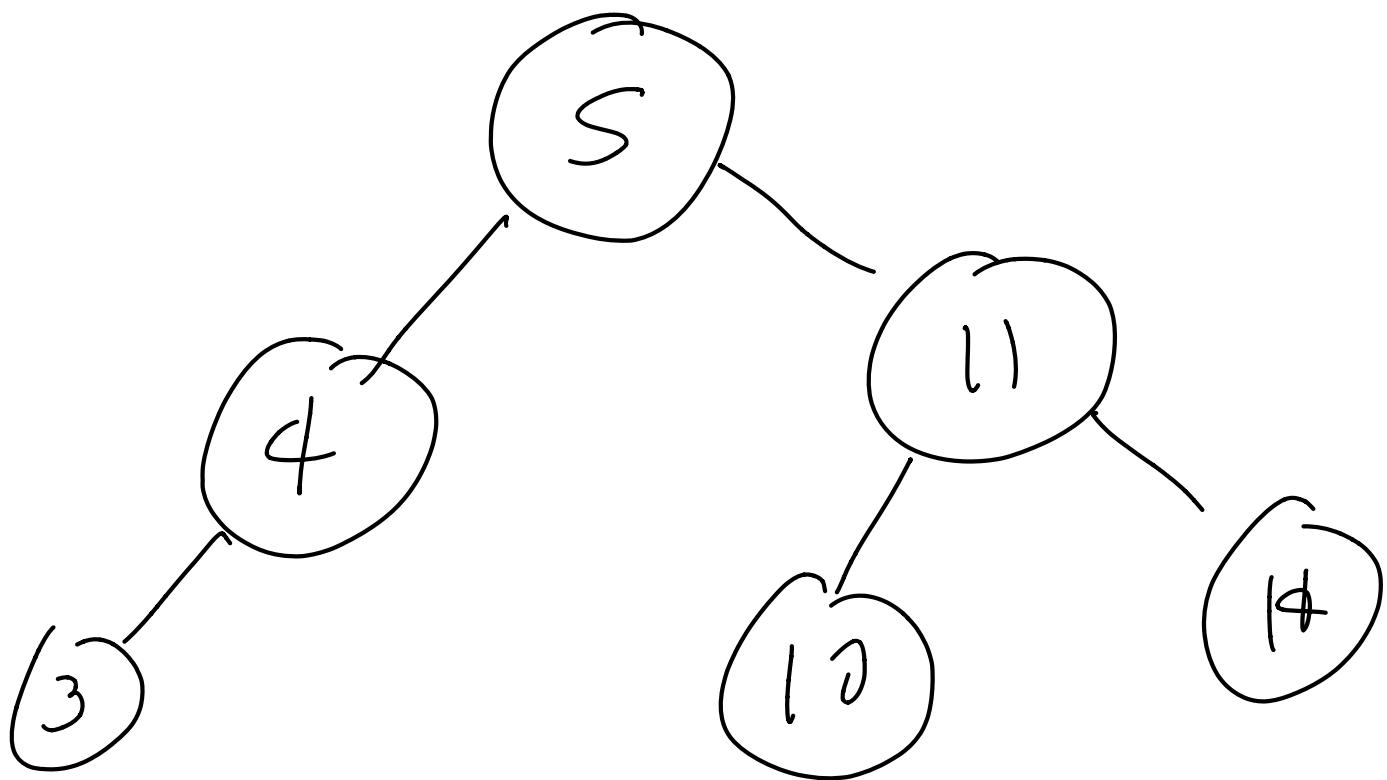
(: node-insert : (V 'none (Node A))
A → (Node A))

(define (node-insert node value)

(match node
['none (Node value 'none 'none)]
[(Node my-val lc rc)
(cond
[(lte? value my-val)
 (node-insert lc value)]
[(lte? my-val value)
 (node-insert rc value)]
[else (error "Error")]]]))]

(BST lte? (node-insert (BST-bst)+
 value)))

Deletion



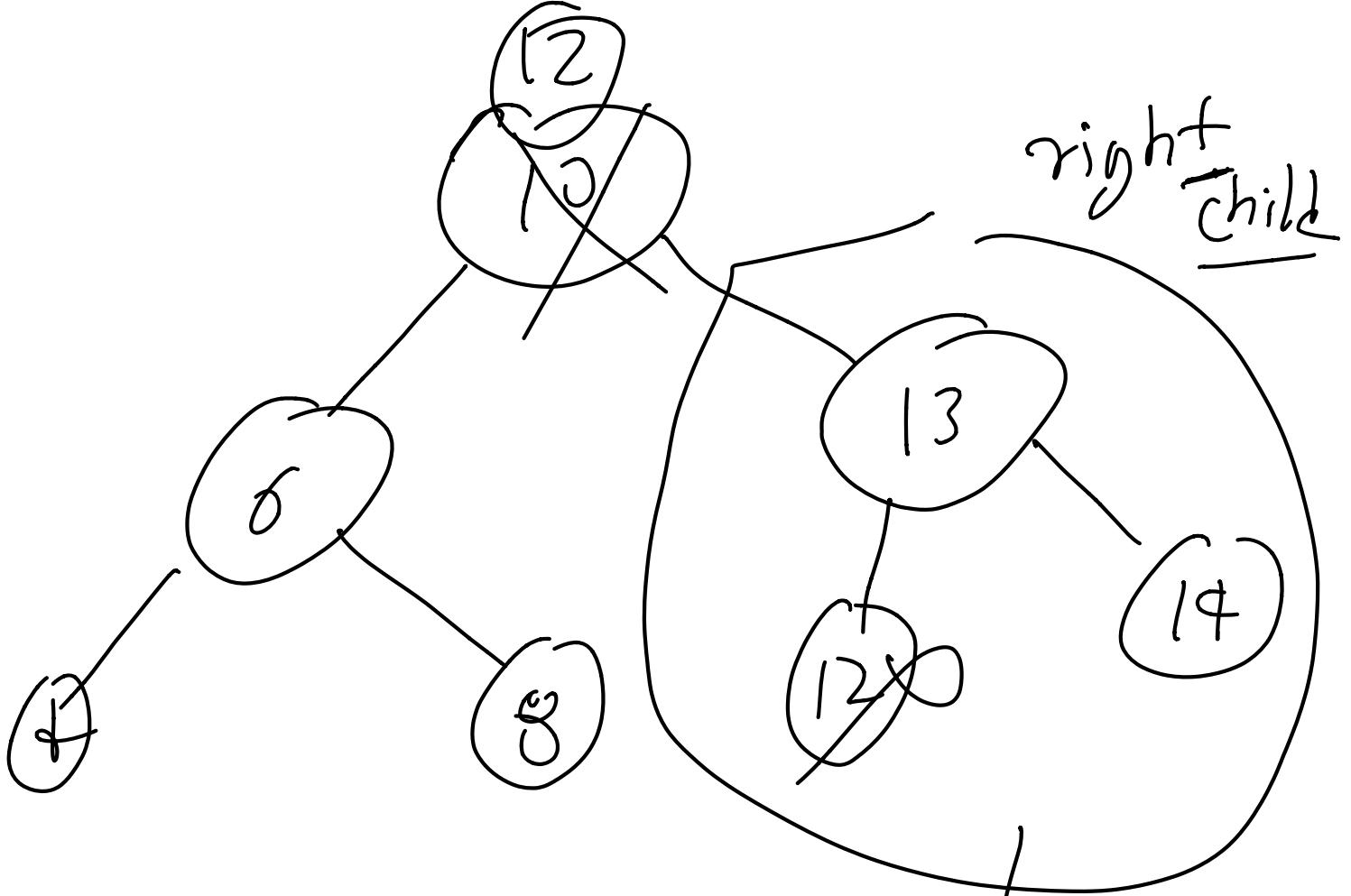
Step 1: If $\text{target} > \underline{\text{root}}$

Then delete from the
right subtree

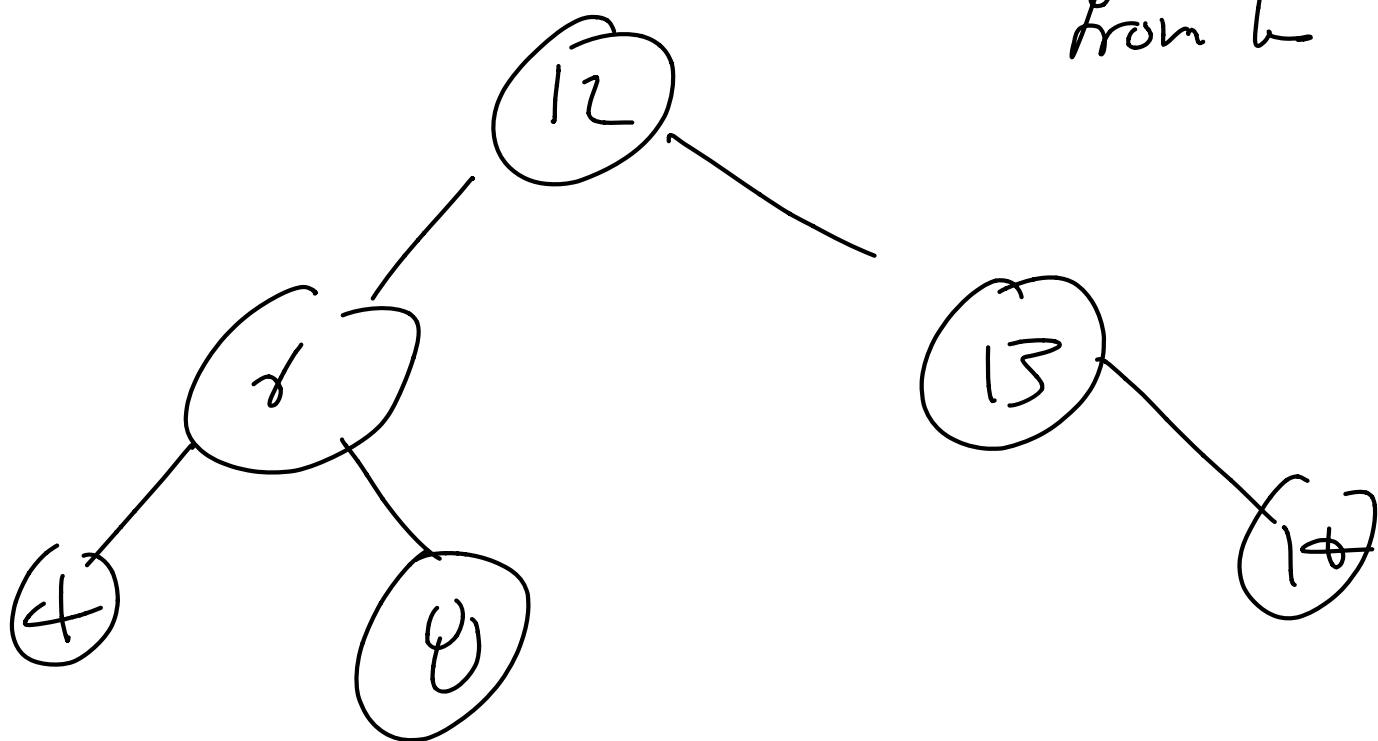
Step 2: If $\text{target} < \text{root}$

Then delete from the
left subtree

If the target is root ?



Smallest
element
from L



If $\text{forget} == \text{root}$

Find smallest in the
right child $\rightarrow S$

Relect S from the right child.

make S the root
Create the tree

(: BST-delete : (All (A) A (BST A))
→ (BST A))

(define (BST-delete value +)

(local
{

(: /te? : AA → Boolean)

(define /te? (BST-/te? +))

(: node-min : (Node A) → A)

(define (node-min node)

(match node ← (left child is missing)
[((Node ∨ 'none r) ∨]

[(Node ∨ l r)

(node-min l)]) .

(: root-delete : (Node A))
→ (\cup 'none (Node A)))

(define (root-delete node)
 (match node → no left child
 [(Node - 'none r) r]
 [(Node - l 'none) l] → no right
 child
 [(Node v l r)
 (local & (define min-val (node-min r)))
 (Node min-val' l (node-delete
 min-val r))]])

(: node-delete : A (\cup 'none
 (Node A)) → (\cup 'none
 (Node A))
 (define node-delete value node))

(match node

['none 'none]

[(Node my-val (c rc))

```
(cond [ (and (lke? value my-val) -value
          (lke? my-val value) ) -root
                (root-delete node) ] -deletion)
```

[(He? value my-val)] root value
Delete from
the left
(Node my-val (Node-delete
value | c) child
root value. rc) }

$\boxed{[(\text{Node? } \text{my-val} \text{ value}) \rightarrow \text{left-left-sons},$
 $\text{right-child}](\text{Node? } \text{my-val} \text{ lc } (\text{Node-delete}$
 $\text{value rc}))]}]$

[else (error "Error")]]])]

(BST /te? (node-delel value
 (BST-bst +))))

Graphs

$$\mathcal{L} = (V, E)$$

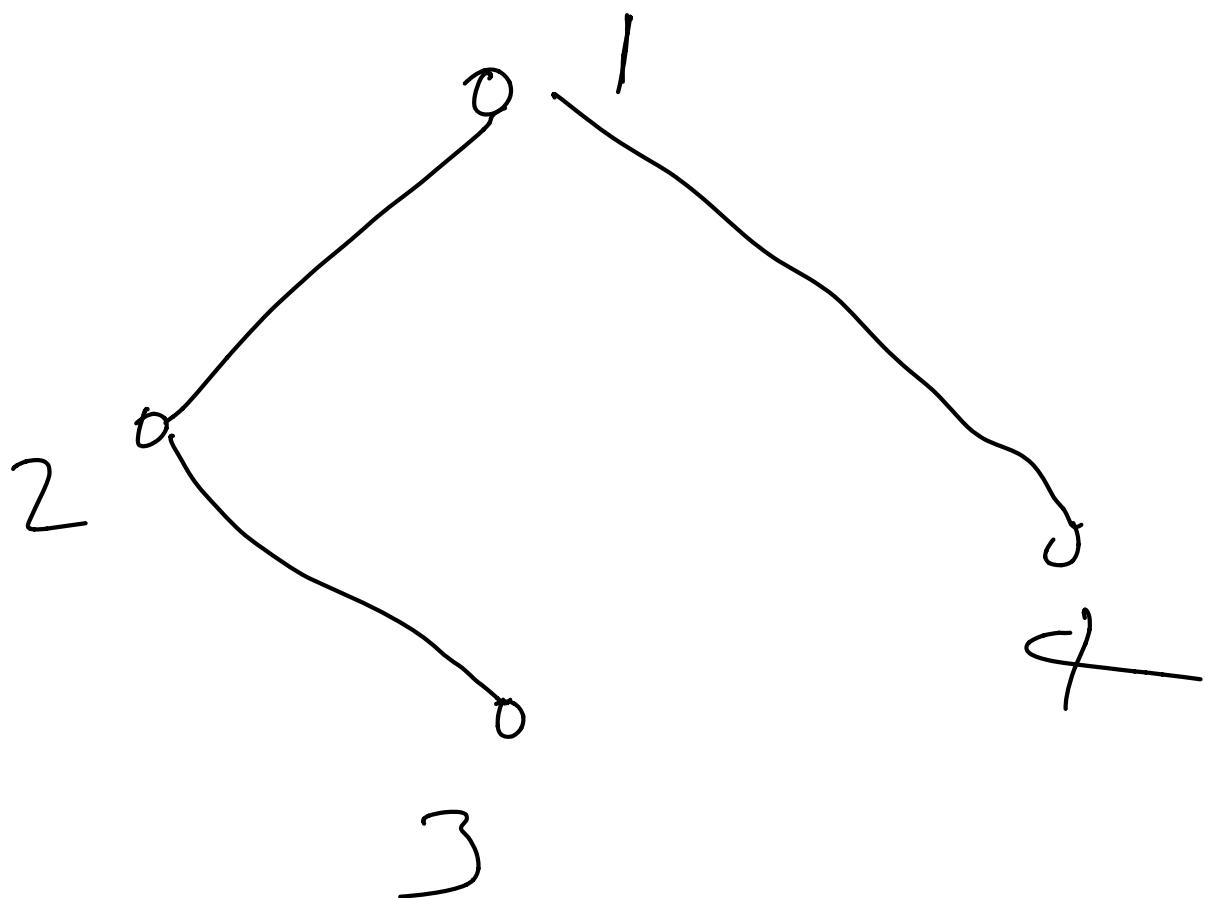
→ vertices

$$V = \{1, 2, 3, 4\}$$

$$E = \{ \underline{\underline{\{1, 2\}}}, \{2, 3\}, \{4, 1\} \}.$$

$$\{1, 2\} = \underline{\underline{\{2, 1\}}}$$

Undirected version



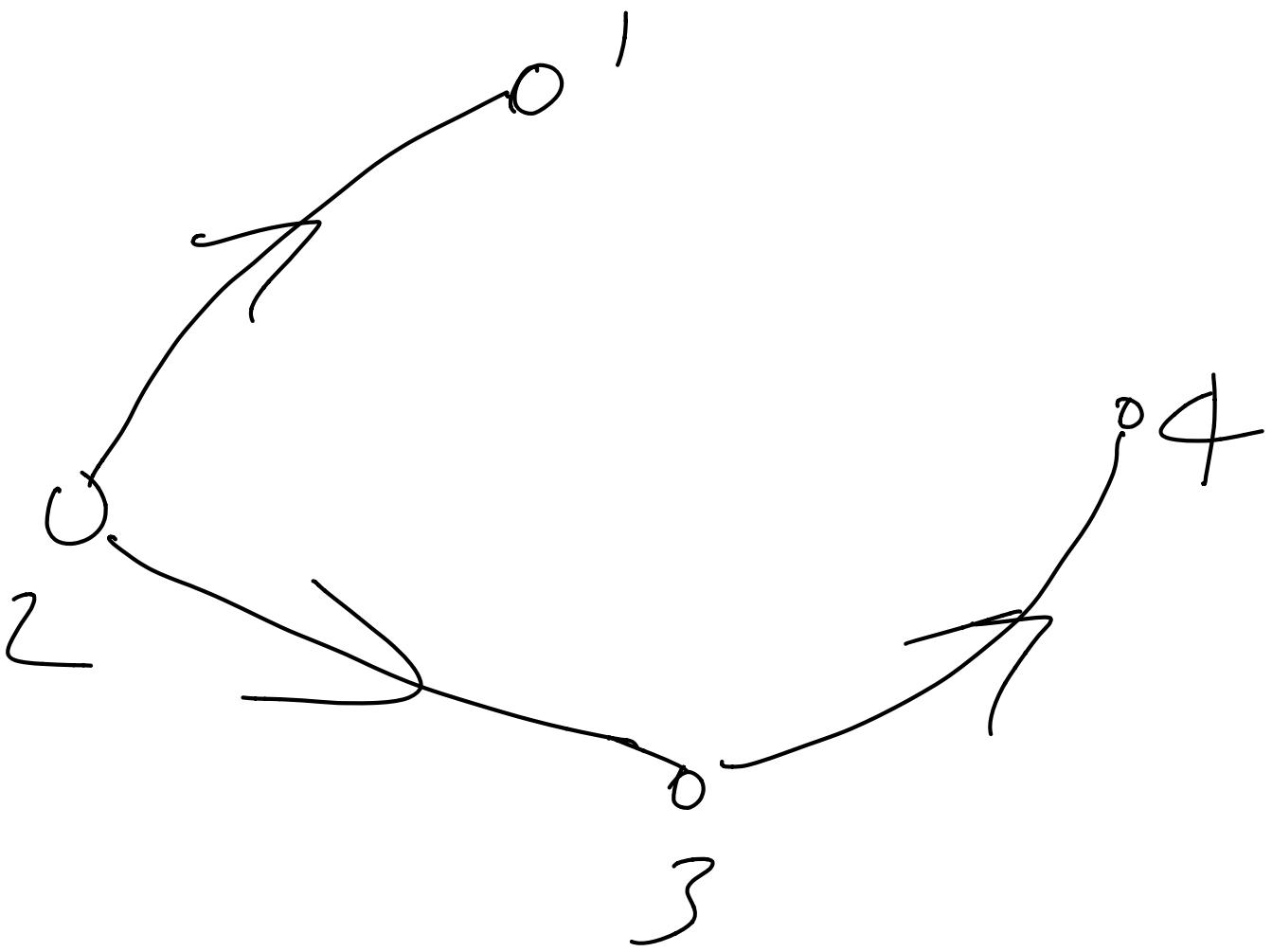
$$\mathcal{L} = (\mathbb{V}, E)$$

$$\mathbb{V} = \{1, 2, 3, 4\}$$

$$E = \{(2, 1), (3, 4), (2, 3)\}$$

↑
ordered pair

$$(2, 1) \neq (1, 2)$$



Adjacency list

1 - []	2 - [1, 3]	3 - [4]	4 - []
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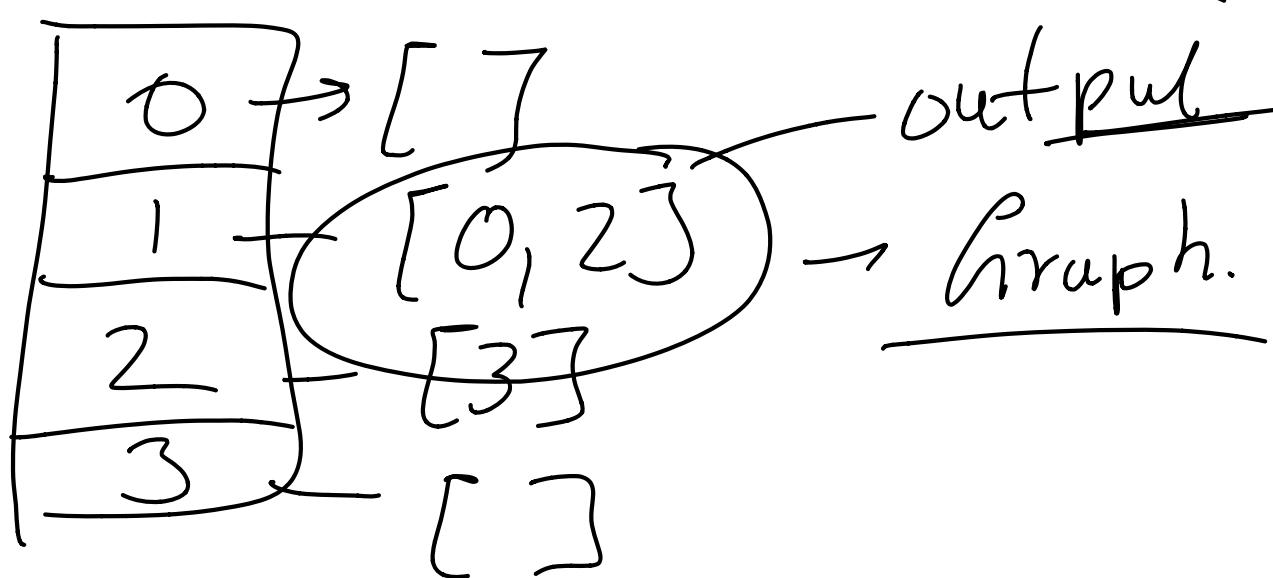
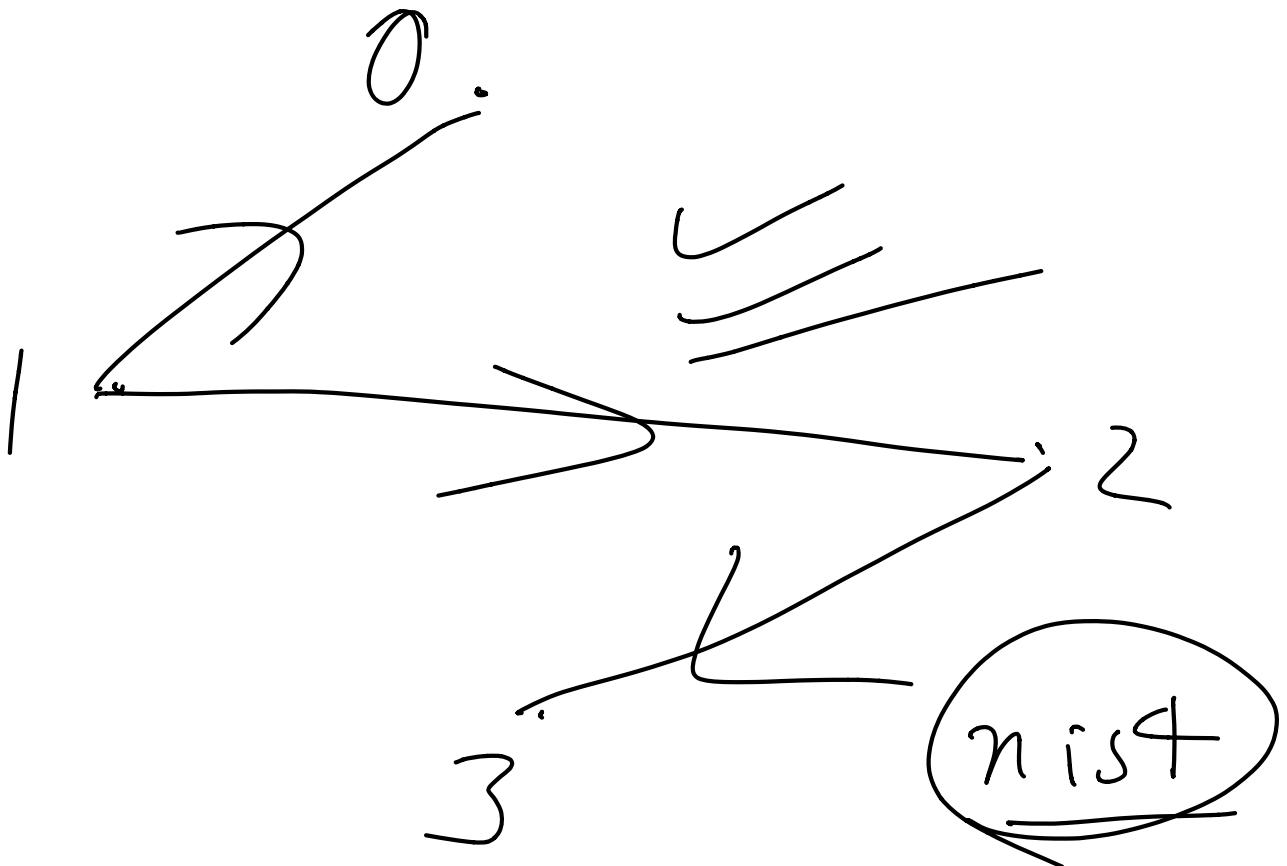
We will adjacency list
representation.

```
(define-type Vertex Integer)
(define-struct Graph
  ([n : Integer]  $\Rightarrow$  numbers of numbers
   [adj : (Vectorof (Listof Vertex))])
```

Why not use list of list
Because vector-ref is $O(1)$
list-ref is not.

Example: Write a function
which takes a graph as

input and outputs
the list of vertices
adjacent to that vertex.



(vector (list)) (list 02) (list 3)

Vertex 1 (list)

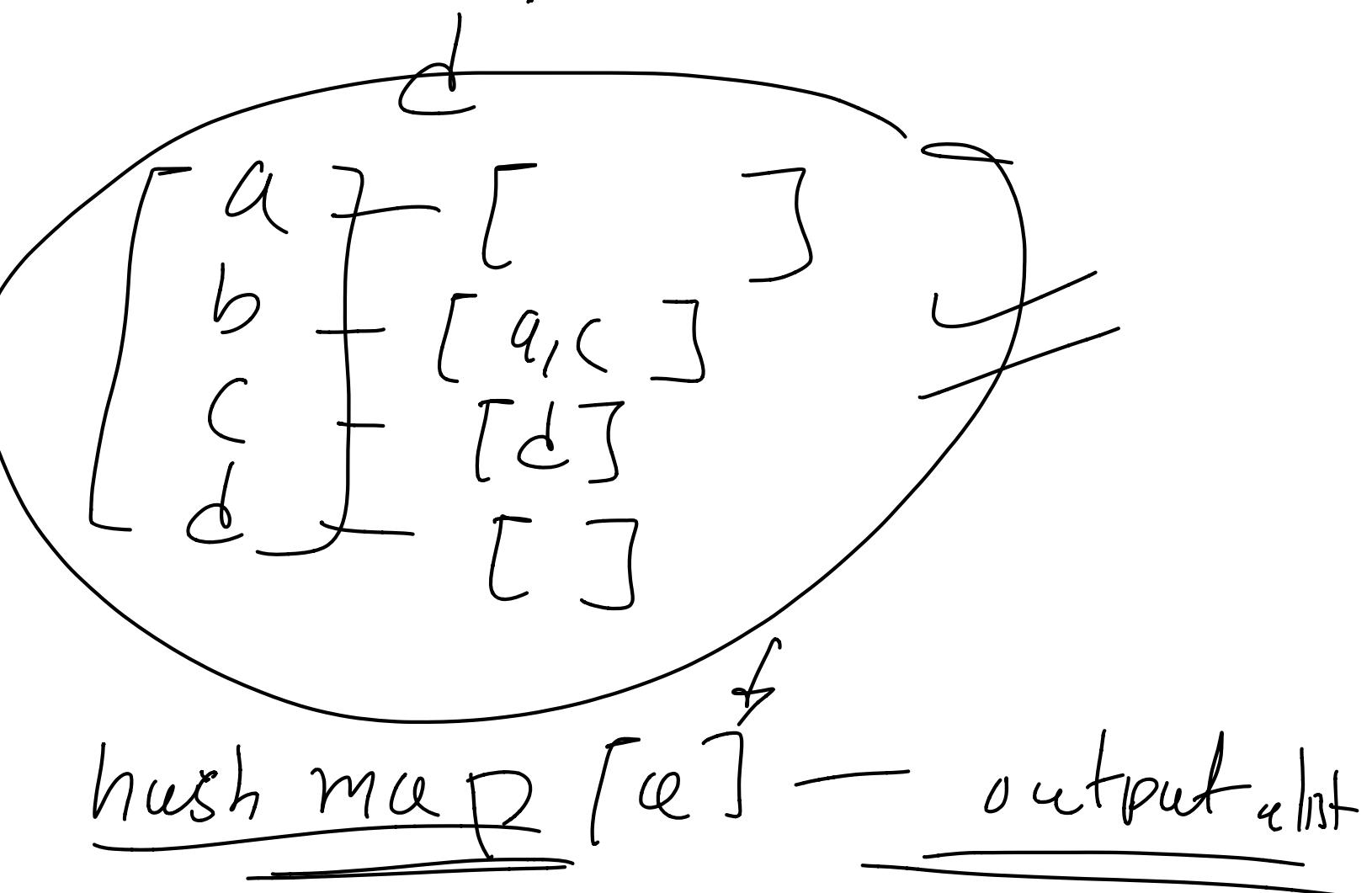
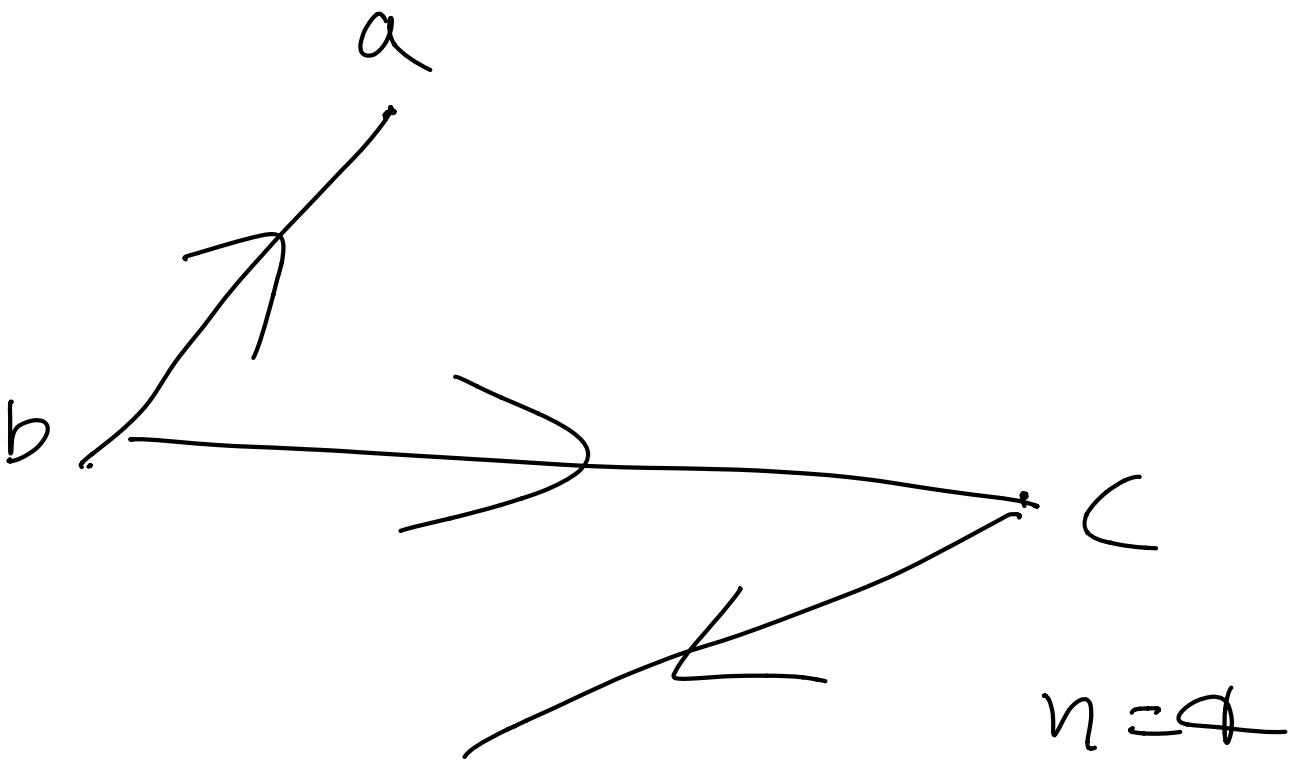
Output should be

[0, 2]

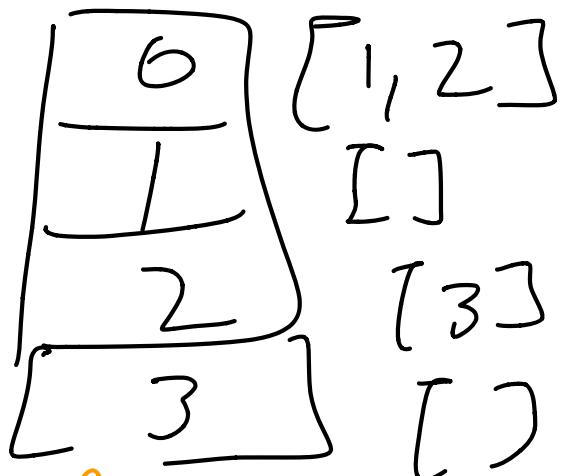
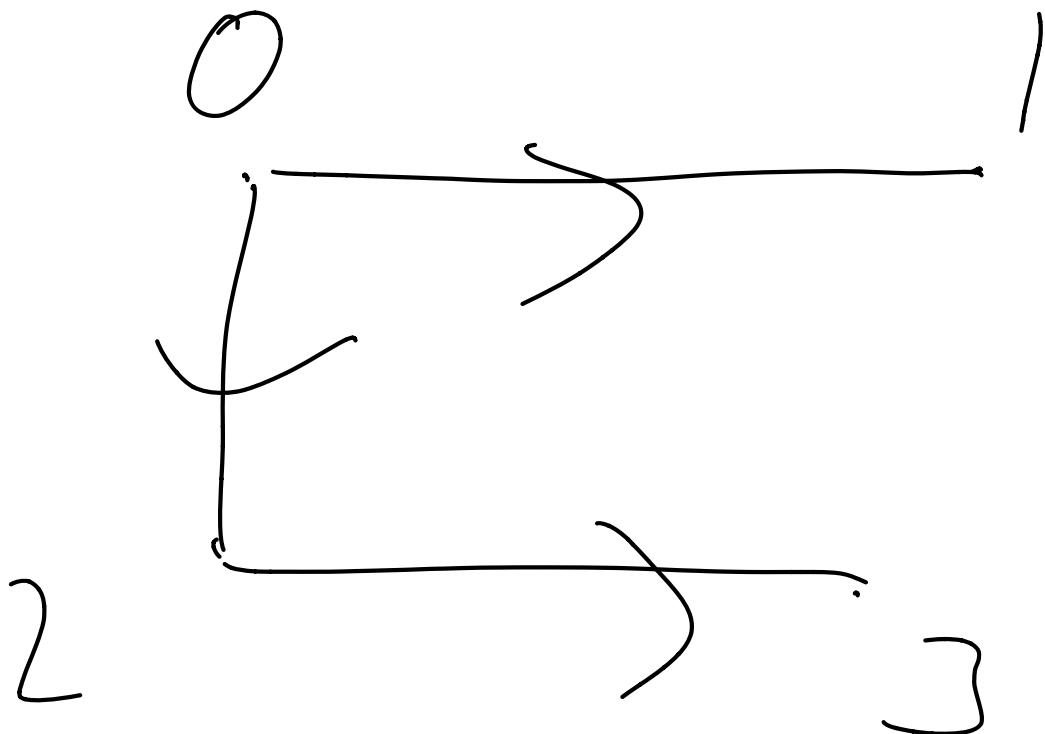
(: get-nbrs : Graph Vertex
→ (Listof Vertex))

(define (get-nbrs g v)

(vector-ref (graph-adj g) v))



Graph example



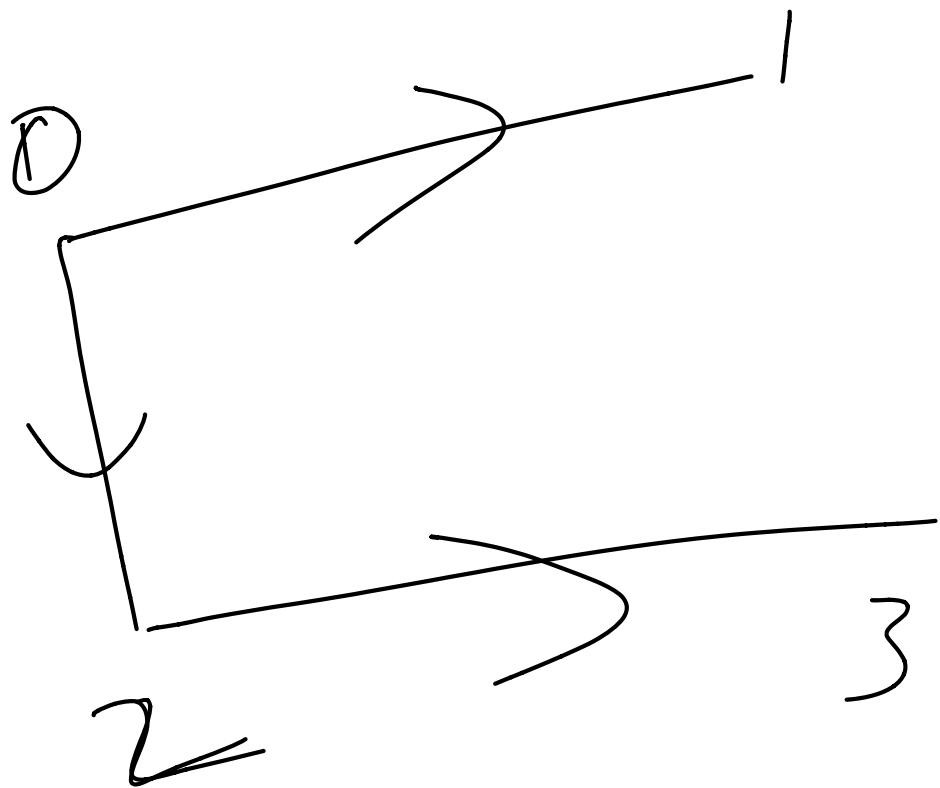
Define my-graph (Graph 3)

(vector (list 1 2) (list)
(list 3) (list))

in-degree of a vertex
is number of incoming
edges into the vertex

out-degree of a vertex

is the number of outgoing
edges from the vertex.



out-degree of 0 is 2
in-degree of 0 is 0

out-degree of 2 is 1
in-degree of 2 is 1

Problem 2 BST

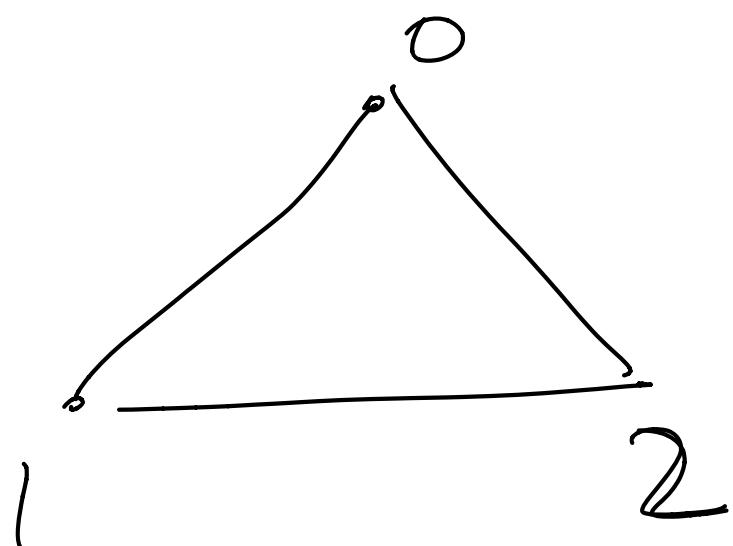
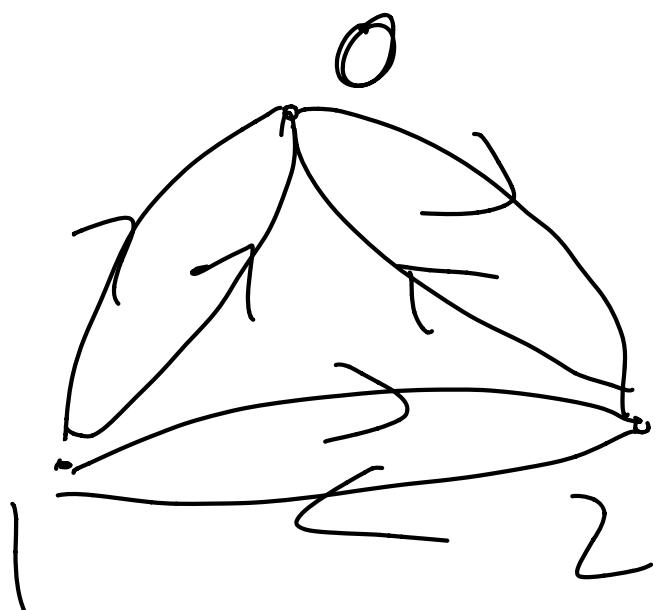
BST-dekk function

BST- & Kt lab last

Save this file in tk
include

(require "include/BST.rkt")

Undirected graph



in-degree of 2 is 2
out-degree of 2 is 2

