# CISC452/CMPE452/COGS400 Threshold Logic Units

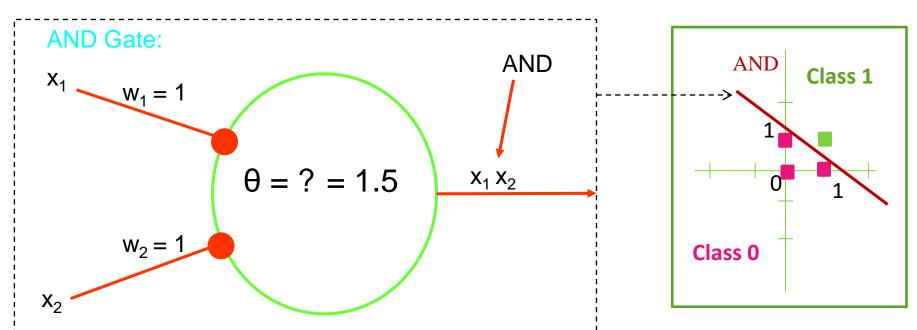
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### Threshold Logic Units (TLUs) AND Gate

TLUs apply a threshold activation function and *only accept binary inputs* (0 or 1) – simulate logic gates.

AND Gate: 00, 01, 10=0 and 11=1 (x,y)

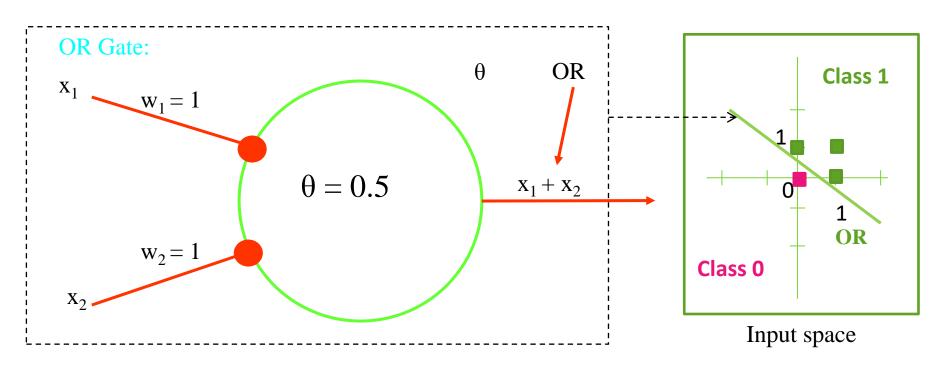
Each point is represented by  $x_1x_2$ 



#### TLUs and Linear Separability – OR

OR Gate: 00 = 0 and 01, 10, 11 = 1TLU works as a linear separator for AND and OR gates.

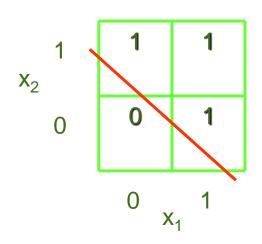
Each point is represented by  $x_1x_2$ 



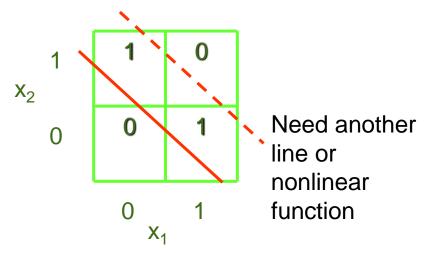
 $w_1x_1 + w_2x_2 >= 0$  then output 1 else output 0

### What if the data are not linearly separable?

- A function  $f:\{0,1\}^n \to \{0,1\}$  is linearly separable if the space of input vectors yielding 1 can be separated from those yielding 0 by a linear surface having (hyperplane) n-l dimensions.
- Examples: 2-D (dimensions) points: Separated by a 1-D line.



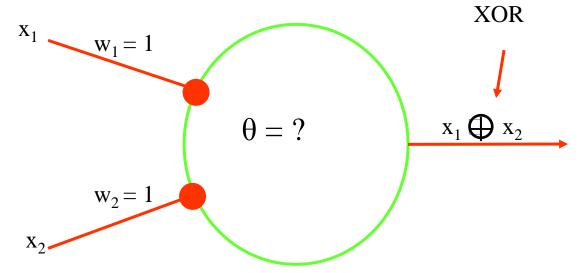




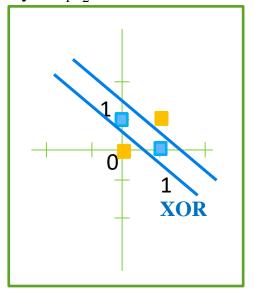
linearly inseparable (XOR)

#### TLUs cannot implement XOR

#### What about XOR?



Each point is represented by  $x_1x_2$ 



XOR Gate: **00,11=0** and **10,01=1 NOT linearly separable by one line !!!** 

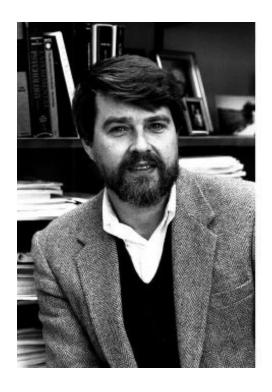
TLUs CANNOT realize functions that are **NOT linearly separable**.

