



IBM Developer
SKILLS NETWORK

Winning Space Race with Data Science

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14 December 2021

Outline

Executive Summary

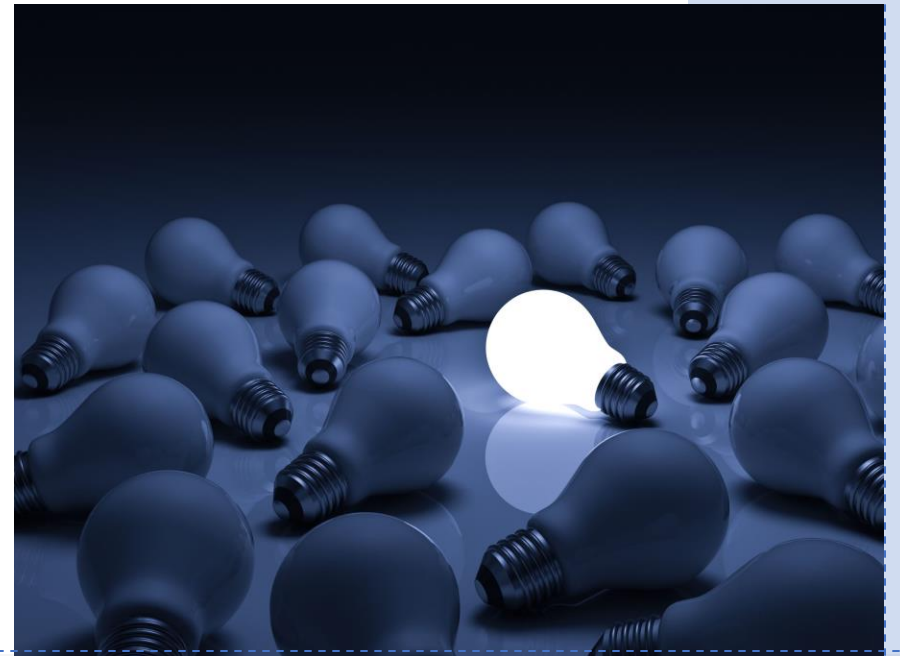
Introduction

Methodology

Results

Conclusion

Appendix





Executive Summary

Summary of methodologies

Data Collection

Data Wrangling

EDA with SQL

EDA with data visualization

Building an Interactive map with Folium

Building an Interactive Dashboard
with Plotly Dash

Predictive Analysis (Classification)

Summary of all results

Exploratory Data Analysis results

Interactive Analytics (screenshots)

Predictive Analysis results

Introduction

Project background and context

We predicted whether the first stage of the SpaceX's Falcon 9 rocket would land successfully.

SpaceX advertises Falcon 9 rocket launches on its website with a cost of 62 million dollars; other providers cost upwards of 165 million dollars each, much of the savings is because SpaceX can reuse the first stage. Therefore, if we can determine if the first stage will land, we can determine the cost of a launch.

Problems you want to find answers

- Relationship between rockets variables outcome
- In what case the rocket will land successfully

Methodology

Data collection methodology:

- SpaceX REST API, Web scraping from [Wikipedia](#)

Perform data wrangling

- I converted landing outcomes to Classes (0 or 1) with using OneHotEncoder
- **Perform exploratory data analysis (EDA) using visualization and SQL**
- Plotting: scatter point chart, bar chart to show relationships between variables

Perform interactive visual analytics using Folium and Plotly Dash

- I built a dashboard to analyze launch records interactively with Plotly Dash and an interactive map to analyze the launch site proximity with Folium.

Perform predictive analysis using classification models

I split my data into training data and test data to find the best Hyperparameter for SVM, Classification Trees, and Logistic Regression. Then find the method that performs best using test data.

Data Collection

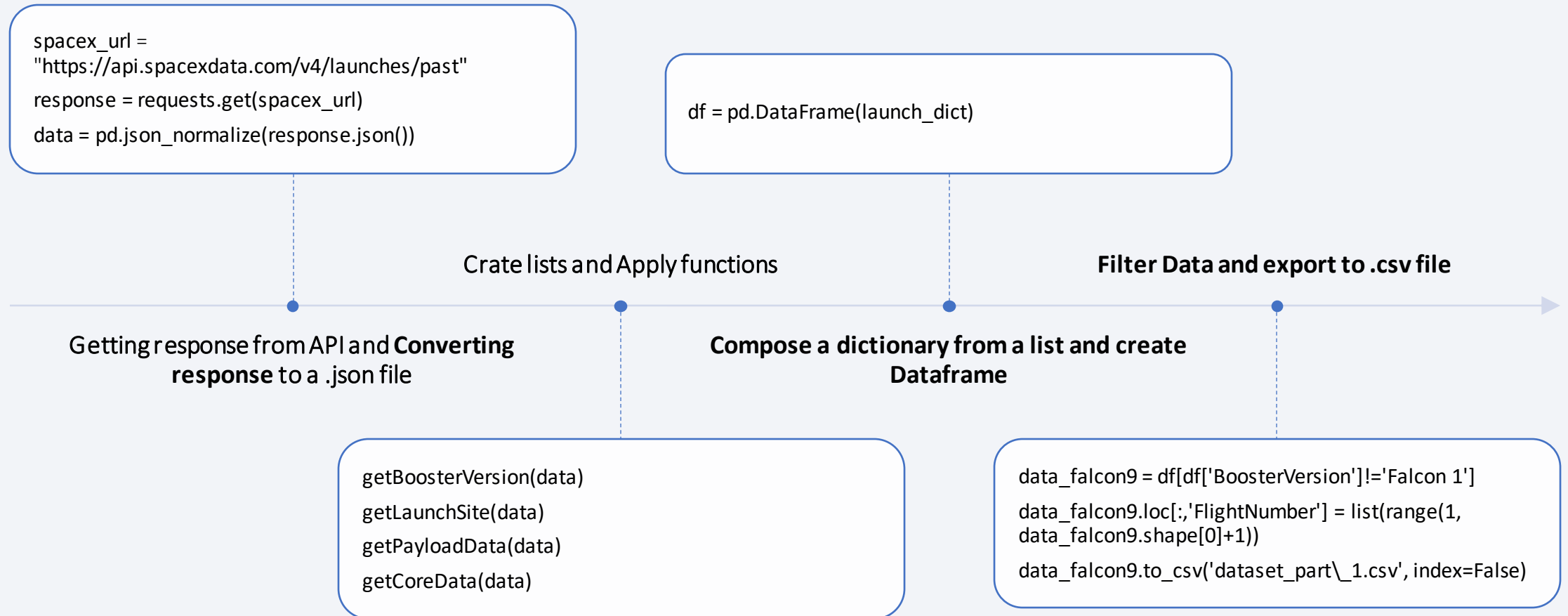
Getting Data from Api
and Web page

Convert it to Dataframe

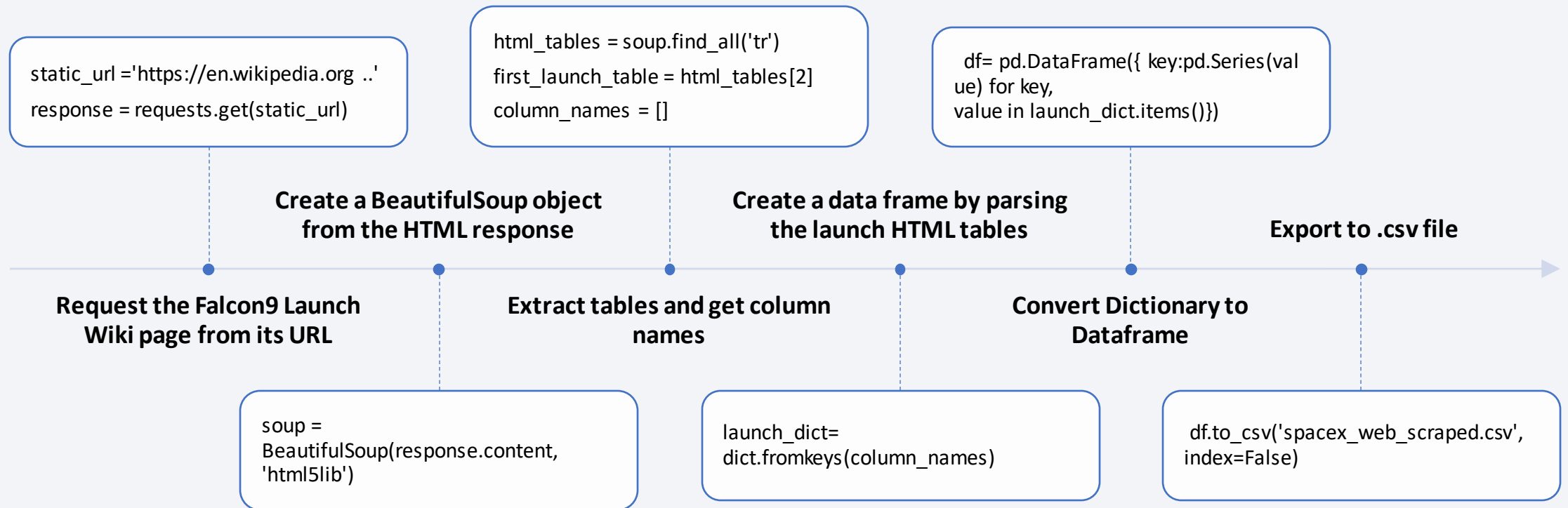
Clean and
Filter Dataframe

Export it to a CSV file

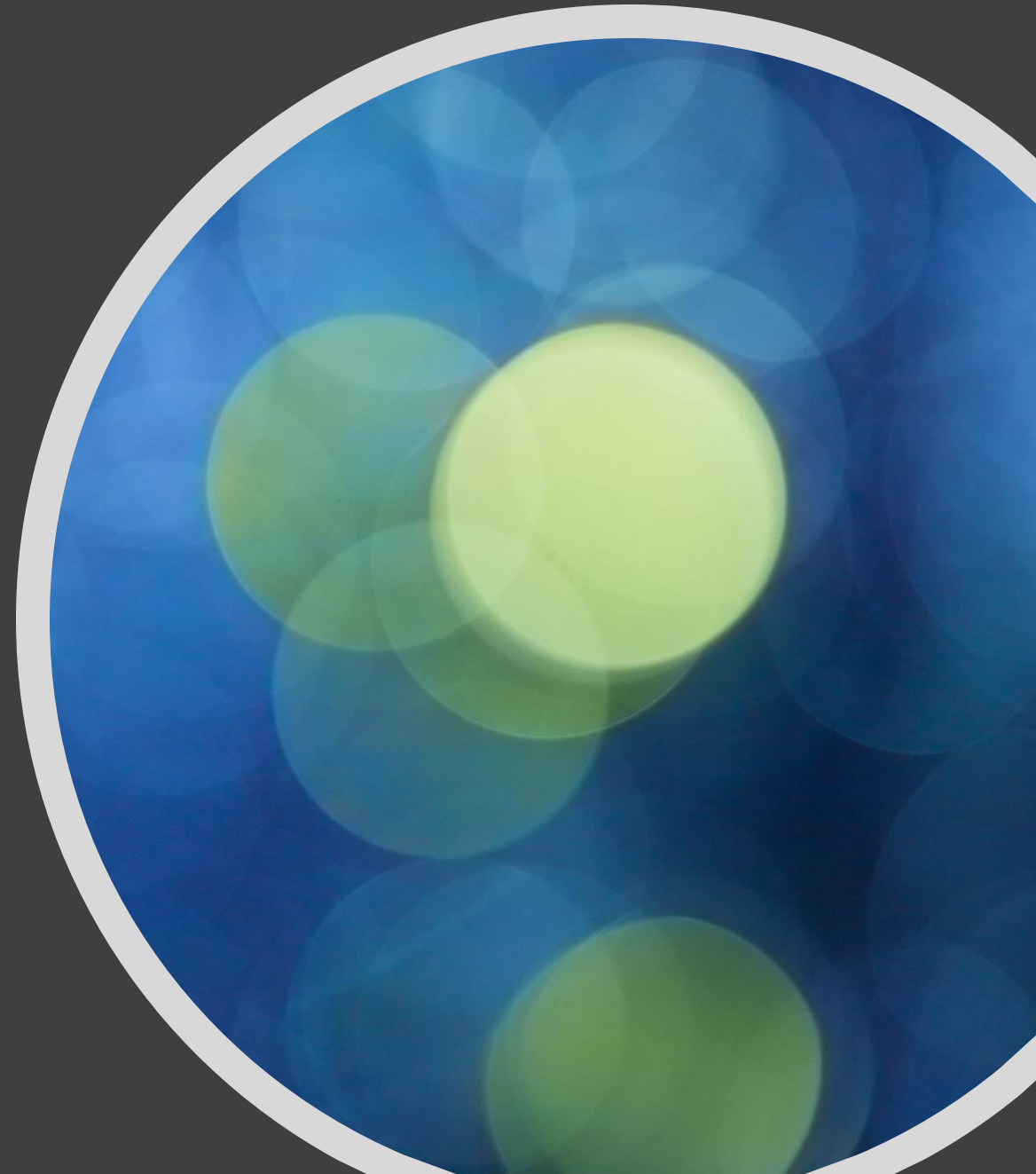
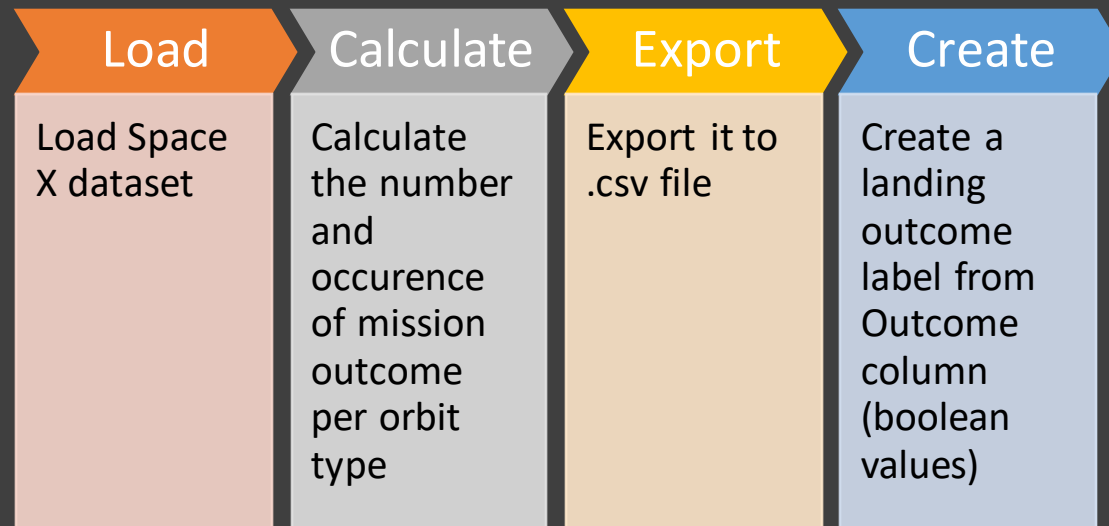
Data Collection – SpaceX API



Data Collection - Scraping



Data Wrangling





EDA with Data Visualization

Scatter point chart:

FlightNumber vs. PayloadMass and

FlightNumber vs LaunchSite

Payload vs. Launch Site

FlightNumber vs Orbit type

Payload vs. Orbit

Bar chart:

Success rate of each orbit type

Line chart

launch success yearly trend

GitHub

[Link](#)

EDA with SQL

1. *Display the names of the unique launch sites in the space mission*
2. *Display 5 records where launch sites begin with the string 'CCA'*
3. *Display the total payload mass carried by boosters launched by NASA (CRS)*
4. *Display average payload mass carried by booster version F9 v1.1*
5. *List the date when the first successful landing outcome in ground pad was achieved*
6. *List the names of the boosters which have success in drone ship and have payload mass greater than 4000 but less than 6000*
7. *List the total number of successful and failure mission outcomes*
8. *List the names of the booster_versions which have carried the maximum payload mass.*
9. *List the failed landing_outcomes in drone ship, their booster versions, and launch site names for in year 2015*
10. *Rank the count of landing outcomes (such as Failure (drone ship) or Success (ground pad)) between the date 2010-06-04 and 2017-03-20, in descending order*

[GitHub](#)



| MAP Object | Code | Explanation |
|----------------|----------------------------------|---|
| Circle | <code>Folium.Circle()</code> | Create circle area with a text label on a specific coordinate where Marker is being placed |
| Marker | <code>folium.map.Marker()</code> | To make a mark on Map |
| Marker Cluster | <code>MarkerCluster()</code> | Marker clusters can be a good way to simplify a map containing many markers having the same coordinate. |
| Mouse Position | <code>MousePosition()</code> | To get coordinate for a mouse over a point on the map |
| PolyLine | <code>folium.PolyLine()</code> | Create the line between points |

- [GitHub](#)

Build an Interactive Map with Folium

| Map Object | Code | Explanation |
|---------------|--|--|
| Dropdown | <code>dcc.Dropdown()</code> | Add a dropdown list to enable Launch Site selection |
| Range Slider | <code>dcc.RangeSlider()</code> | Add a slider to select payload range |
| Pie Chart | <code>dcc.Graph(id='success-pie-chart')</code> | Add a pie chart to show the total successful launches count for all sites |
| Scatter Chart | <code>dcc.Graph(id='success-payload-scatter-chart')</code> | Add a scatter chart to show the correlation between payload and launch success |

- [GitHub](#)

Build a Dashboard with Plotly Dash

Predictive Analysis (Classification)

Building model

- Load DataFrame
- Create a NumPy array from the column Class in data
- Standardize and transform the data
- Split the data into training and testing data
- Create a logistic regression object then create a GridSearchCV object. Then fit the model

Evaluating Model

- Find accuracy for each model
- Find best parameters
- Plot confusion matrixes

Find the method performs best

- Finding the model with best accuracy using the method score

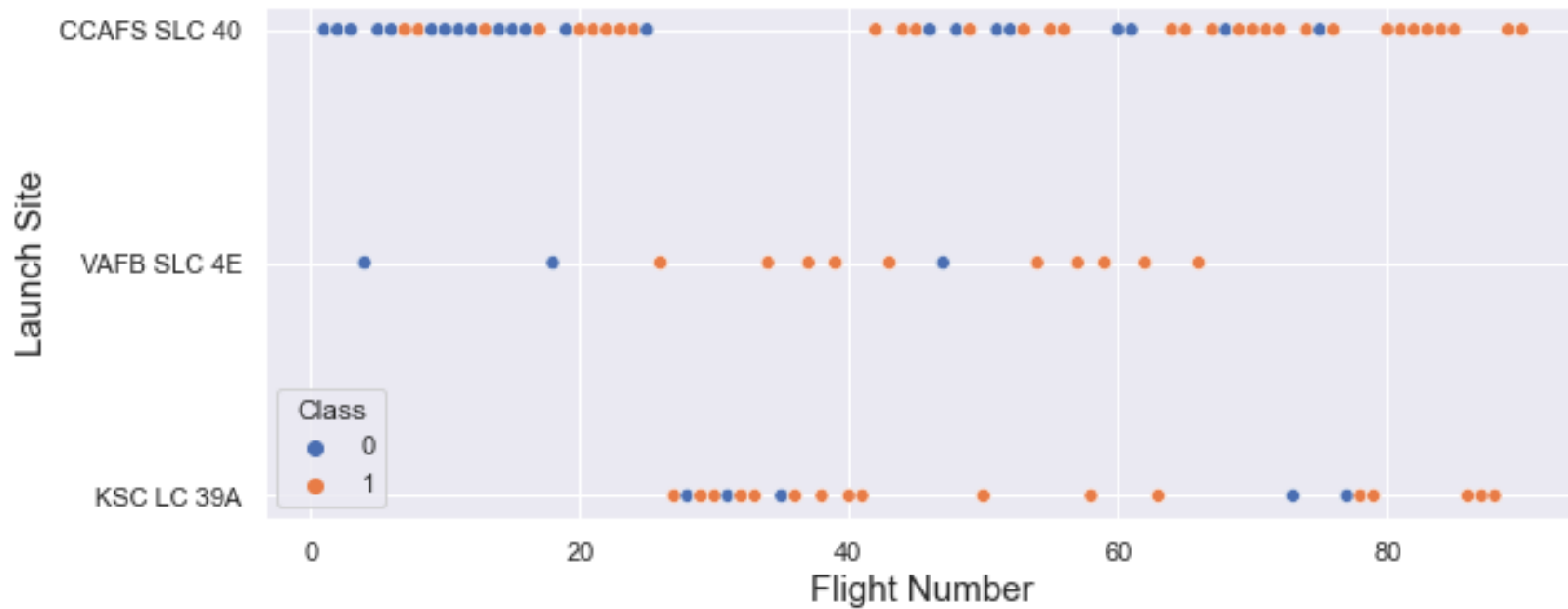
Results

- Exploratory data analysis results
- Interactive analytics demo in screenshots
- Predictive analysis results



