

## Gurobi Formulation – Phase-Model

### Sets:

- $P$  – phase (INT1\_NS, INT1\_EW, INT2\_NS, INT2\_EW, INT3\_NS, INT3\_EW, INT4\_NB, INT4\_EB, INT4\_WB)
- $I$  – Incompatible phases
- $G$  – Intersection Groups – which phase is associated with which intersection
- $C$  – Congested Phase

### Data:

- $T$  – simulation length.
- $\min_p$  – minimum time a phase can be on (20 seconds).
- $\max_p$  – maximum time a phase can be on (90 seconds).
- $\text{current\_percentage}$  – The current percentage a lane can be “on” for.
- $\max_{cap}$  – the maximum a lane percentage can be turned “on” for.
- $\text{current\_score}$  – the score the simulation returns based on the light schedule.

### Variables:

- $x_{p,t} = 1$  if phase  $p \in P$  is “on” in time  $t \in T$ , 0 if not
- $\theta$  – score (cars exited)

### Objective:

- maximise:  $\theta$

### Constraints:

- Incompatible phases cannot be on at the same time:

$$x_{p_i,t} + x_{p_j,t} \leq 1 \quad \forall t \in T, \forall p \in P, \forall i, j \in I$$

- One phase at each intersection must always be on – relaxed for final 90 seconds:

$$\sum_{p \in g} x_{p,t} = 1 \quad \forall t \in [T - \max_p], \forall g \in G$$

$$\sum_{p \in g} x_{p,t} \leq 1 \quad \forall t \in [T - \max_p, T], \forall g \in G$$

- A phase cannot be on longer than  $\max_p$

$$\sum_{t=s}^{s+\max_p} x_{p,t} \leq \max_p \quad \forall p \in P, \forall s \in [0, T - \max_p - 1]$$

- If a light turns on, the phase must be on for at least  $\min_p$

$$\sum_{t=s}^{s+\min_p} x_{p,t} \geq \min_p * (x_{p,s} - x_{p,s-1}) \quad \forall p \in P, \forall s \in [1, T - \min_p - 1]$$

- Lights cannot be green at the end of the simulation

$$x_{p,s} - x_{p,s-1} \leq 0 \quad \forall p \in P, \forall s \in [T - \min_p + 1, T]$$

### **Lazy Constraints:**

- Optimality cut: Bounds the maximum potential score ( $\theta$ ) based on the  $current_{score}$  returned by the simulation.

$$\theta \leq current_{score} + 50 * dist_{expr}$$

Where  $dist_{expr}$  is the Hamming Distance Expression and is the difference between the generated schedules and is represented as:

$$dist_{expr} = old_{on} + new_{on} - 2 * matches$$

Where  $old_{on}$  is the number of lights that are green in the old schedule,  $new_{on}$  is the number of lights that are on in the new schedule and  $matches$  is the number of lights that stay the same between the two schedules.

- Feasibility cut: if a lane during the simulation reaches above 75% maximum capacity, add a feasibility cut that forces that lanes “on” time to be increased by at least  $new\_min_{percentage}$ .

$$\sum_{t \in T} x_{c,t} \geq new\_min_{percentage} * T$$

where  $new\_min_{percentage} = \min(\max(current_{percentage} + 0.025, 0.01), max_{cap})$ .