### Minsky and Papert

- In 1969, Marvin Minsky and Seymour Papert, two "PSS" researchers at MIT studied the ANNs and revealed that a two-layered (input and output) network cannot handle all logical relations specifically the XOR.
  - It implies that ANNs lacked the power of a Turing machine.
- Federal funding for ANNs immediately stopped.

#### The Big Breakthrough

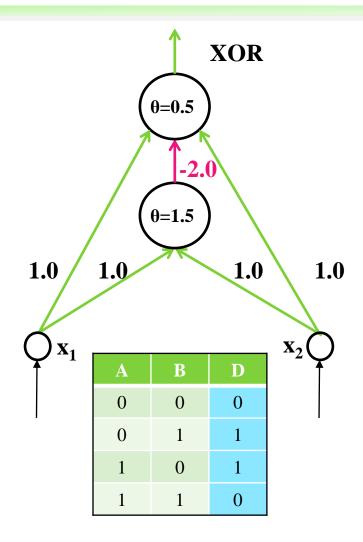
• David Rumelhart and Jim McClelland developed Parallel Distributed Processing (PDP).





#### Multilayer Networks with Inhibition

- The solution that Rumelhart and McClelland propose is simple: Add a third layer between input and output.
- 3 layers enable creating an XOR gate and handle all logic.
- Note that middle layer neuron inhibits output layer neuron when  $x_1 = x_2 = 1$ .
  - New for ANN



## Linear Separability as Functional Mapping

• To explain linear separability, let us consider the function  $f: \mathbb{R}^n \to \{0, 1\}$ .  $\theta$  is called the **bias**.

$$f(x_1, x_2, ..., x_n) = 1, \quad \text{if} \quad \sum_{i=1}^n w_i x_i \ge \theta$$
$$= 0, \quad \text{otherwise}$$

where  $x_1, x_2, ..., x_n$  represent real numbers (not TLU).

- Here the output function is generating values 0 or 1.
- $(w_1x_1 + w_2x_2 = \theta)$  represents the separator line in a 2-D space. Writing as (y = mx + c) to plot the line

$$\rightarrow x_2 = (-w_1/w_2)x_1 + \theta/w_2$$

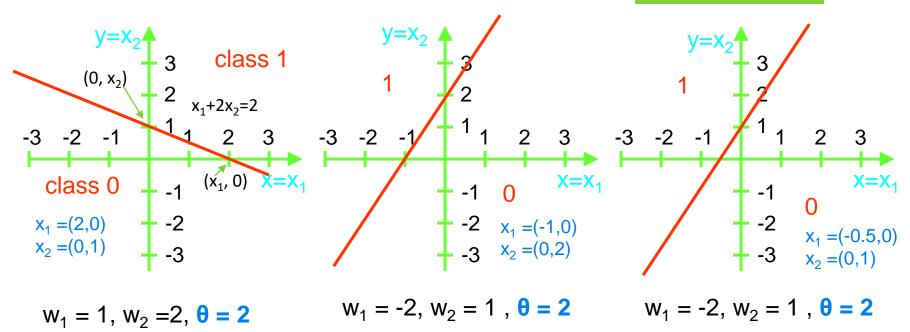
### Examples – Linear Separability

Given x values and  $\theta$ , we can determine the weights  $(w_1, w_2)$  to model the mapping using ANN using

 $x_2 = (-w_1/w_2)x_1 + \theta/w_2$ 

$$f(x_1, x_2, ..., x_n) = 1$$
, if  $\sum_{i=1}^n w_i x_i \ge \theta$ 

=0, otherwise



By changing w and  $\theta$ , we can adjust the line to separate two classes in a 2-D space.

#### Learning/Training in ANN

- Training a network means finding the best fitting values of  $\theta$  and the weights to categorize a given set of values correctly
  - Find the line that divides a labelled set of values into known categories.

#### Linear Separability (cont...)

- As we have seen, a two-dimensional input space can be divided by any straight line.
- A three-dimensional input space can be divided by any two-dimensional plane.
- In general, an *n-dimensional input space can* be divided by an (*n-1*)-dimensional plane or hyperplane.
- Of course, for n > 3 this is hard to visualize.