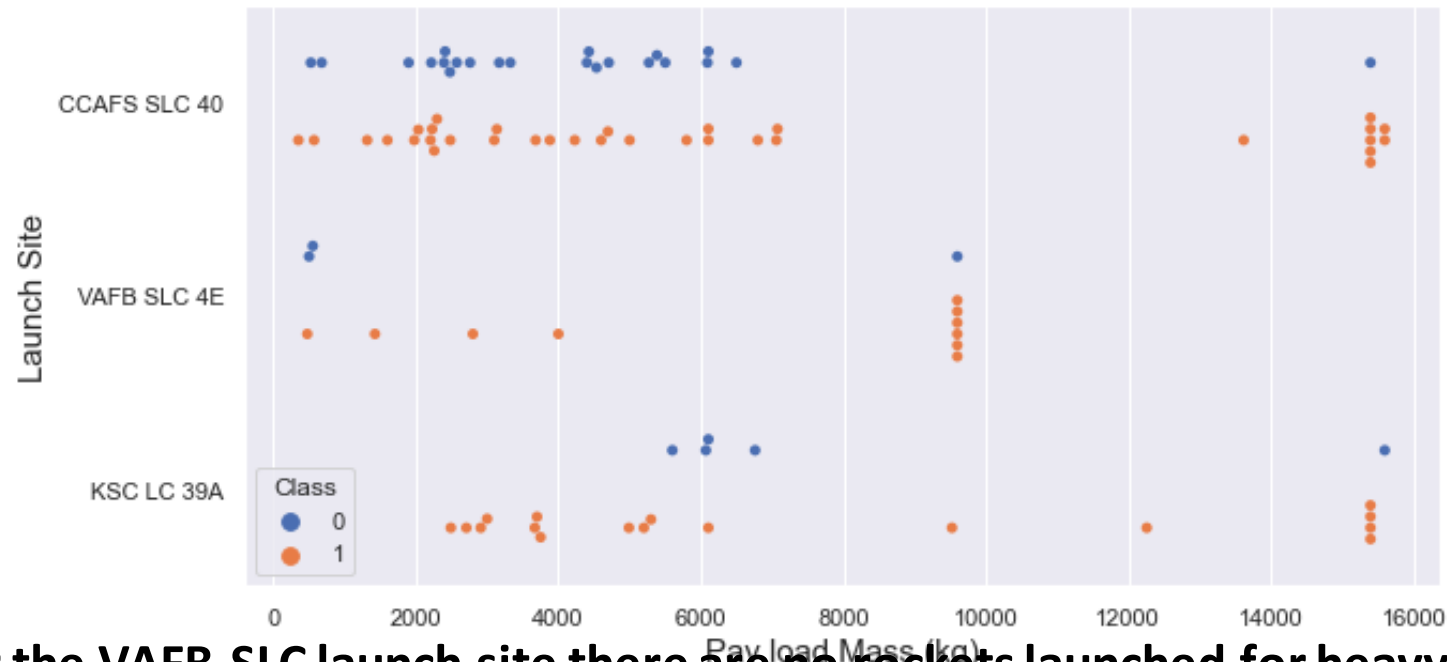
EDA with Visualization





- With higher Flight number the success Launch site is increasing

Flight Number vs. Launch Site

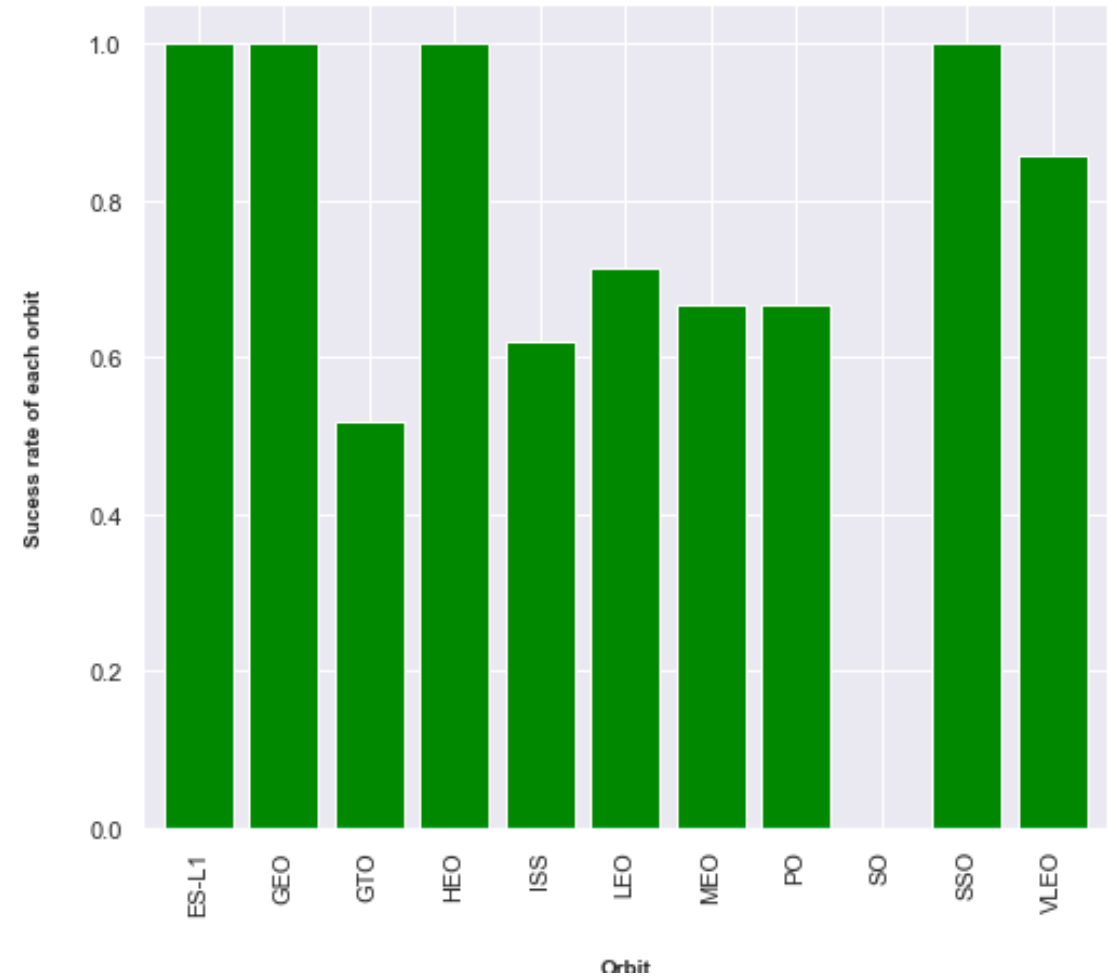


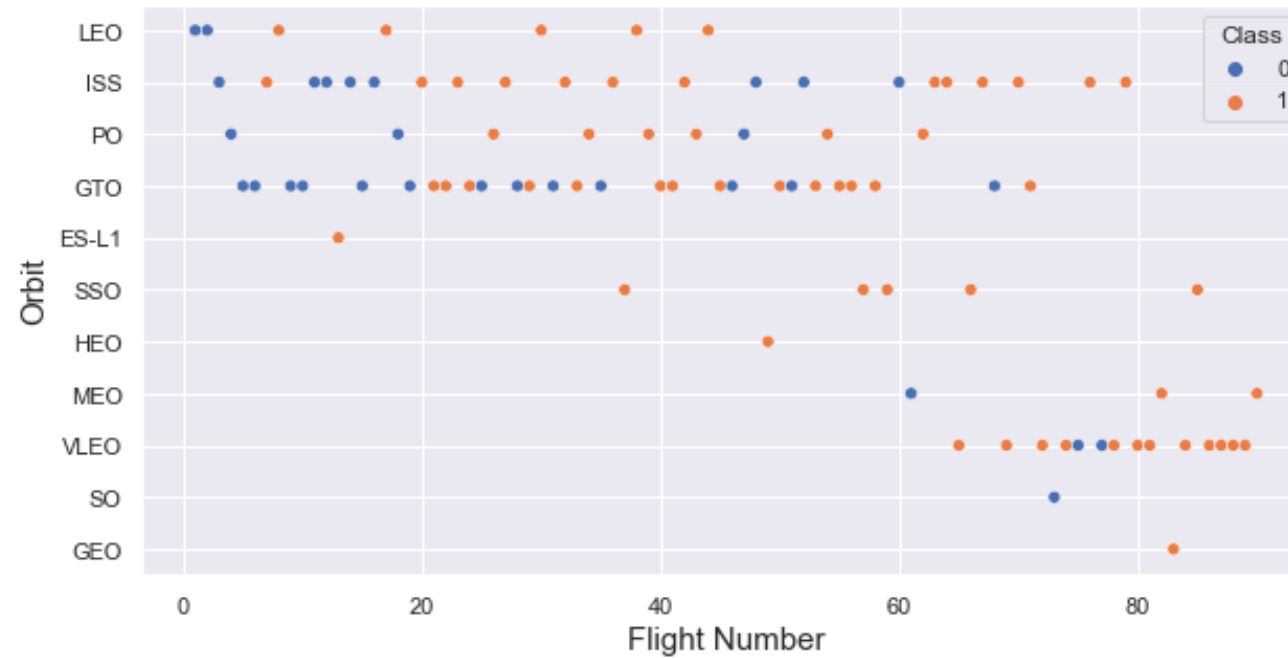
- For the VAFB-SLC launch site there are no rockets launched for heavy payload mass(greater than 10000).
- And the greater the Payload mass, the higher the success rate

Payload vs. Launch Site

Success Rate vs. Orbit Type

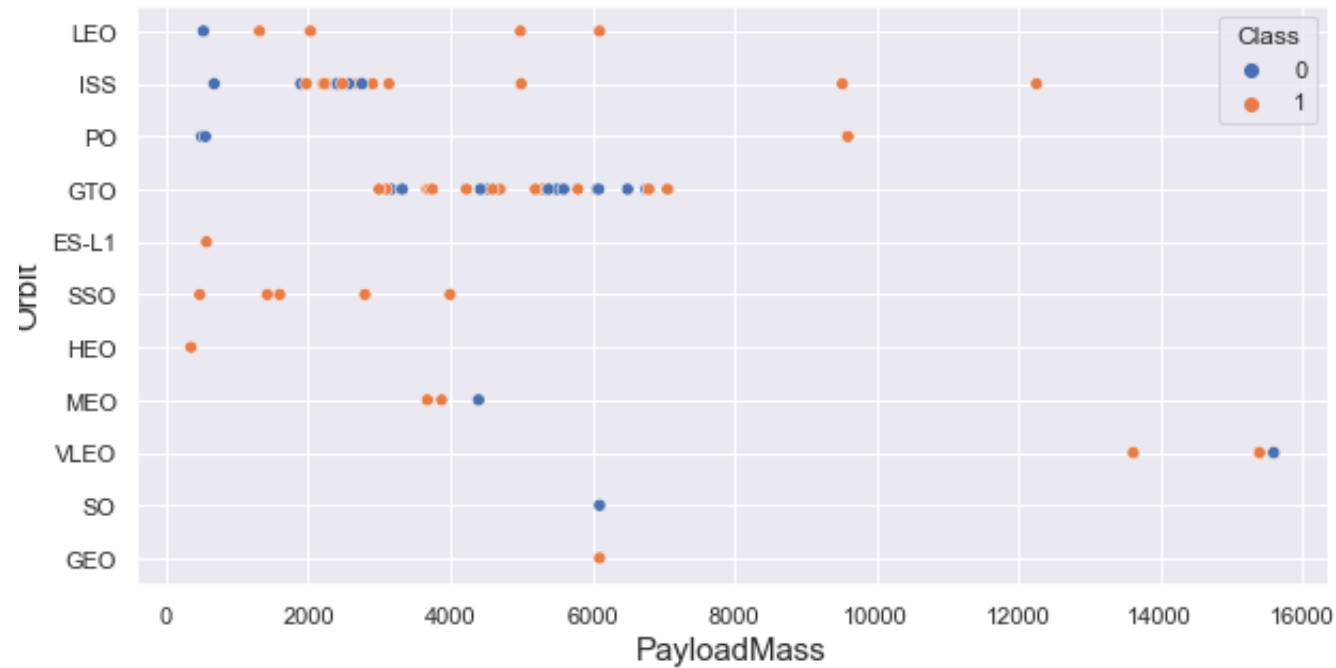
- ES-L1, GEO, HEO and SSO has highest success rates





- We see that in the LEO orbit the Success appears related to the number of flights; on the other hand, there seems to be no relationship between flight number when in GTO orbit.

Flight Number vs. Orbit Type

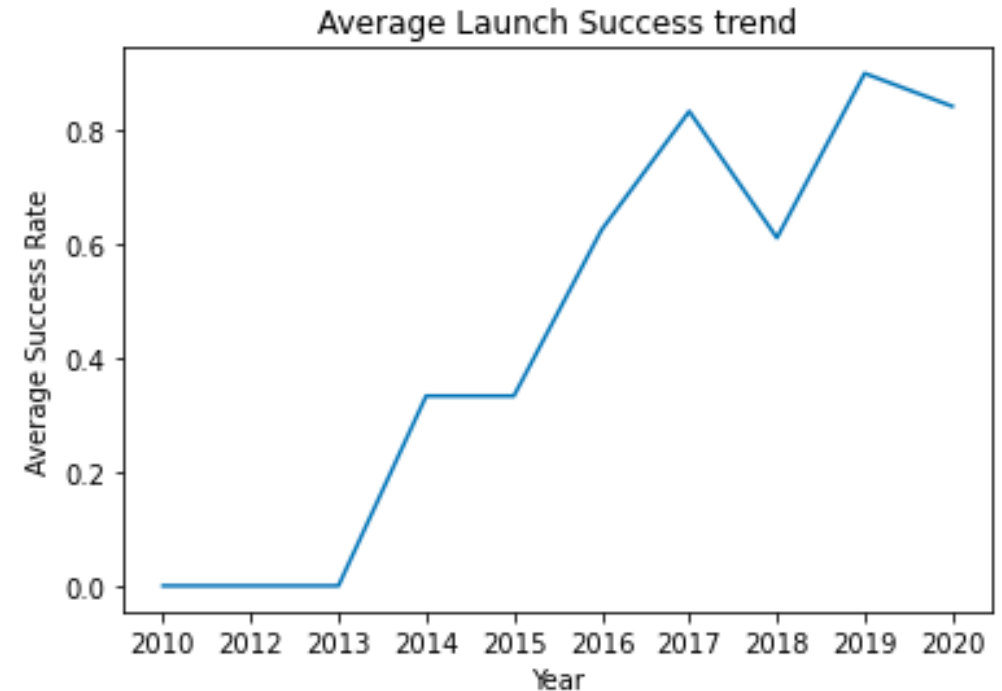


- With heavy payloads the successful landing or positive landing rate are more for Polar, LEO and ISS.
- However for GTO we cannot distinguish this well as both positive landing rate and negative landing (unsuccessful mission) are both there here

Payload vs. Orbit Type

Launch Success Yearly Trend

We can observe that the success rate since 2013 kept increasing till 2020



EDA with SQL





Launch_Sites

CCAFS LC-40

CCAFS SLC-40

KSC LC-39A

VAFB SLC-4E

All Launch Site Names



```
%sql select DISTINCT  
LAUNCH_SITE from SPACEXTBL
```



Using DISTINCT we pull
unique values for LAUNCH_SITE
from SPACEXTBL



Launch Site Names Begin with 'CCA'

```
%sql select * from SPACEXTBL where LAUNCH_SITE like  
'CCA%' LIMIT 5
```

LIMIT is used for restricting the number of rows (5) retrieved from the SPACEXTBL

Keyword 'like' means that LAUNCH_SITE name must start with 'CCA'

| DATE | time__utc__ | booster_version | launch_site | payload | payload_mass__kg__ | orbit | customer | mission_outcome | landing__outcome |
|------------|-------------|-----------------|-------------|---|--------------------|-----------|-----------------|-----------------|---------------------|
| 2010-06-04 | 18:45:00 | F9 v1.0 B0003 | CCAFS LC-40 | Dragon Spacecraft Qualification Unit | 0 | LEO | SpaceX | Success | Failure (parachute) |
| 2010-12-08 | 15:43:00 | F9 v1.0 B0004 | CCAFS LC-40 | Dragon demo flight C1, two CubeSats, barrel of Brouere cheese | 0 | LEO (ISS) | NASA (COTS) NRO | Success | Failure (parachute) |
| 2012-05-22 | 07:44:00 | F9 v1.0 B0005 | CCAFS LC-40 | Dragon demo flight C2 | 525 | LEO (ISS) | NASA (COTS) | Success | No attempt |
| 2012-10-08 | 00:35:00 | F9 v1.0 B0006 | CCAFS LC-40 | SpaceX CRS-1 | 500 | LEO (ISS) | NASA (CRS) | Success | No attempt |
| 2013-03-01 | 15:10:00 | F9 v1.0 B0007 | CCAFS LC-40 | SpaceX CRS-2 | 677 | LEO (ISS) | NASA (CRS) | Success | No attempt |

Total Payload Mass

```
%sql select sum(PAYLOAD_MASS__KG_) from SPACEXTBL where CUSTOMER='NASA (CRS)'
```

- Sum calculated the total in (PAYLOAD_MASS__KG_)
- Where clause with the predicate CUSTOMER by name 'NASA (CRS)'

Total Payload Mass by NASA (CRS)

45596

Average Payload Mass by F9 v1.1

- %sql select AVG(PAYLOAD_MASS__KG_) from SPACEXTBL
where BOOSTER_VERSION = 'F9 v1.1'
- AVG find the average in (PAYLOAD_MASS__KG_)

Average Payload Mass by Booster Version F9 v1.1

2928

First Successful Ground Landing Date

- %sql select MIN(DATE) from SPACEXTBL where LANDING__OUTCOME = 'Success (ground pad)'
- MIN find the minimum in Date

First Successful Landing Outcome in Ground Pad

2015-12-22

booster_version

F9 FT B1022

F9 FT B1026

F9 FT B1021.2

F9 FT B1031.2

Successful Drone Ship
Landing with Payload
between 4000 and 6000

- %sql select BOOSTER_VERSION from SPACEXTBL where LANDING_OUTCOME='Success(drone ship)' and PAYLOAD_MASS__KG_ between 4000 and 6000
- AND clause specifies additional filter conditions

Total Number of Successful and Failure Mission Outcomes

- **%sql** select COUNT(MISSION_OUTCOME) as "Total Number of Successful and Failure Mission"
FROM SPACEXTBL \
- where MISSION_OUTCOME like 'Success%' or MISSION_OUTCOME like 'Failure%'
- I used sub query to get success and failure counts

| Successful Mission | Failure Mission |
|--------------------|-----------------|
|--------------------|-----------------|

| | |
|-----|---|
| 100 | 1 |
|-----|---|

Boosters Carried Maximum Payload

```
%sql select DISTINCT
BOOSTER_VERSION as "Booster
Versions which carried the
Maximum Payload Mass" from
SPACEXTBL where
PAYLOAD_MASS__KG_=(select
MAX(PAYLOAD_MASS__KG_)
from SPACEXTBL)
```

- MAX finding the maximum in (PAYLOAD_MASS__KG_)

Booster Versions which carried the Maximum Payload Mass

| |
|---------------|
| F9 B5 B1048.4 |
| F9 B5 B1048.5 |
| F9 B5 B1049.4 |
| F9 B5 B1049.5 |
| F9 B5 B1049.7 |
| F9 B5 B1051.3 |
| F9 B5 B1051.4 |
| F9 B5 B1051.6 |
| F9 B5 B1056.4 |
| F9 B5 B1058.3 |
| F9 B5 B1060.2 |
| F9 B5 B1060.3 |

2015 Launch Records

- %sql select {fn MONTHNAME(DATE)} BOOSTER_VERSION, LAUNCH_SITE from SPACEXTBL where DATE like '2015%' and Landing_Outcome='Failure (drone ship)'
- Using {fn MONTHNAME(DATE)} we get the month name

| Month | booster_version | launch_site |
|---------|-----------------|-------------|
| January | F9 v1.1 B1012 | CCAFS LC-40 |
| April | F9 v1.1 B1015 | CCAFS LC-40 |

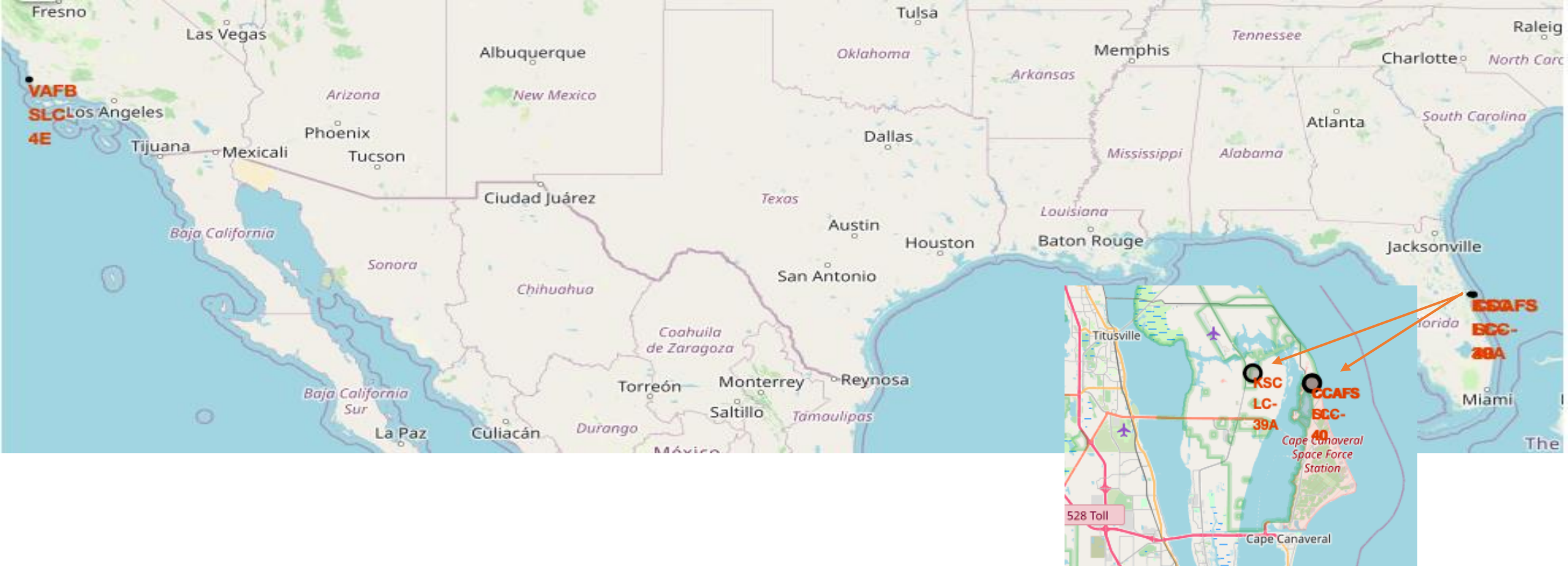
Rank Landing Outcomes Between 2010-06-04 and 2017-03-20

- %sql select Landing_Outcome as 'Landing Outcome', \COUNT(Landing_Outcome) as 'Total Count' from SPACEXTBL \where DATE between '2010-06-04' and '2017-03-20' \group by Landing_Outcome\order by COUNT(Landing_Outcome) DESC
- Grouping by Landing_Outcome and Ordering by COUNT(Landing_Outcome) in Descending order

| Landing Outcome | Total Count |
|------------------------|-------------|
| No attempt | 10 |
| Failure (drone ship) | 5 |
| Success (drone ship) | 5 |
| Controlled (ocean) | 3 |
| Success (ground pad) | 3 |
| Failure (parachute) | 2 |
| Uncontrolled (ocean) | 2 |
| Precluded (drone ship) | 1 |

A close-up photograph of a map of Europe, which is the central focus. The map is a light blue color and is surrounded by numerous black pushpins. One pushpin, located in the center of the map (over the British Isles), is orange. The pushpins are scattered across the map, with some pointing towards the center and others pointing away. The background is a light blue surface.

Interactive map with Folium



We can see that SpaceX launch sites are in Florida and California regions (near the costs)

All launch sites on map

Color mark the success/failed launches for each site on the map



Shows successful launches



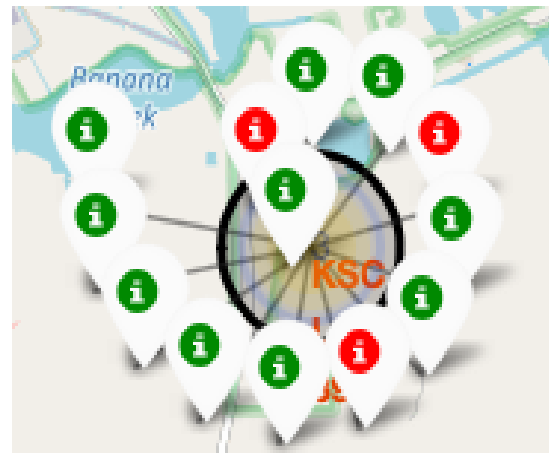
Shows failures

In this slides we can see that site KSL LC 40 has high number of successful launches

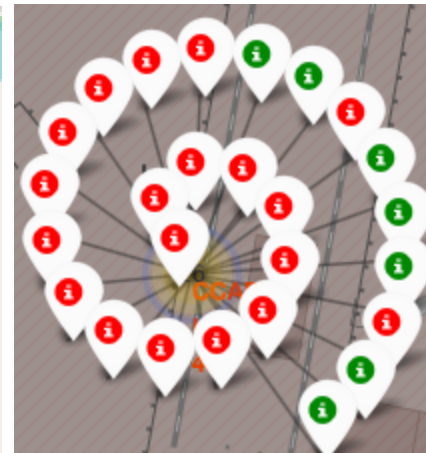
VAF SLC 4E



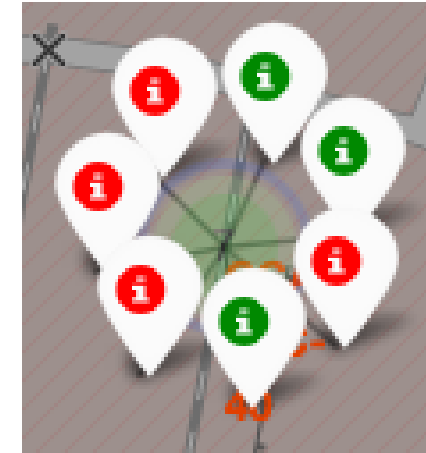
KSC LC 39A

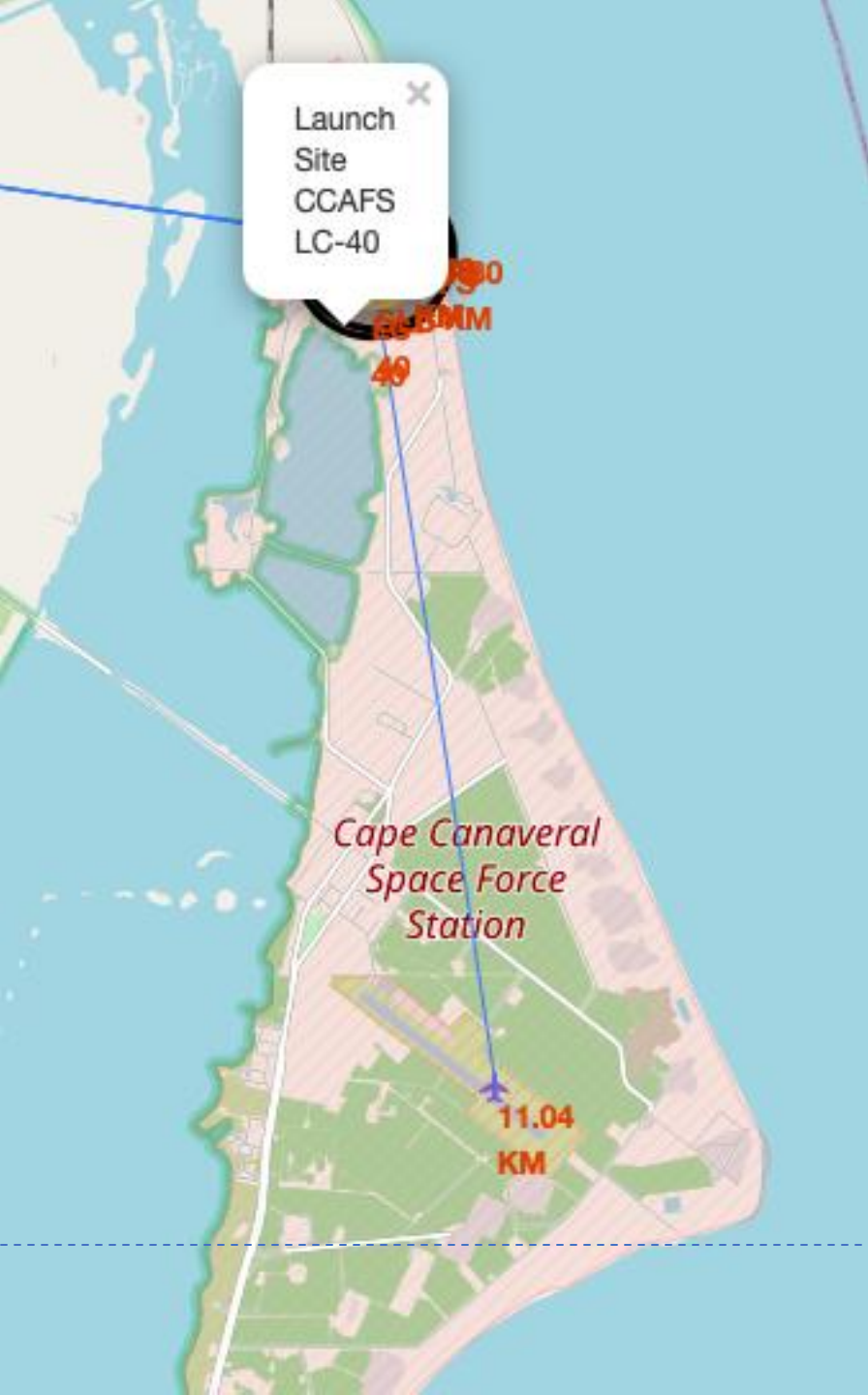


CCAFS SLC-40



CCAFS SLC-40





Distance between a launch site
to Cape Canaveral SFS Skid Strip

Distance from Launch Site CCAFS LC-40 more than
11 km



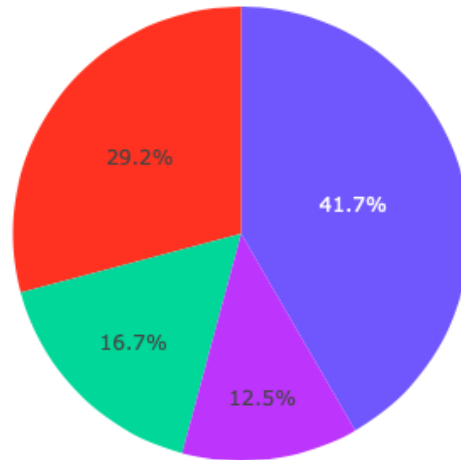
Build Dashboard with Plotly Dash

SpaceX Launch Records Dashboard

All Sites



Success Count for all launch sites

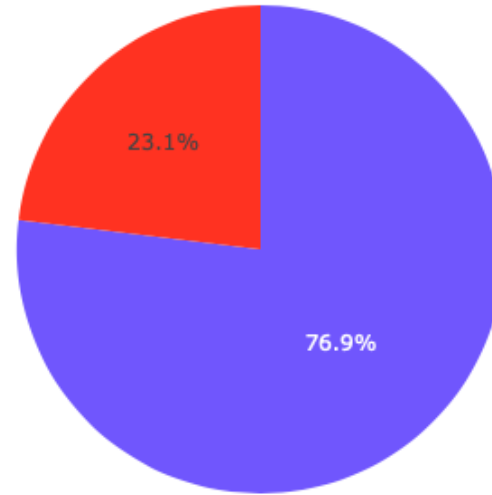


■ KSC LC-39A
■ CCAFS LC-40
■ VAFB SLC-4E
■ CCAFS SLC-40

Launch success
count for all sites

- We can see that KSC LC 39 had the most successful launches

Total Success Launches for site KSC LC-39A



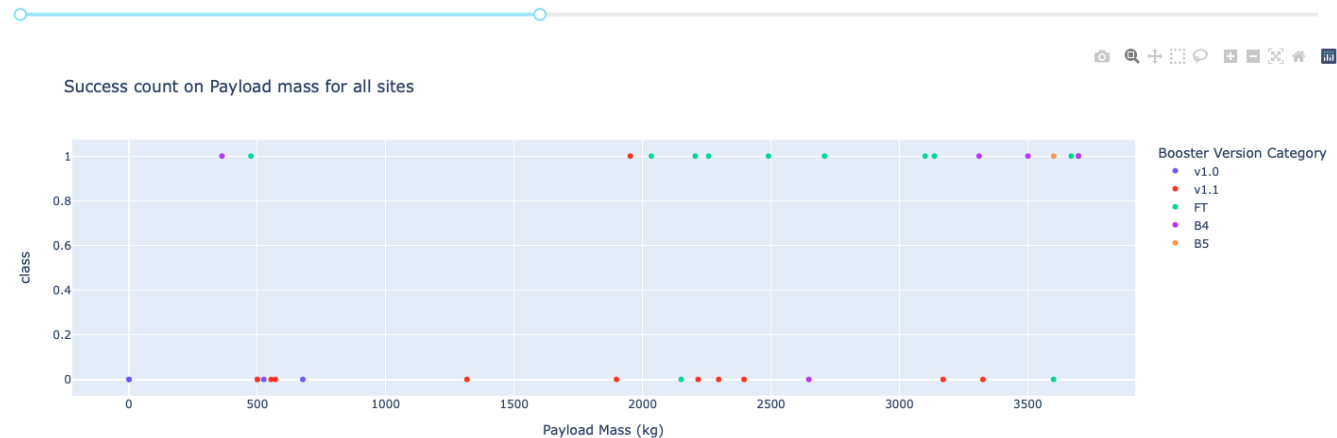
Launch site with highest
launch success ratio

- KSC LC 39 has 76,9% success rate and 23,1% failure rate

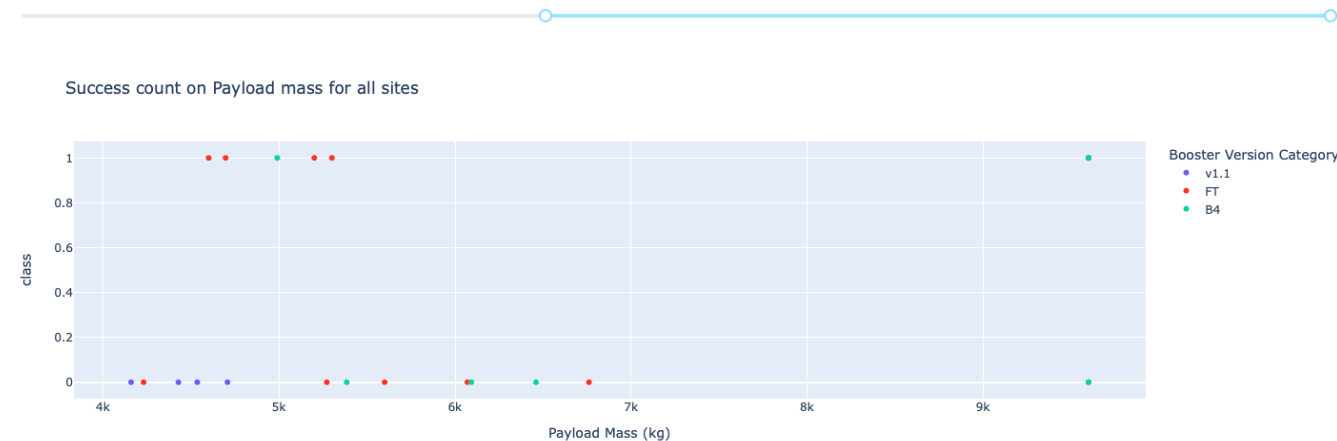
Payload vs. Launch Outcome Scatter Plot for all sites

