Problem2_Code

February 16, 2019

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In [0]: import numpy as np
        import matplotlib.pyplot as plt
        import torch
        import torch.nn as nn
        import torch.nn.functional as F
        import torch.optim as optim
        import torchvision
        from torchvision import transforms
        torch.backends.cudnn.deterministic=True
        device = torch.device("cuda")
In [2]: from google.colab import drive
        drive.mount('/content/gdrive')
Go to this URL in a browser: https://accounts.google.com/o/oauth2/auth?client_id=947318989803-
Enter your authorization code:
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Mounted at /content/gdrive
In [0]: # ~~ MNIST ~~
        transform = transforms.Compose([transforms.ToTensor()])
       train_set = torchvision.datasets.MNIST(root='/content/gdrive/My Drive/Datasets/MNIST',
        test_set = torchvision.datasets.MNIST(root='/content/gdrive/My Drive/Datasets/MNIST',
In [0]: # MNIST
        train_loader = torch.utils.data.DataLoader(train_set, batch_size=100, shuffle=True)
        test_loader = torch.utils.data.DataLoader(test_set, batch_size=100, shuffle=False)
In [0]: class ConvolutionalNeuralNetwork(nn.Module):
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def __init__(self):
    super().__init__()
    m = 10
    # ~~ SmallVGGNET ~~ #
    # Block #1
    self.conv1 = nn.Conv2d(1, 16, 3, padding=3)
    self.conv2 = nn.Conv2d(16, 16, 3, padding=1)
    # Block #2
    self.conv3 = nn.Conv2d(16, 32, 3, padding=1)
    self.conv4 = nn.Conv2d(32, 32, 3, padding=1)
    # Block #3
    self.conv5 = nn.Conv2d(32, 64, 3, padding=1)
    self.conv6 = nn.Conv2d(64, 64, 3, padding=1)
    # Block #4
    self.fc1 = nn.Linear(64*4*4, 500)
    self.fc2 = nn.Linear(500, 500)
    self.fc3 = nn.Linear(500, m)
    # Xavier Initialization
    nn.init.xavier_uniform_(self.conv1.weight)
    nn.init.xavier_uniform_(self.conv2.weight)
    nn.init.xavier_uniform_(self.conv3.weight)
    nn.init.xavier_uniform_(self.conv4.weight)
    nn.init.xavier_uniform_(self.conv5.weight)
    nn.init.xavier_uniform_(self.conv6.weight)
    nn.init.xavier_uniform_(self.fc1.weight)
    nn.init.xavier_uniform_(self.fc2.weight)
    nn.init.xavier_uniform_(self.fc3.weight)
def forward(self, x):
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out = F.relu( self.conv1(x) )
                out = F.relu( self.conv2(out) )
                out = F.max_pool2d(out, 2)
                out = F.relu( self.conv3(out) )
                out = F.relu( self.conv4(out) )
                out = F.max_pool2d(out, 2)
                out = F.relu( self.conv5(out) )
                out = F.relu( self.conv6(out) )
                out = F.max_pool2d(out, 2)
                out = out.view(out.size(0), -1)
                out = F.relu( self.fc1(out) )
                out = F.relu( self.fc2(out) )
                out = self.fc3(out)
                return out
In [0]: class Model:
            def __init__(self, architecture):
                self.net = architecture
            def train(self, train_loader, test_loader, nb_epochs=10):
                self.net.train()
                criterion = nn.CrossEntropyLoss()
                optimizer = optim.SGD(self.net.parameters(), lr=0.03)
                train_accuracy = []
                train_er = []
                test_accuracy = []
                test_er = []
                # Record train values
                train_accuracy_epoch, train_er_epoch = self.test(train_loader)
                print(train_er_epoch)
                print(train_accuracy_epoch)
                train_accuracy.append(train_accuracy_epoch)
                train_er.append(train_er_epoch)
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# Record test values
test_accuracy_epoch, test_er_epoch = self.test(test_loader)
test_accuracy.append(test_accuracy_epoch)
test_er.append(test_er_epoch)
print(test_er_epoch)
print(test_accuracy_epoch)
# Start training
for epoch in range(nb_epochs):
    print('\nEpoch', epoch+1)
    for i, (X_batch, y_batch) in enumerate(train_loader):
        # Send the batch to the GPU
        X_batch, y_batch = X_batch.to(device), y_batch.to(device)
        # Reset the gradients to zero
        optimizer.zero_grad()
        # Forward propagation
        y_hat_batch = self.net(X_batch)
        # Compute loss
        loss = criterion(y_hat_batch, y_batch)
        # Backward propagation
        loss.backward()
        # Update weights
        optimizer.step()
    # Record train values
    train_accuracy_epoch, train_er_epoch = self.test(train_loader)
    print(train_er_epoch)
    print(train_accuracy_epoch)
    train_accuracy.append(train_accuracy_epoch)
    train_er.append(train_er_epoch)
    # Record test values
    test_accuracy_epoch, test_er_epoch = self.test(test_loader)
    test_accuracy.append(test_accuracy_epoch)
```

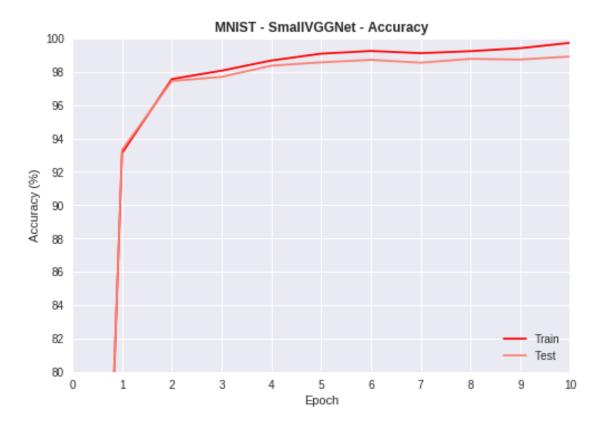
```
print(test_er_epoch)
                    print(test_accuracy_epoch)
                return train_accuracy, train_er, test_accuracy, test_er
            def test(self, data_loader):
                self.net.eval()
                criterion = nn.CrossEntropyLoss()
                with torch.no_grad():
                    accuracy = 0
                    correct_predictions = 0
                    empirical_risk = 0
                    for X_batch, y_batch in data_loader:
                        # Send the batch to the GPU
                        X_batch, y_batch = X_batch.to(device), y_batch.to(device)
                        # Forward propagation
                        y_hat_batch = self.net(X_batch)
                        # Compute loss
                        loss = criterion(y_hat_batch, y_batch)
                        # Pick up most predicted class
                        _, predictions = torch.max(y_hat_batch.data, 1)
                        # Compare predictions and real label
                        correct_predictions += (predictions == y_batch).sum().item()
                        # Sum losses
                        empirical_risk += loss
                accuracy = (correct_predictions / len(data_loader.dataset)) * 100
                empirical_risk /= len(data_loader)
                return accuracy, empirical_risk
In [22]: torch.manual_seed(0)
         torch.cuda.manual_seed(0)
```

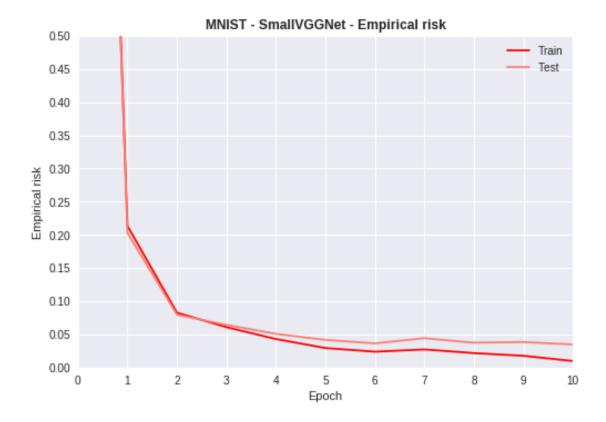
test_er.append(test_er_epoch)