#### Activation as a Vector Product

The net input signal is the sum of all inputs where *x* values represent all the features in a data point:

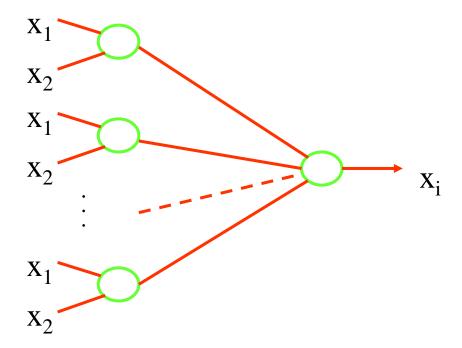
$$\operatorname{net}_{i}(t) = \sum_{j=1}^{n} w_{i,j}(t) x_{j}(t)$$

$$\operatorname{net}_{i}(t) = |\mathbf{w}_{i}(t)| \cdot |\mathbf{x}(t)| \cdot \cos \alpha = \mathbf{w}^{T} \mathbf{x} = [w_{1} w_{2} w_{3}] \begin{bmatrix} x_{1} \\ x_{2} \\ x_{3} \end{bmatrix}$$

This can be viewed as computing the **inner product** of the **vectors w**<sub>i</sub> and **x**: https://en.wikipedia.org/wiki/Dot\_product where  $\alpha$  is the **angle** between the two vectors and  $|a| = \operatorname{sqrt}(a.a)$  and a is a given vector

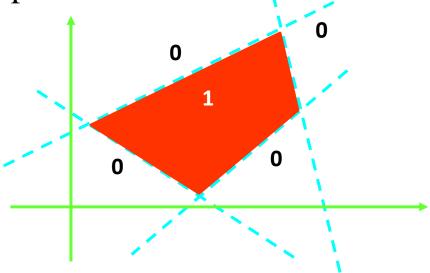
#### What about complex functions?

- So what can threshold neurons do for us?
- Let us consider a neuron with two inputs. We can combine multiple artificial neurons in multiple layers to form networks with increased capabilities.



#### Identify a Polygon

• The dotted lines can represent the first layer neurons which output 0 or 1 depending on which side of the line the input data point lies.



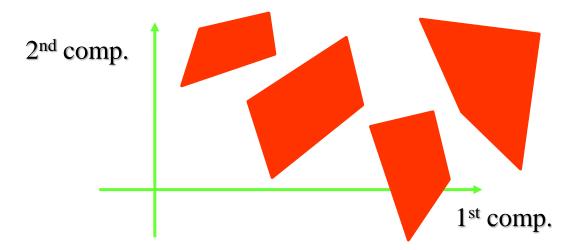
• Then, the second-layer neuron could output 1 if all the outputs of the first layer neurons is 1 to identify a polygon, and 0 otherwise.

#### Identify Multiple Polygons

- The more neurons there are in the first layer, the more vertices can the polygons have.
- With a sufficient number of first-layer neurons, the polygons can approximate any given shape.
- The more neurons there are in the second layer, the more of these polygons can be combined to form the output function of the network.
- With multi-layered ANN, you can identify many different shapes.

#### Capabilities (cont...)

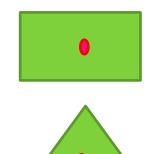
• Assume that the polygons in the diagram indicate the input regions for which each of the **second-layer** neurons yields output 1:

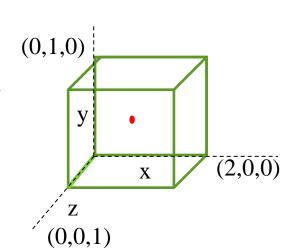


Then, for example, the third-layer neuron could output 1 if the input is within any of the polygons, and 0 otherwise. Example application ???

#### Problem

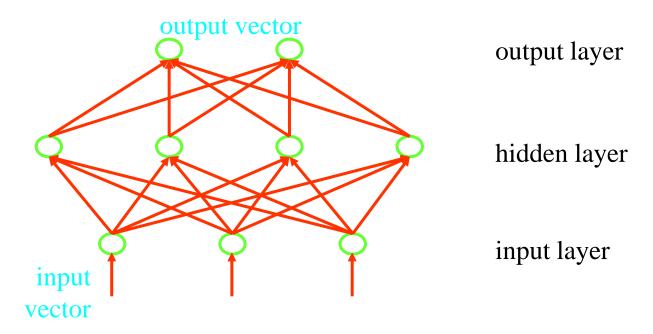
- 1. Draw an ANN that can detect whether a point lies on the surface of a square plane or a triangle. Explain how it would work.
- 2. Draw an ANN to find if a point lies **inside** a hollow box. Explain how it would work.





#### Terminology

• Example: Network function  $f: \mathbb{R}^3 \to \{0, 1\}^2$  means that the network takes 3-dimensional real values as input and generates two-dimensional binary output values.



#### Summary

- Complex ANNs can be created by combining neurons at multiple layers.
- Weights and bias are the variables that need to be assigned correct values to classify data points.
- The *input layer* just contains the input vector and *does* not perform any computations other than distributing inputs to the next layers (used optionally).
- The intermediate layers, termed *hidden layers*, receives input from the input layer or previous hidden layers and *sends output to the final output layer*.
- After applying their *activation function*, the neurons in the final *output layer* generate the output vector.