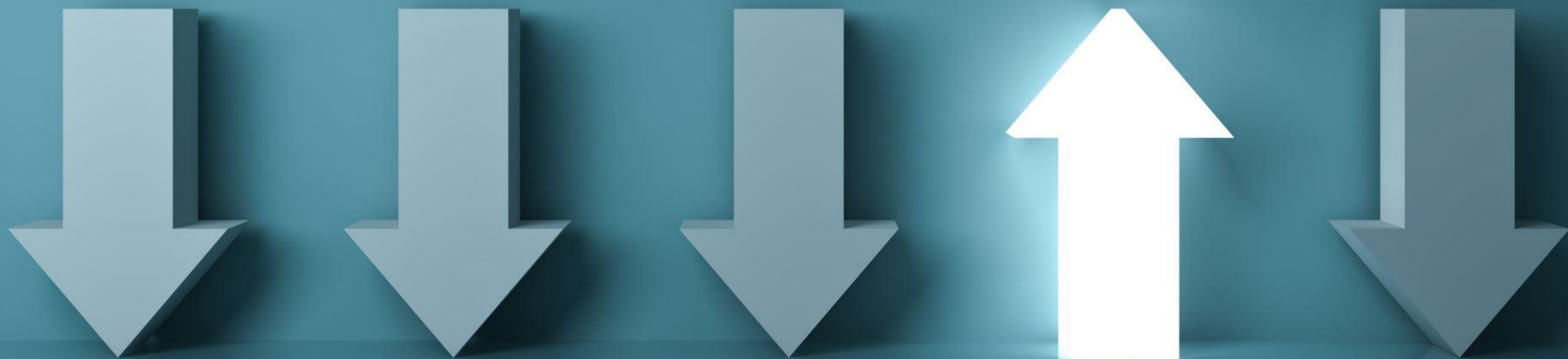
We can see for low weighted
Payload the success rate higher than
for heavy weighted Pa

Payload range (Kg):

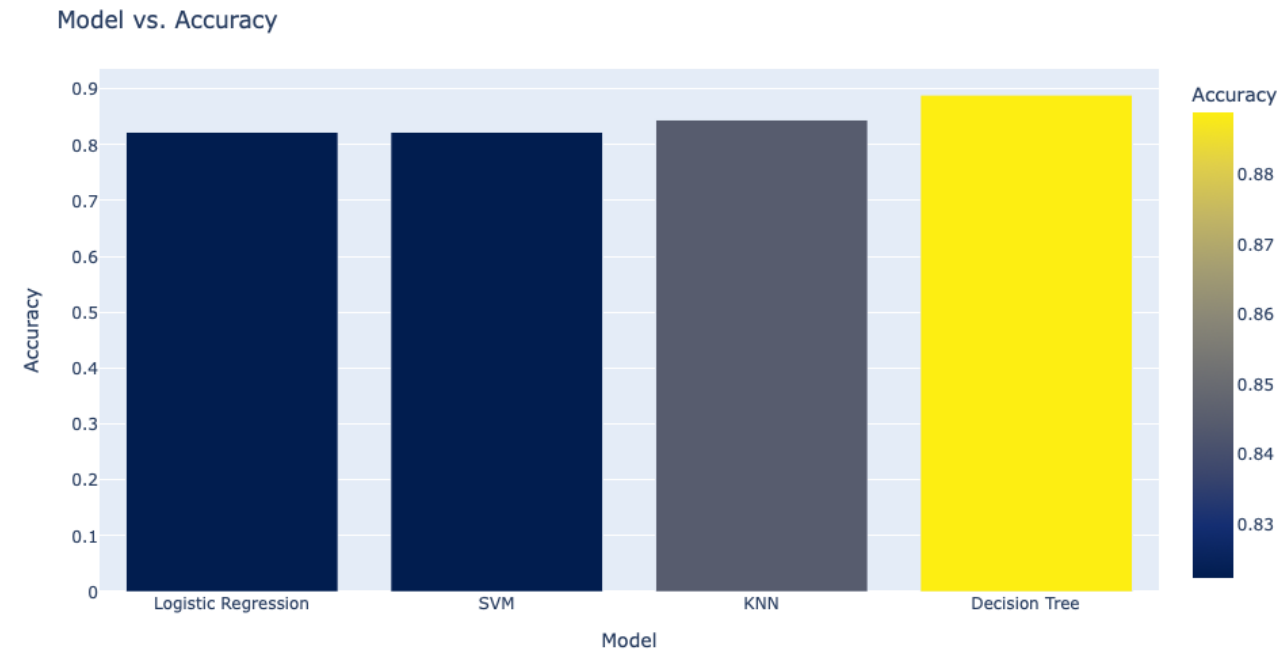


Payload range (Kg):





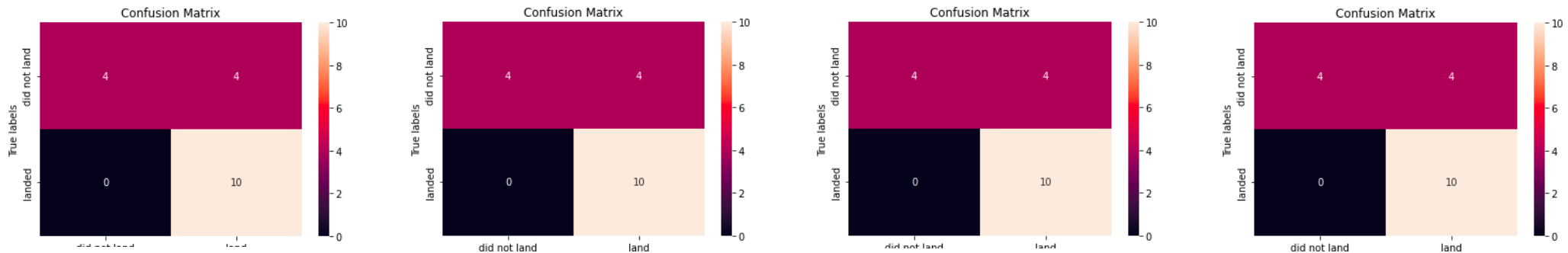
Predictive Analysis (Classification)



- We can see the Decision Tree
- model has highest accuracy

Classification Accuracy

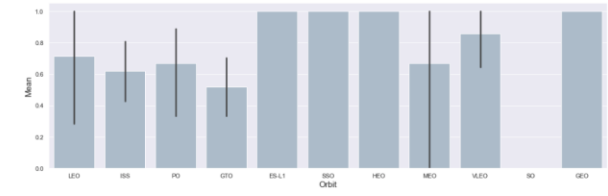
Confusion Matrix



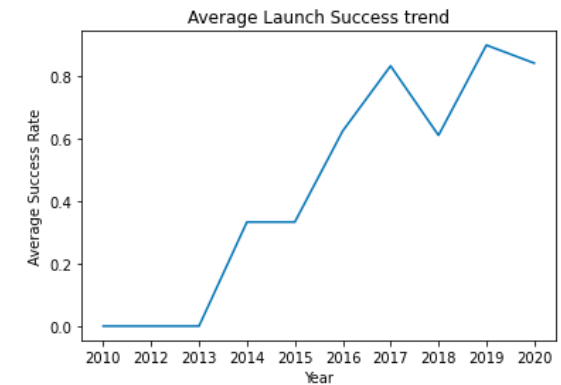
- Practically all these algorithms give the same Confusion Matrix

Conclusions

- The Orbits ES L1, SSO, HEO, GEO has highest success rates



- The success rate since 2013 kept increasing till 2020

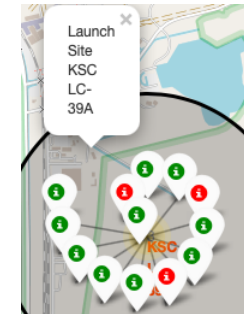
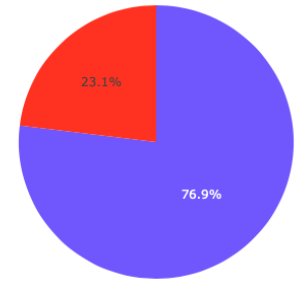


Conclusions

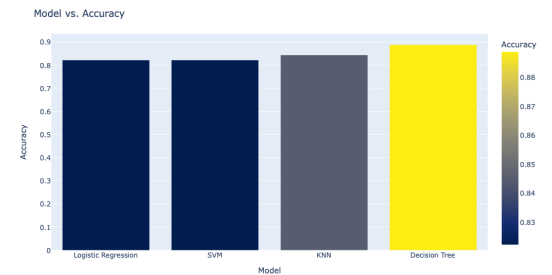
3. KSC LC 39 has 76,9% success rate

and 23,1% failure rate.