```
cnn = ConvolutionalNeuralNetwork().to(device)
                                model = Model(cnn)
                                train_accuracy, train_er, test_accuracy, test_er = model.train(train_loader, test_loader, test_l
tensor(2.3039, device='cuda:0')
9.93
tensor(2.3031, device='cuda:0')
10.32
Epoch 1
tensor(0.2133, device='cuda:0')
93.11833333333334
tensor(0.2029, device='cuda:0')
93.31
Epoch 2
tensor(0.0827, device='cuda:0')
97.55833333333334
tensor(0.0797, device='cuda:0')
97.44
Epoch 3
tensor(0.0609, device='cuda:0')
98.0616666666667
tensor(0.0644, device='cuda:0')
97.69
Epoch 4
tensor(0.0430, device='cuda:0')
98.6716666666667
tensor(0.0508, device='cuda:0')
98.36
Epoch 5
tensor(0.0295, device='cuda:0')
99.08
tensor(0.0417, device='cuda:0')
98.56
Epoch 6
tensor(0.0240, device='cuda:0')
99.24333333333333
tensor(0.0365, device='cuda:0')
98.71
Epoch 7
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tensor(0.0273, device='cuda:0')
99.1116666666666
tensor(0.0443, device='cuda:0')
98.54
Epoch 8
tensor(0.0218, device='cuda:0')
99.2316666666667
tensor(0.0375, device='cuda:0')
98.77
Epoch 9
tensor(0.0178, device='cuda:0')
99.40833333333333
tensor(0.0385, device='cuda:0')
98.7299999999999
Epoch 10
tensor(0.0099, device='cuda:0')
99.7299999999999
tensor(0.0348, device='cuda:0')
98.91
In [32]: plt.xticks(np.arange(0,11))
        plt.yticks(np.arange(80,101,2))
         plt.ylim(80,100)
        plt.xlim(0,10)
         plt.plot(train_accuracy, label='Train', color='red')
         plt.plot(test_accuracy, label='Test', color='salmon')
         plt.title('MNIST - SmallVGGNet - Accuracy', fontweight='bold')
         plt.xlabel('Epoch')
         plt.ylabel('Accuracy (%)')
        plt.legend(loc=4)
        plt.show()
         plt.clf()
         plt.xticks(np.arange(0,11))
         plt.yticks(np.arange(0,0.51,0.05))
         plt.ylim(0,0.5)
         plt.xlim(0,10)
         plt.plot(train_er, label='Train', color='red')
         plt.plot(test_er, label='Test', color='salmon')
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plt.title('MNIST - SmallVGGNet - Empirical risk', fontweight='bold')
plt.xlabel('Epoch')
plt.ylabel('Empirical risk')
plt.legend(loc=1)
plt.show()
```





In [0]: