
```
function [ L , D ] = MarsGliderFunction( CL , CD , S , v , h )
%UNTITLED3 Summary of this function goes here
% Detailed explanation goes here
[D0] = MarsStdAtm(h);
q = .5 * D0 * v^2 ;
L = CL * q * S ;
D = CD * q * S ;
disp( 'Lift' )
disp( L )
disp( 'Drag' )
disp( D )
disp( 'L/D' )
disp( L/D )

end
```

Not enough input arguments.

Error in MarsGliderFunction (line 4)
[D0] = MarsStdAtm(h);

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