

base_link

xyz: -0.28306 -0.0023143 0.18309
rpy: 1.5708 -0 1.5708

joint1

Link1

xyz: 0.32463 0.005 -0.0010683
rpy: -3.14159 -0.0032638 -3.14159

joint2

Link2

xyz: -0.4276 0.1842 -0.0082182
rpy: 2.9911 -1.38778e-17 -1.5708

joint3

Link3

xyz: 0.1892 -0.839 0.50165
rpy: 0 -0.15379 1.5708

joint4

Link4

xyz: 0.32463 0.005 -0.0010683
rpy: -3.14159 -0.0032638 -3.14159

joint5

Link5

xyz: -0.427604 0.1842 -0.00821818
rpy: 2.99107 1.38778e-17 -1.5708

joint6

Link6