This the best result from all Sites



4. The Decision Tree model has highest accuracy



Appendix

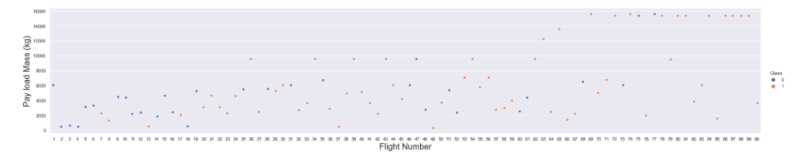
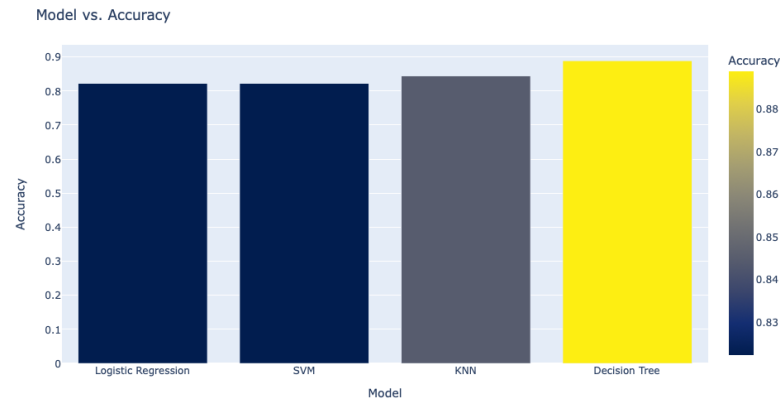
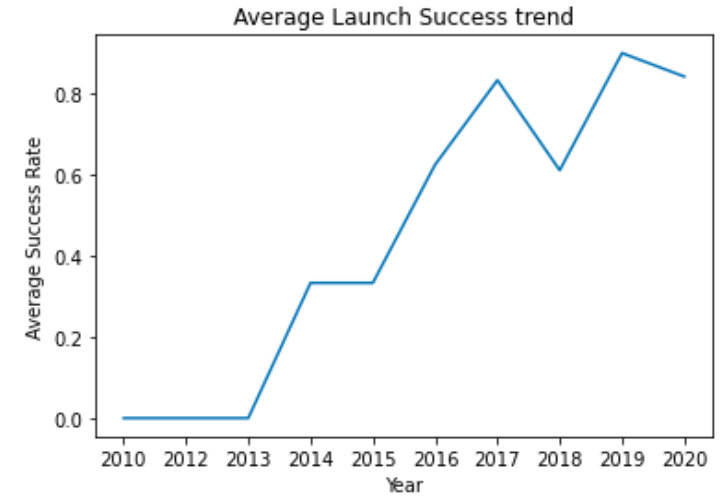
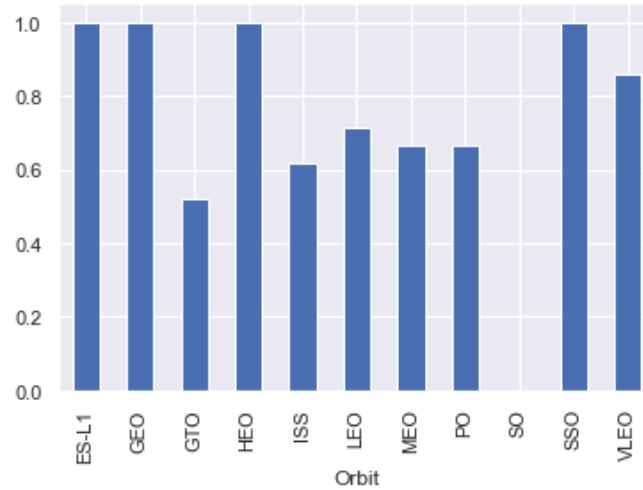
Interactive Plotly

Folium Mouse
Position and MarkerCluster plugins
Tool

Basic Decision Tree Constructor

Interactive Plotly

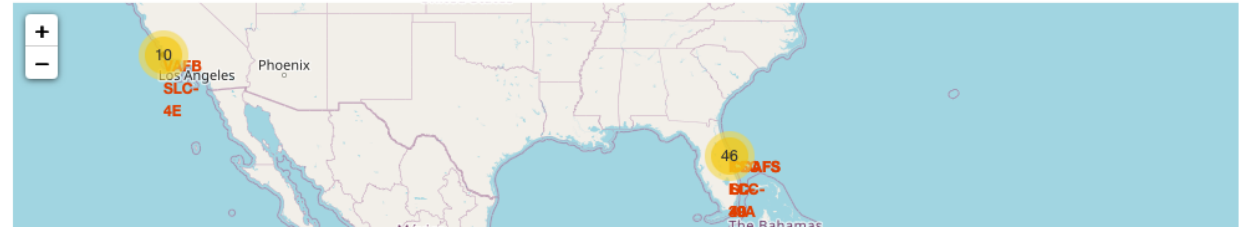
Helps to explore data



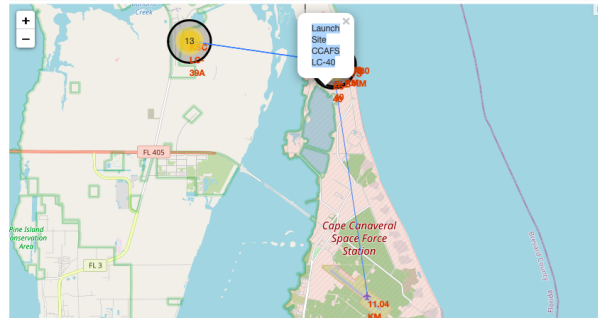
Folium Mouse Position and Marker Cluster plugins Tool

Help mark point and distance
on map

```
marker = folium.Marker([row['Lat'], row['Long']], icon=folium.Icon(color='white', icon_color=row['marker_color'])).  
add_to(marker_cluster)  
marker_cluster.add_child(marker)  
  
site_map
```

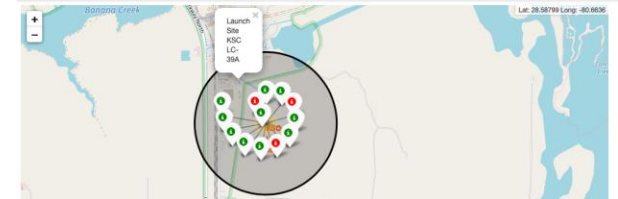


```
lines_airport=folium.PolyLine(locations=[[28.562302, -80.577356], [28.46416, -80.56068]], weight=1)  
site_map.add_child(lines_airport)  
site_map
```

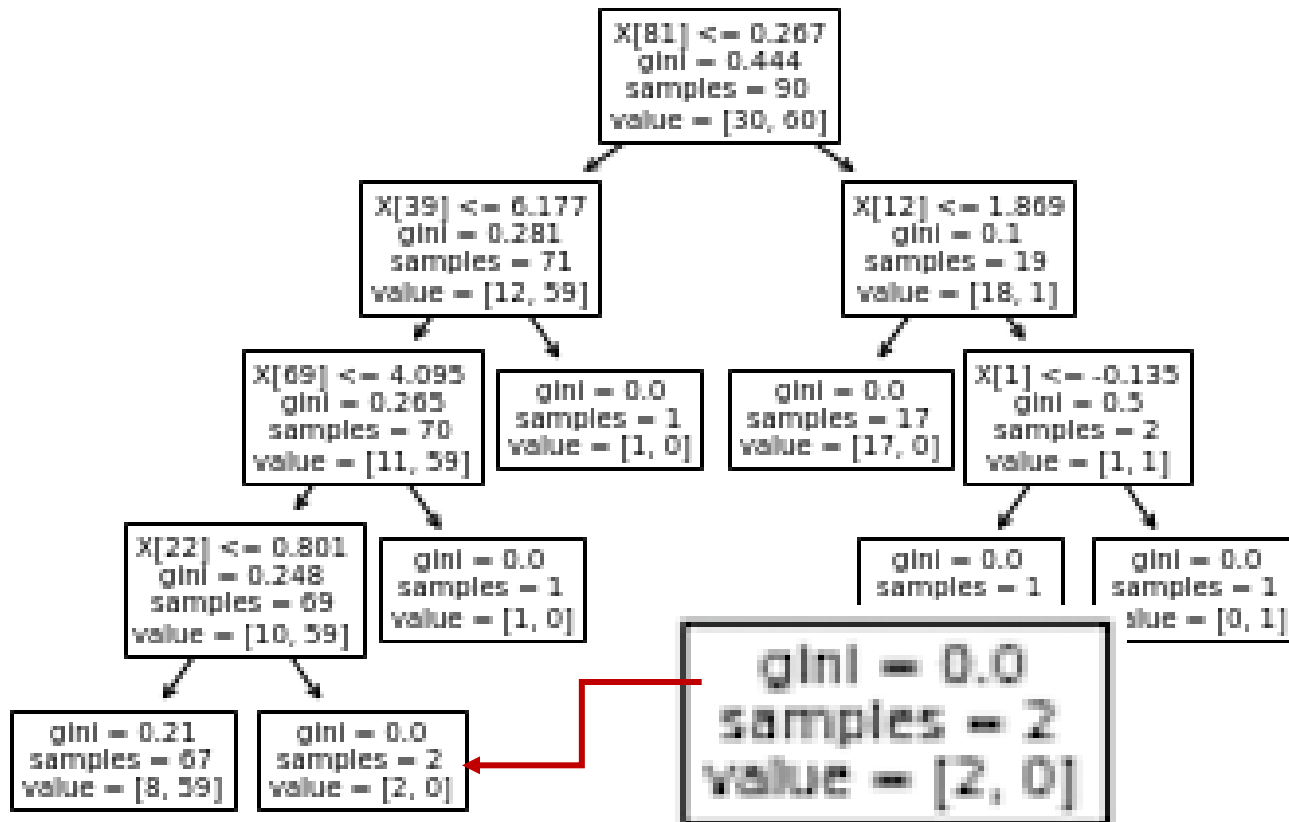


```
mouse_position = MousePosition(  
    position='topright',  
    separator=' Long',  
    empty_string='NaN',  
    lng_first=False,  
    num_digits=20,  
    prefix='Lat:',  
    lat_formatter=formatter,  
    lng_formatter=formatter,  
)
```

```
site_map.add_child(mouse_position)  
site_map
```



Basic Decision Tree Constructor



As you can see
'gini' near '0' - the
probability of the
success will be
highest



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